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Design Lenses for 3D User Interface in Extended Reality

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**“Any sufficiently advanced technology
is indistinguishable from magic.”**

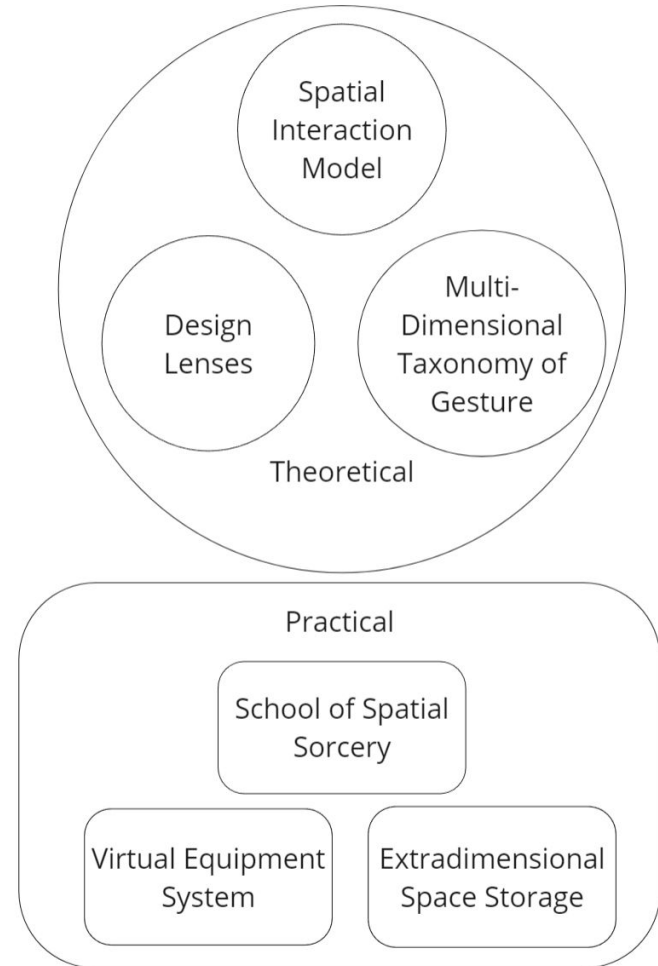
- Arthur C. Clarke

My work presents a systematic and practical approach to the design and development of user interfaces and user interactions in XR that feel like Clarke's magic.

Body of Work

Table of Contents

- Introduction
- Theoretical
 - Spatial Interaction Model
 - Design Lenses
 - Gesture Taxonomy
- Practical
 - School of Spatial Sorcery SSS
 - Virtual Equipment System VES
 - Extradimensional Storage EDS
- Evaluation of VES
- Summary & Conclusion
- Future Work



Introduction

- Extended Reality (XR)
- XR Qualities
- State of XR
- Existing Approach
- Problems
- Approach

Reality-Virtuality Continuum

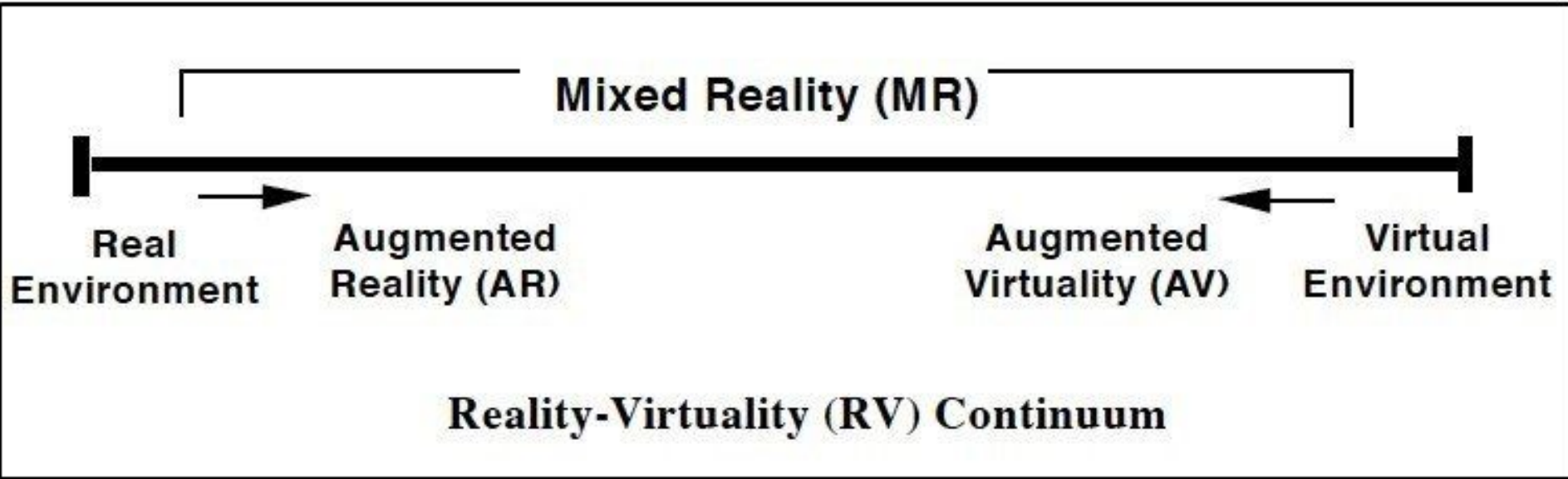


Figure: Reality-Virtuality (RV) Continuum diagram
P. Milgram, H. Takemura, A. Utsumi, and F.
Kishino, "Augmented reality: A class of
displays on the reality-virtuality continuum,"
1995, vol. 2351, pp. 282–292.



Extended Reality (XR)

AR

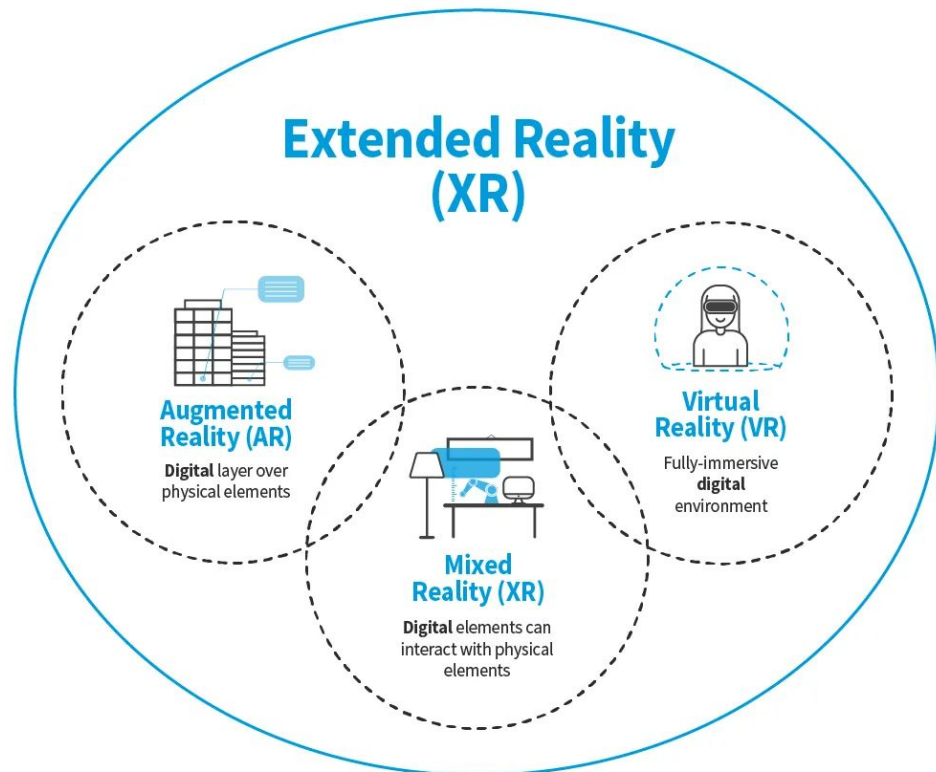
VR

MR

XR

Extended Reality (XR)

Umbrella term that encompasses any sort of technology that alters reality by adding digital elements to the physical or real-world environment by any extent.

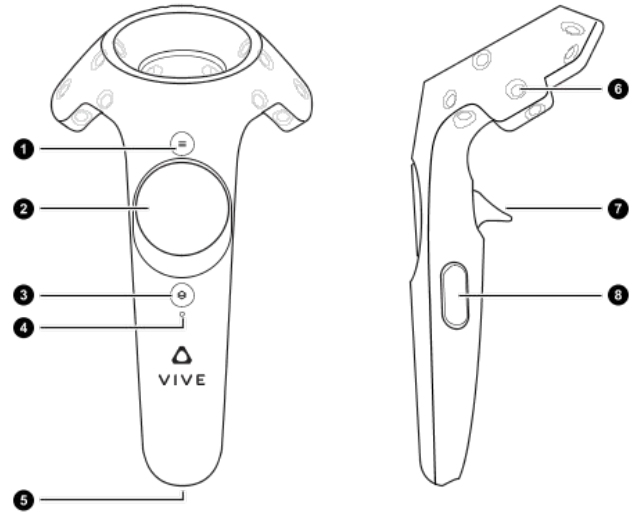


XR Qualities

- 3D Spatial Interaction
- Objects are part of the interaction environment (as interactors or interactables)
- Users are part of the interaction environment
- Many Contexts

3D Spatial Interaction

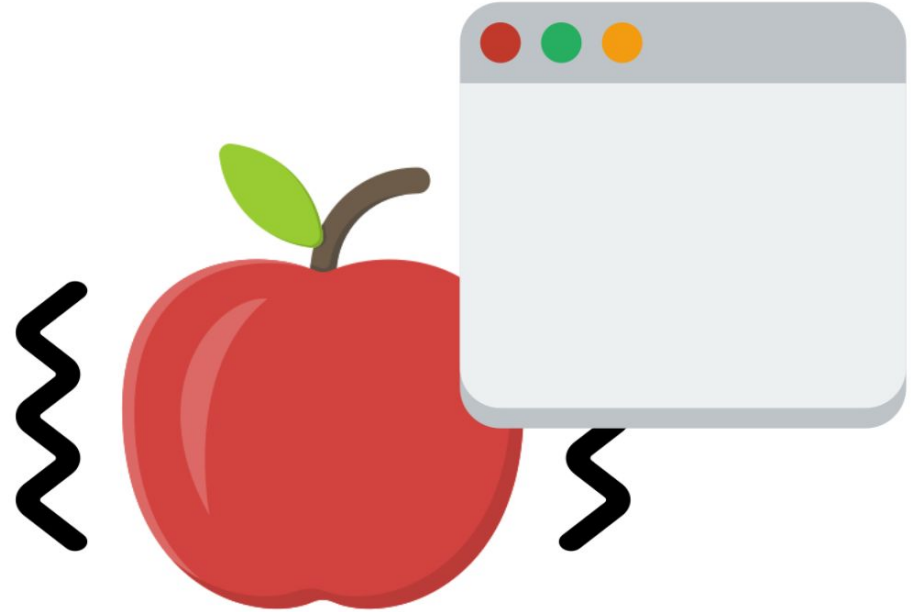
With Motion Controllers or technology to track the user's body, 3D spatial interaction is a staple in XR



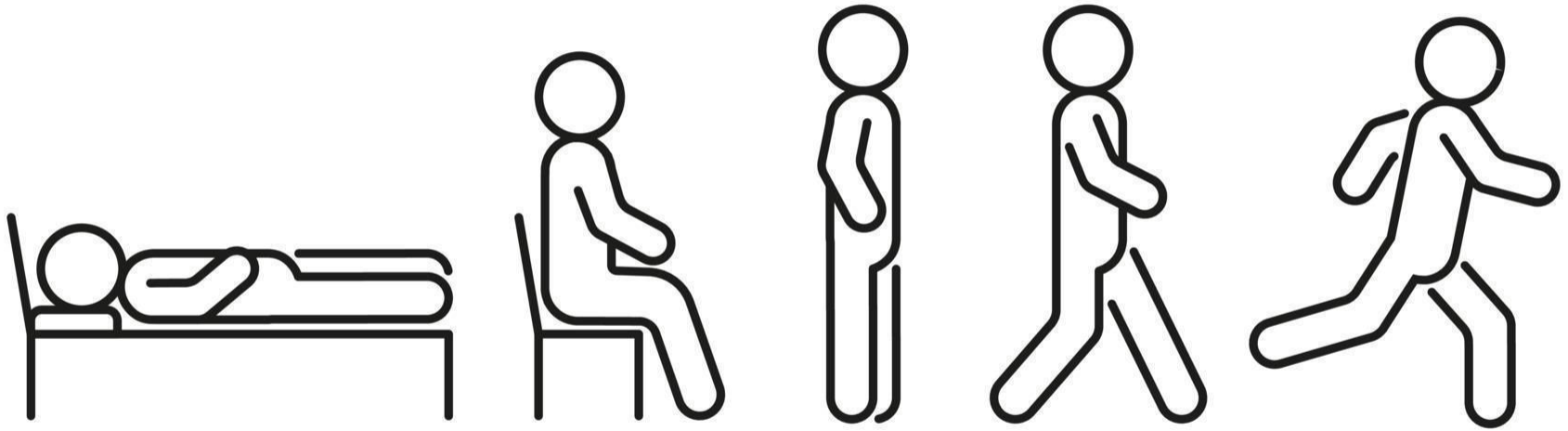
Objects are part of interaction environment (as Interactors or Interactables)

An object, whether physical or virtual, can be tracked in XR.

The apple can be an interactor.



User as part of the environment: Physical Space & Postures



Mobile Augmented Reality: Walking, Riding Vehicles, Driving Vehicles



XR's Many Contexts

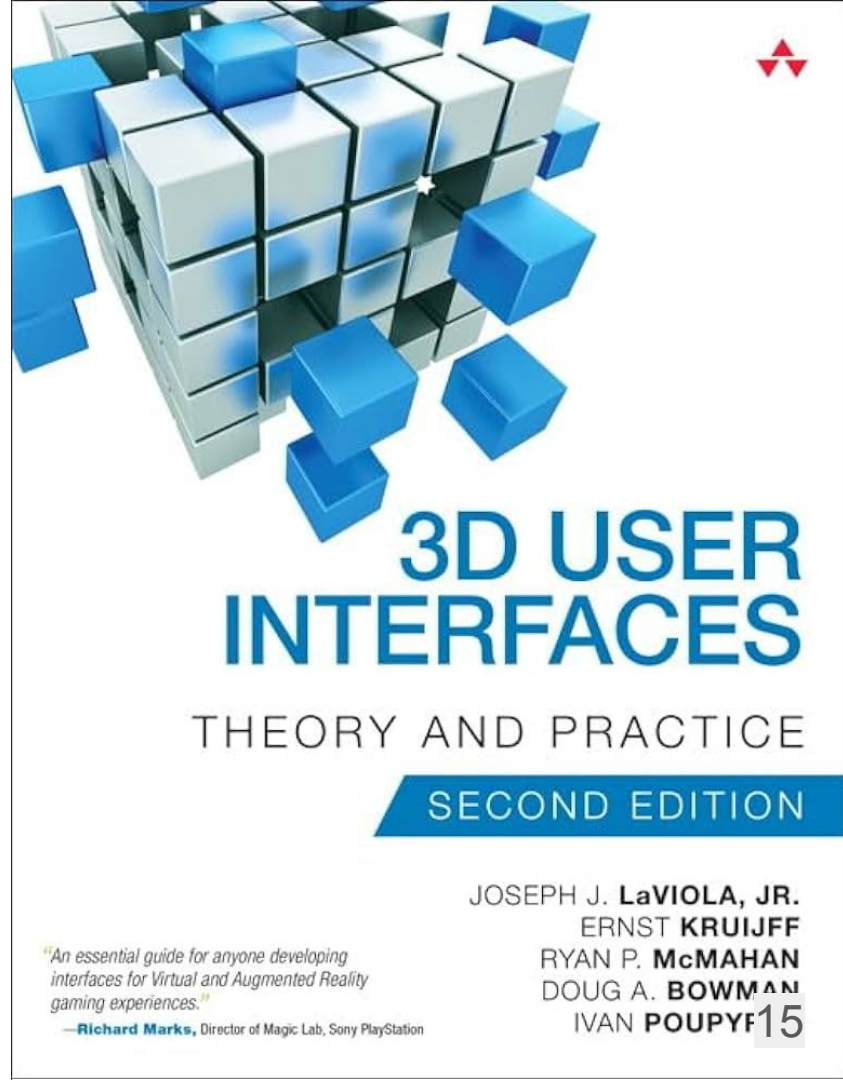


Different Contents: Work, Sports, Training, Medical, Entertainment, Health, Social

Existing Approach

3D User Interface

A user interface that involves 3D interaction.



Natural User Interface

A natural user interface or natural interface is a user interface that is effectively invisible, and remains invisible as the user continuously learns increasingly complex interactions.

BRAVE NUI WORLD

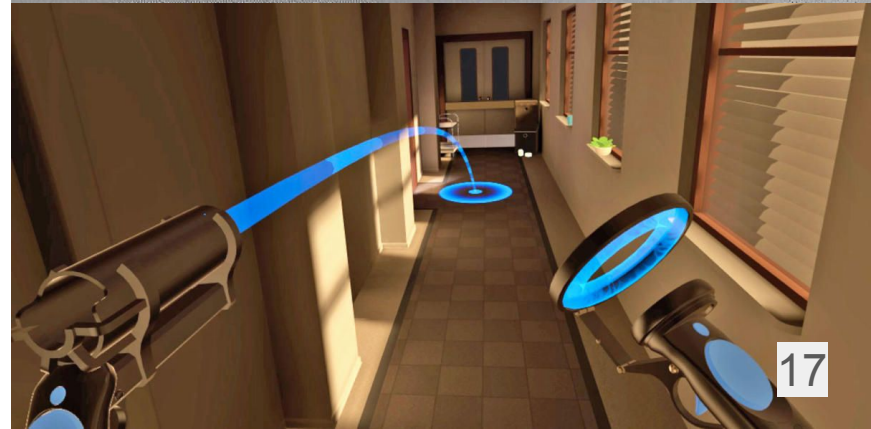
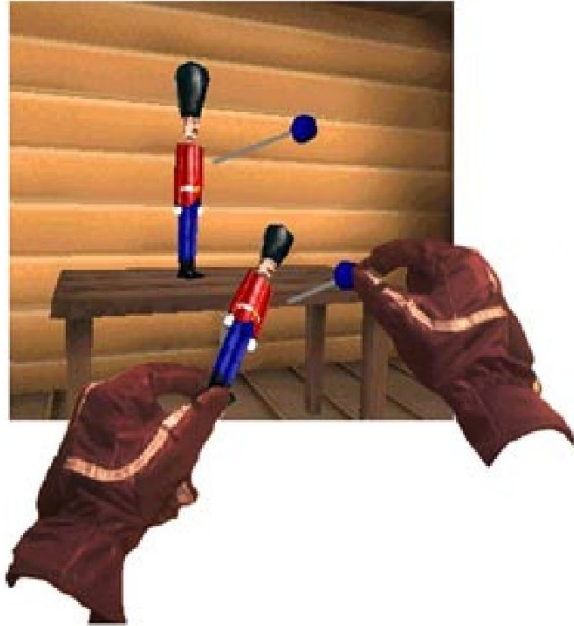
DESIGNING NATURAL
USER INTERFACES
FOR TOUCH AND GESTURE

DANIEL WIGDOR
DENNIS WIXON

MK
MORGAN KAUFMANN

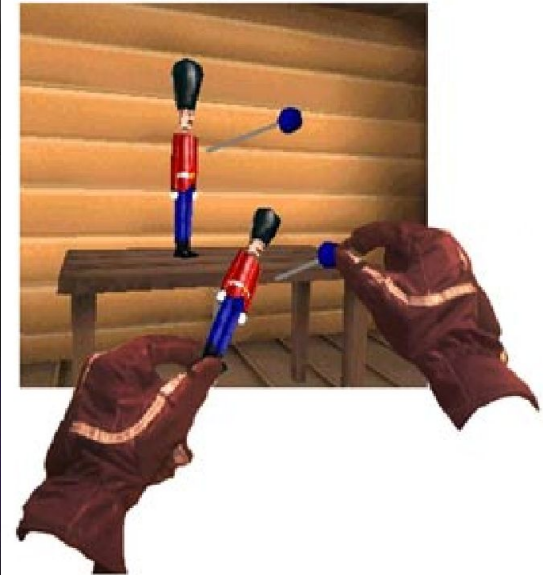
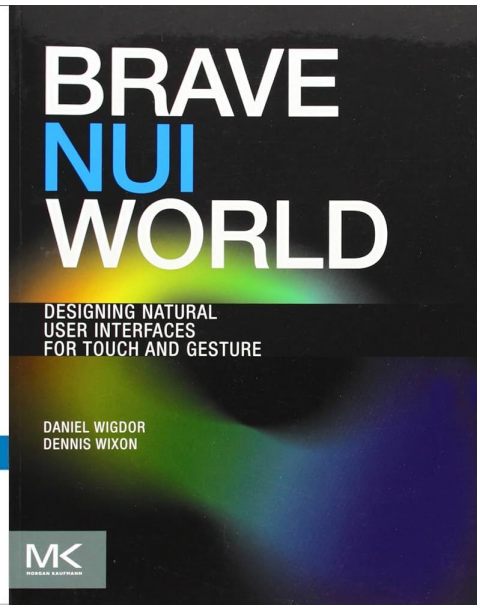
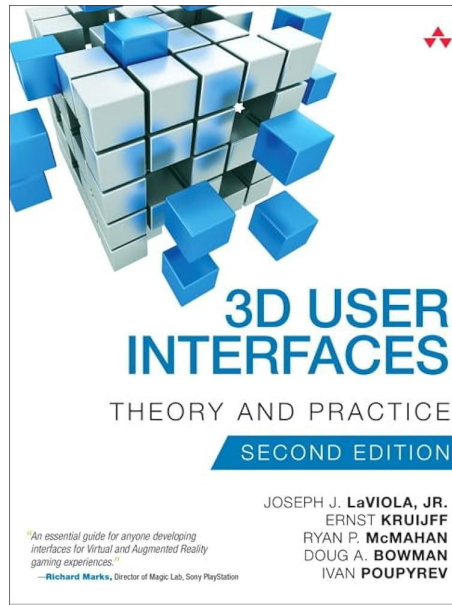
Hyperphysical User Interface

Hyperphysical User Interfaces do not follow the rules of real-world physics.



Many Interaction Techniques

Lots of interaction techniques were developed to address the many different needs.

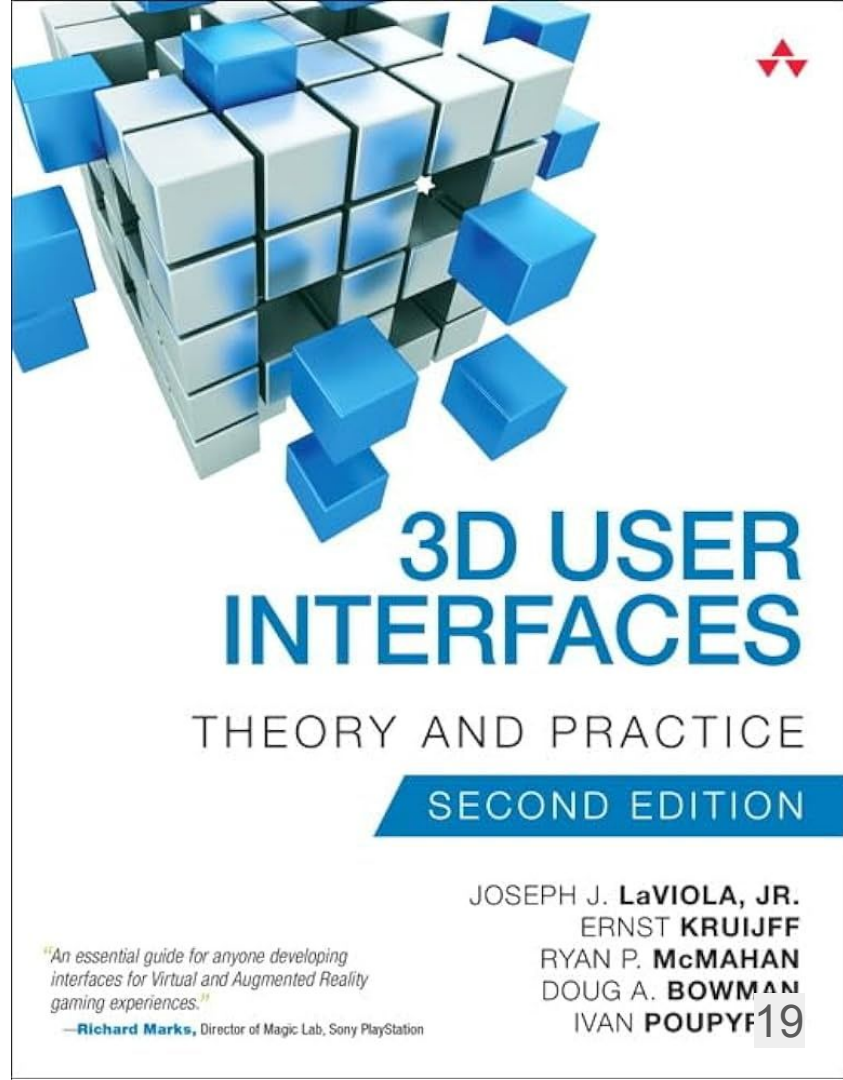


Many Interaction Techniques

In the 3D User Interfaces textbook, techniques are classified based on the type of user task

Let's look at one of the **most common** tasks

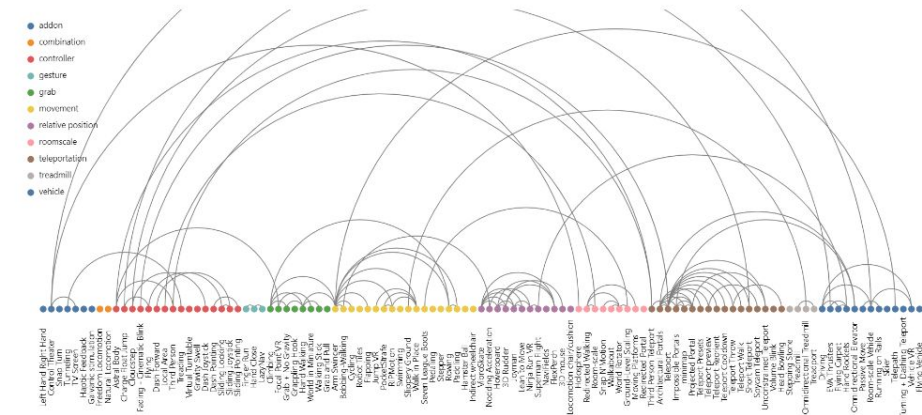
- 1) Selection and Manipulation
- 2) Travel**
- 3) System Control



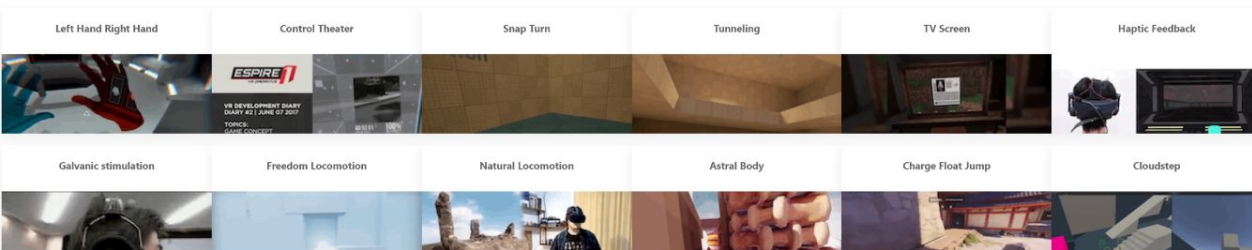
Similarity

Expert Similarity Database Similarity

Similarity threshold: 0.5



Gallery



LOCOMOTION FILTERS (109)



Degrees of Freedom

Hardware

- BOARD BUTTON CONTROLLER TRACKING DIGITIZER FOOT CONTROLLER GAMEPAD
- HAND TRACKING HEAD TRACKING NONE PEDALS PHONE ROBOTS SLIP SURFACE SOME
- SPECIFIC TREADMILL WHEEL

Motion Direction

- DEVICE FIXED GAZE LOCATION MARKER POINTING PULL STICK VARIOUS
- VEHICLE WALKING

Magical	YES	NO
Breaks Presence	YES	NO
Beyond Ground	YES	NO
Video Gamer	YES	NO

Posture	ANY	STANDING	SEATED	
Granularity	LOW	MED	HIGH	
Speed	N/A	LOW	MED	HIGH
Large VE	N/A	LOW	MED	HIGH
Multitasking	N/A	LOW	MED	HIGH

Energy Required	LOW	MED	HIGH
Spatial Awareness	LOW	MED	HIGH
Vection	LOW	MED	HIGH
Nausea	LOW	MED	HIGH
Embodiment	LOW	MED	HIGH
Intuitiveness	LOW	MED	HIGH

Challenges

Many different considerations such as contexts, scenarios, situations with the user as a part of the interaction environment

Many techniques to address the different contexts and scenarios, each with different strengths and weaknesses

Lack of a unified system control interface to allow the user to utilize the best technique for the situation at hand

Need for ways to **evaluate techniques** for different contexts

This Thesis's Approach

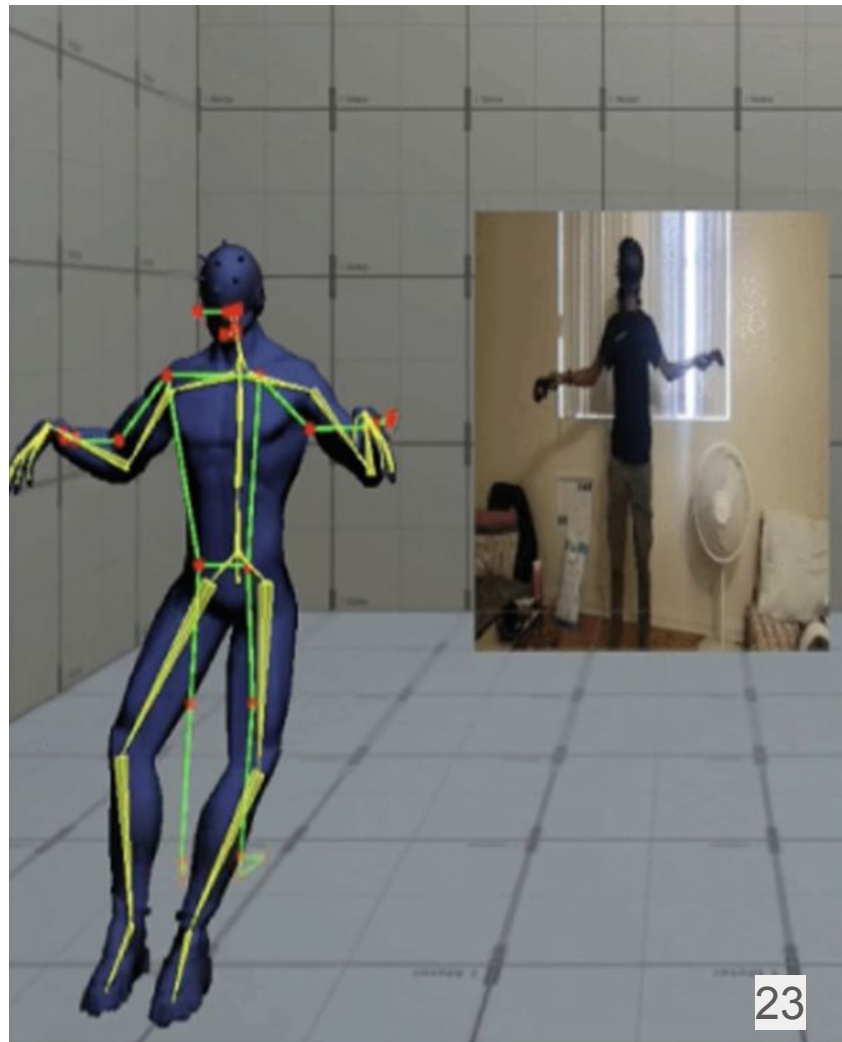
Assumptions

This thesis work applies primarily to 6 Degree of Freedom XR

The design presented also makes the following assumptions:

- The user's body can eventually be fully tracked

- Physical objects, environment can be fully tracked and its context known



XR simulated in VR

Proof of concepts are built and tested in Virtual Reality to simulate Extended Reality with spatial awareness.

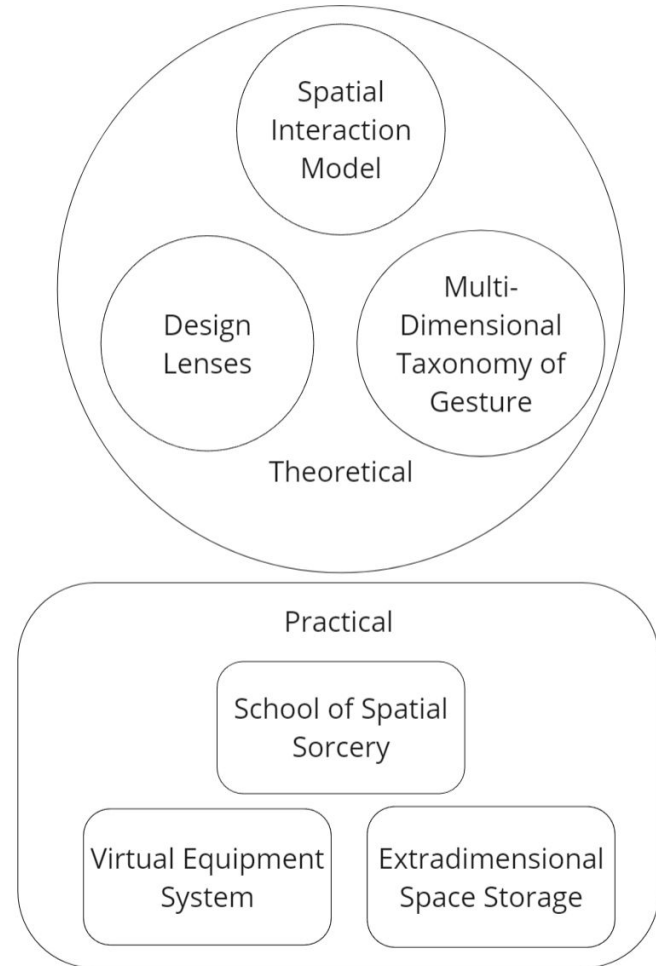


Problem	Solution	Result
Many qualities and contexts to design for in XR	Help design and create better interaction techniques	Implemented many interaction techniques in SSS, VES, and EDS
Have many interaction techniques but unable to determine the best interaction for the job	Help discover and determine the best interaction technique for the job	Created Spatial Interaction Model and the Design Lenses to use on the model. Expanded and adapted Gesture Taxonomy for XR
Have many interaction techniques but unable to access the best interaction for the job	Help manage and access the best interaction technique for the job	Interaction techniques that help manage repository of interactions, such as VES and EDS

Body of Work

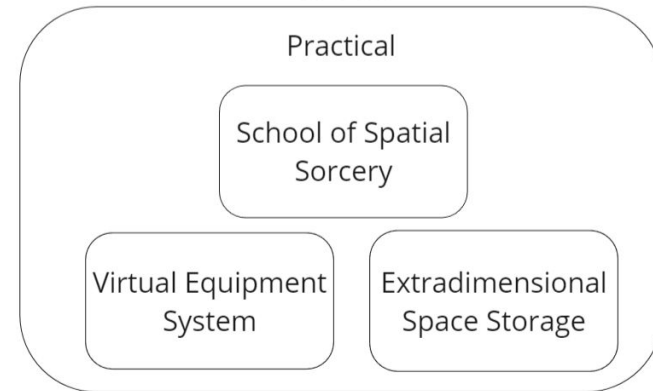
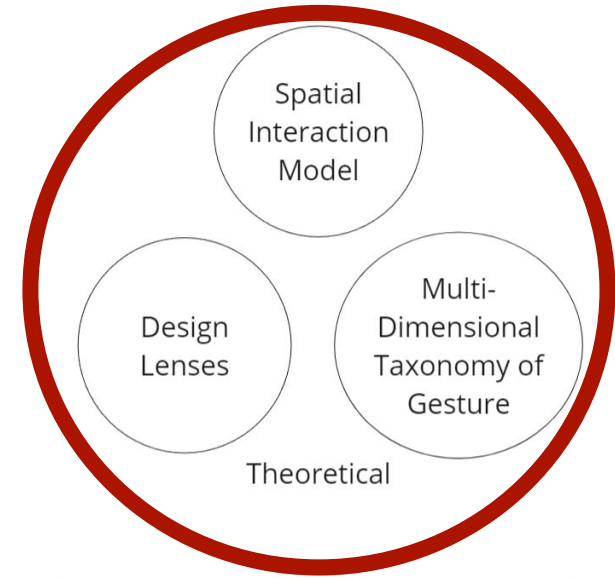
Approach

1. Identify and utilize **Design Lenses** for XR Interaction on the **Spatial Interaction Model**
2. Develop a **Multi-Dimensional Taxonomy** of Gesture as a design guide
3. **Explore and Prototype** different Interaction Techniques and Interaction Technique Management Solutions

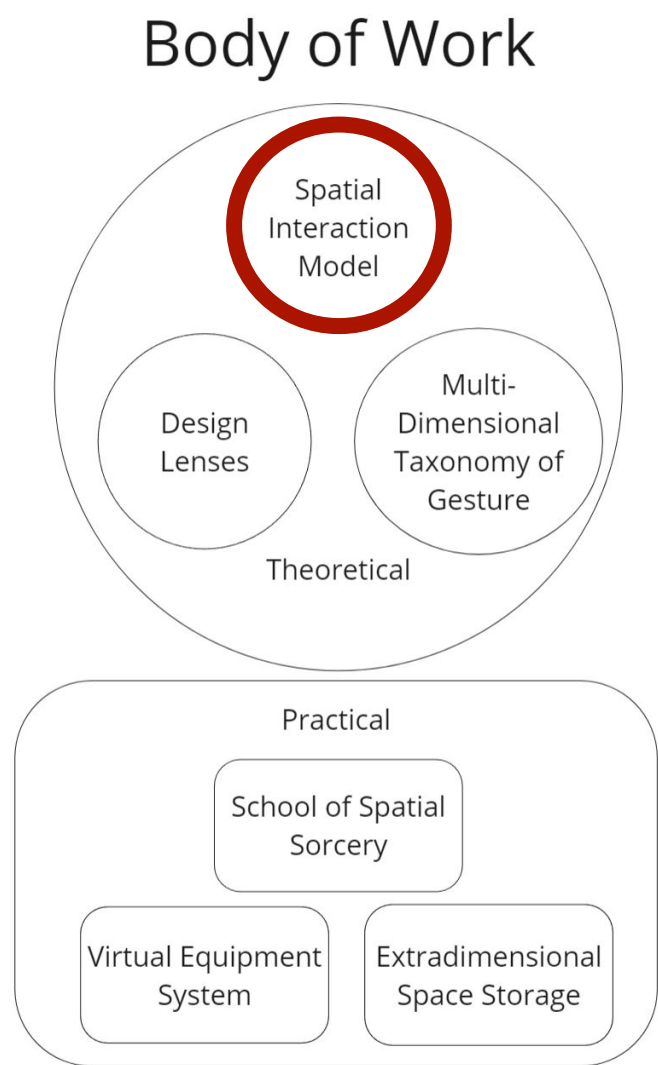


Theoretical Components

Body of Work



Spatial Interaction Model



What is Interaction?

“The term interaction is field-defining, yet surprisingly confused.”

Hornbæk, Kasper, and Antti Oulasvirta. "What is interaction?." CHI 2017

Concept	View of interaction	Key phenomena and constructs	Good interaction	Example support for evaluation and design
Dialogue	a cyclic process of communication acts and their interpretations	mappings between UI and intentions; feedback from the UI; turn taking	understandable; simple, natural; direct	methods/concepts for guessability, feedback, mapping; walkthroughs
Transmission	a sender sending a message over a noisy channel	messages (bits); sender and receiver; noisy channels	maximum throughput of information	metrics and models of user performance
Tool use	a human that uses tools to manipulate and act in the world	mediation by tools; directness of acting in the world; activity as a unit of analysis	useful and transparent tools; amplification of human capabilities	compatibility in instrumental interaction; break down analysis
Optimal behavior	adapting behavior to goals, task, UI, and capabilities	rationality; constraints; preferences; utility; strategies	improves or reaches maximum or satisfactory utility	models of choice, foraging, and adaptation
Embodiment	acting and being in situations of a material and social world	intentionality; context; coupling	provides resources for and supports fluent participation in the world	studies in the wild; thick description
Experience	an ongoing stream of expectations, feelings, memories	non-utilitarian quality; expectations; emotion	satisfies psychological needs; motivating	metrics of user experience; experience design methods
Control	interactive minimization of error against some reference	feedforward; feedback; reference; system; dynamics	rapid and stable convergence to target state	executable simulations of interactive control tasks

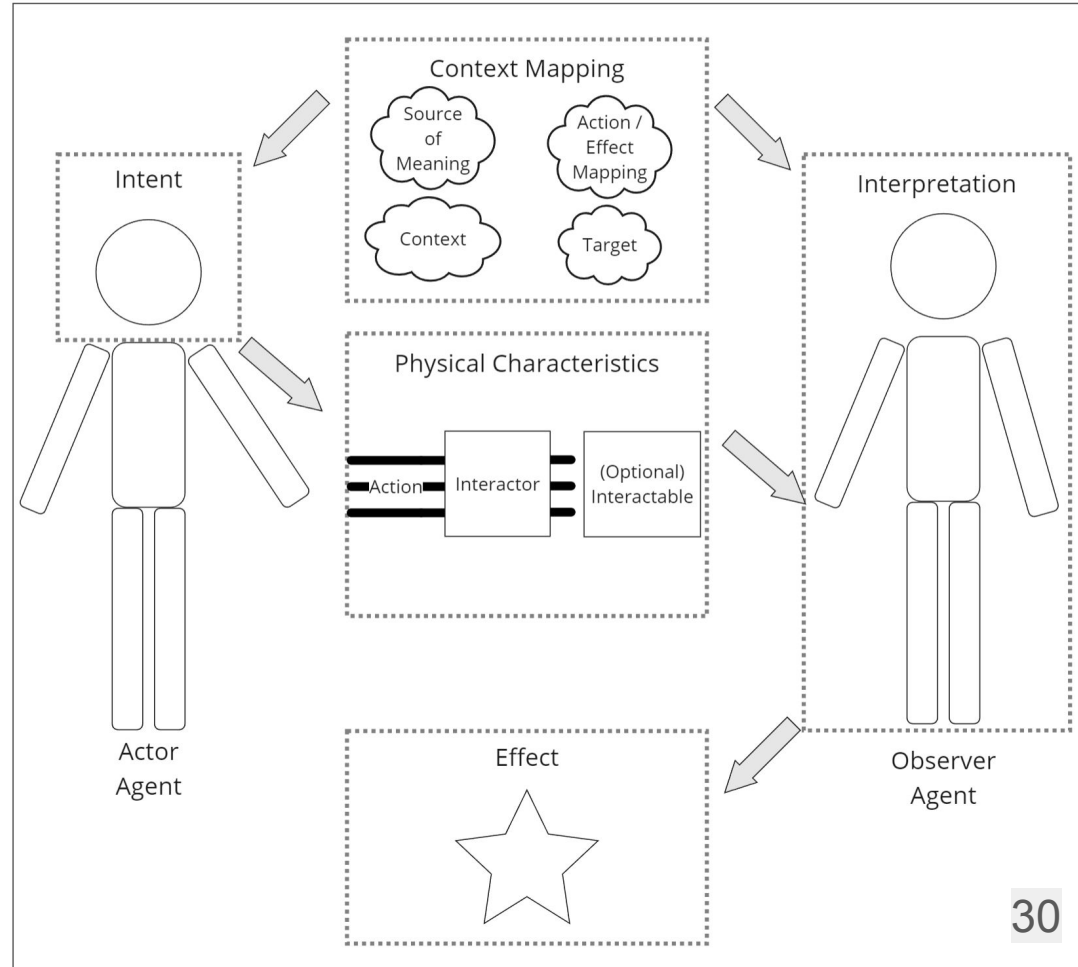
Table 1. Overview of some key concepts of interaction in HCI literature. The columns sum up the core view of what interaction is, the key phenomena that the view has helped see and their associated constructs, the notion of good interaction that follows from the view, and the key techniques and methods to help evaluating and designing user interfaces.

Spatial Interaction Model

A model based on XR qualities

A model to apply design lenses

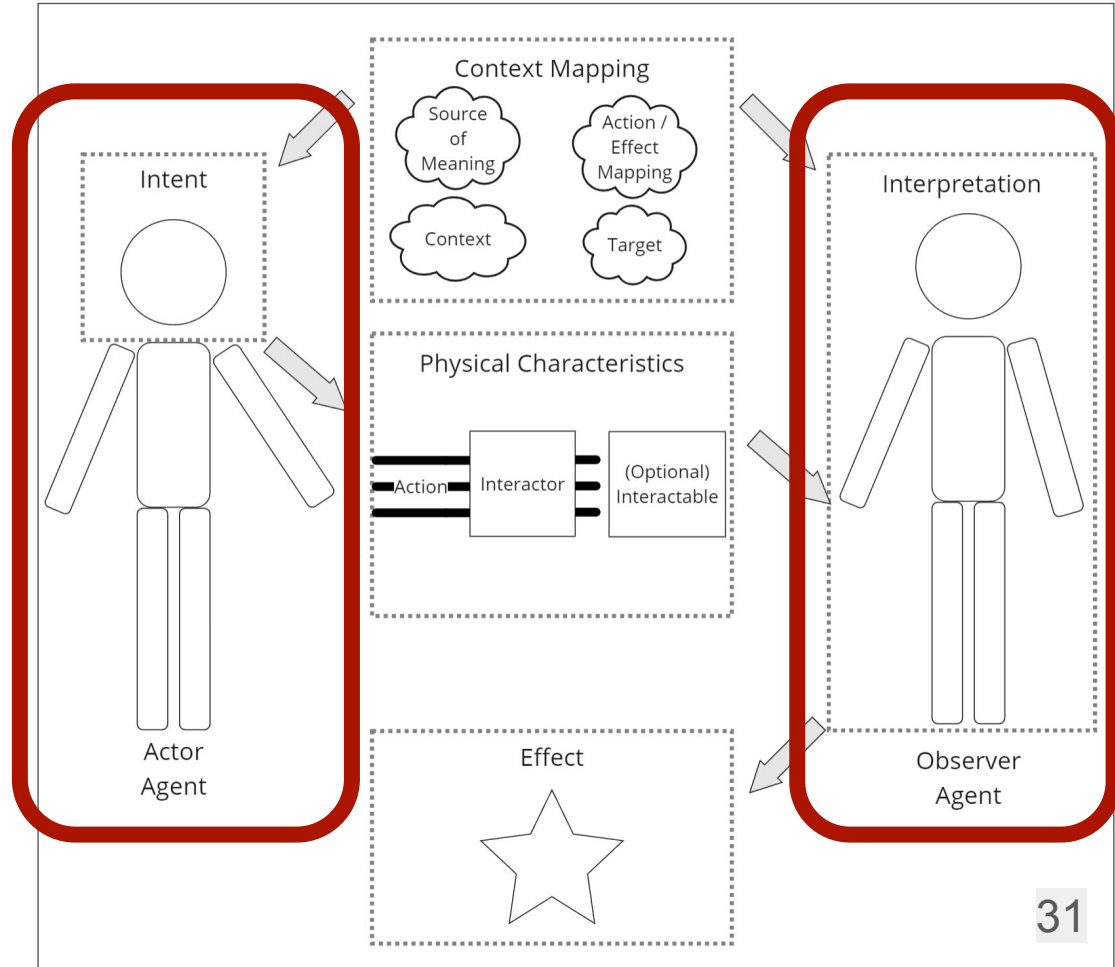
Spatial Interaction Model



Spatial Interaction Model

A model based on XR qualities

A model to apply design lenses

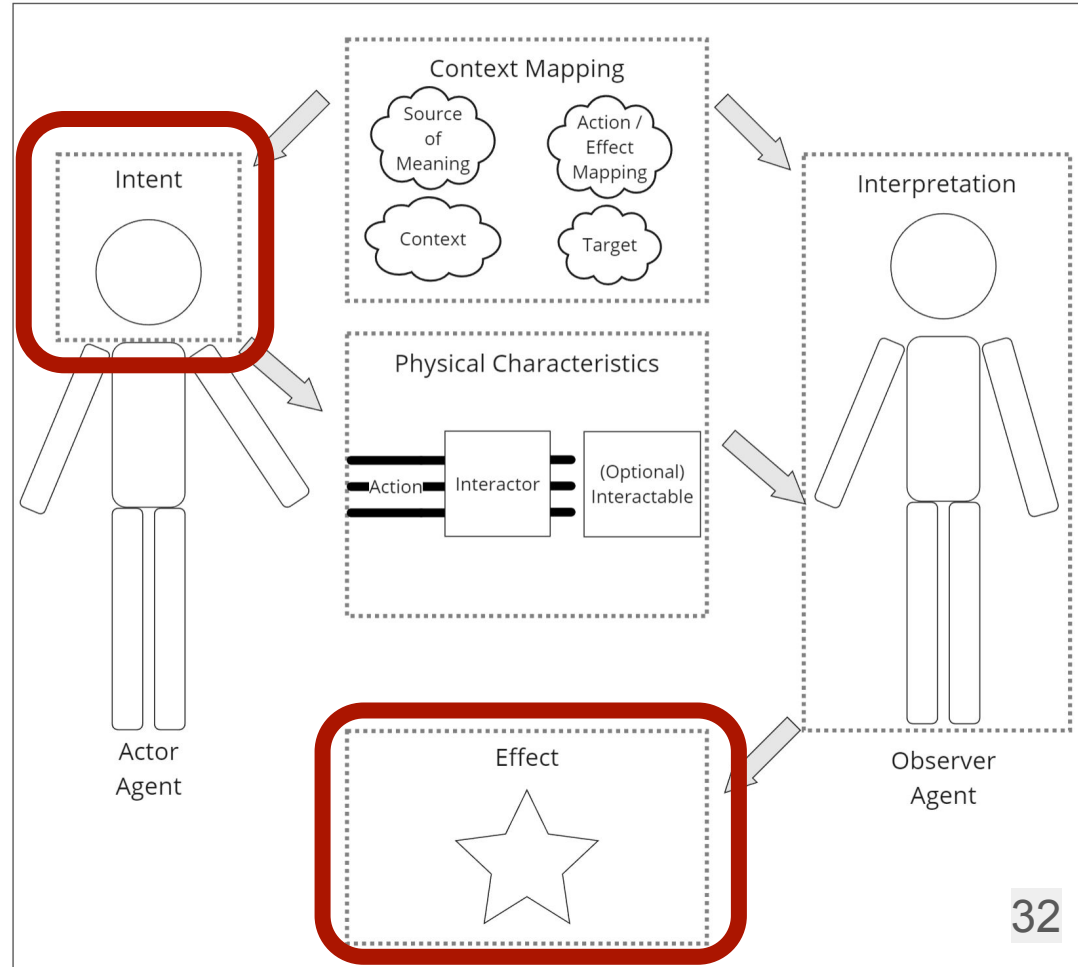


Spatial Interaction Model

A model based on XR qualities

A model to apply design lenses

Spatial Interaction Model

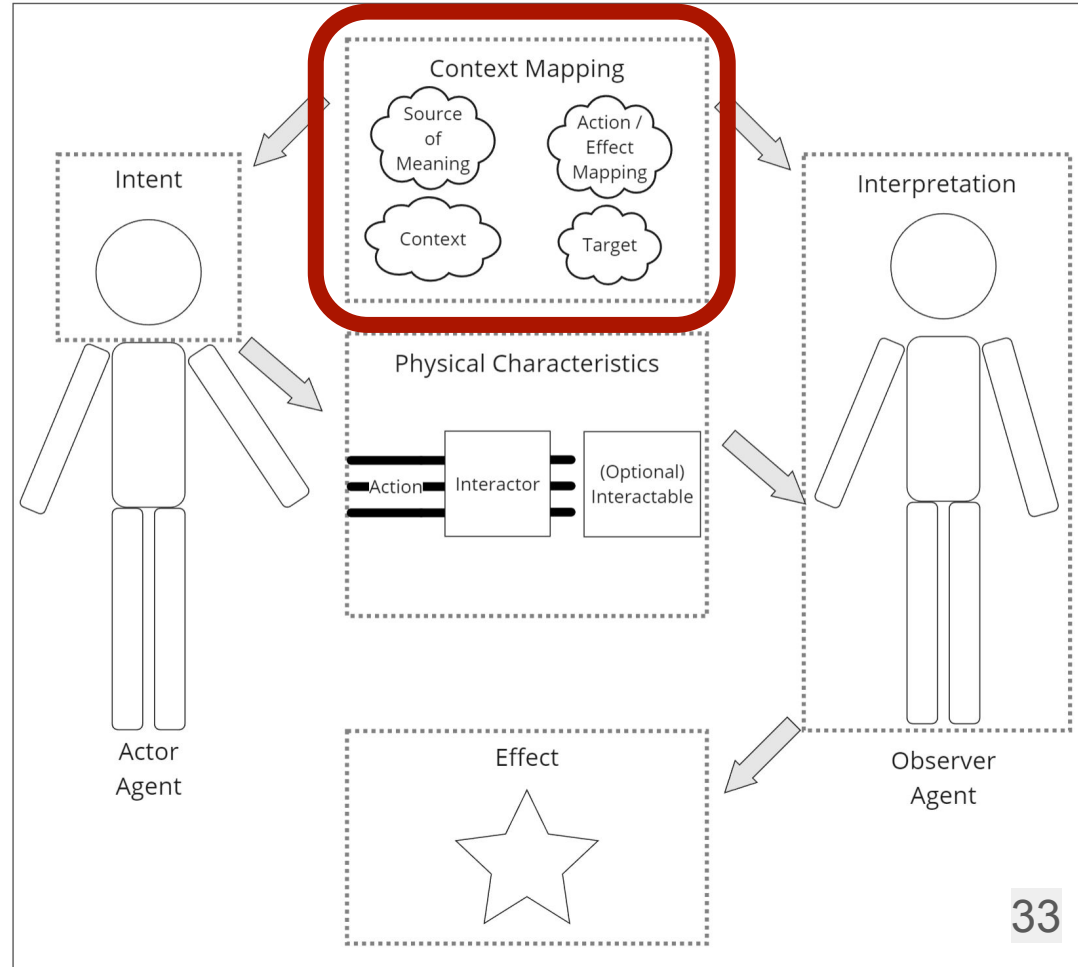


Spatial Interaction Model

A model based on XR qualities

A model to apply design lenses

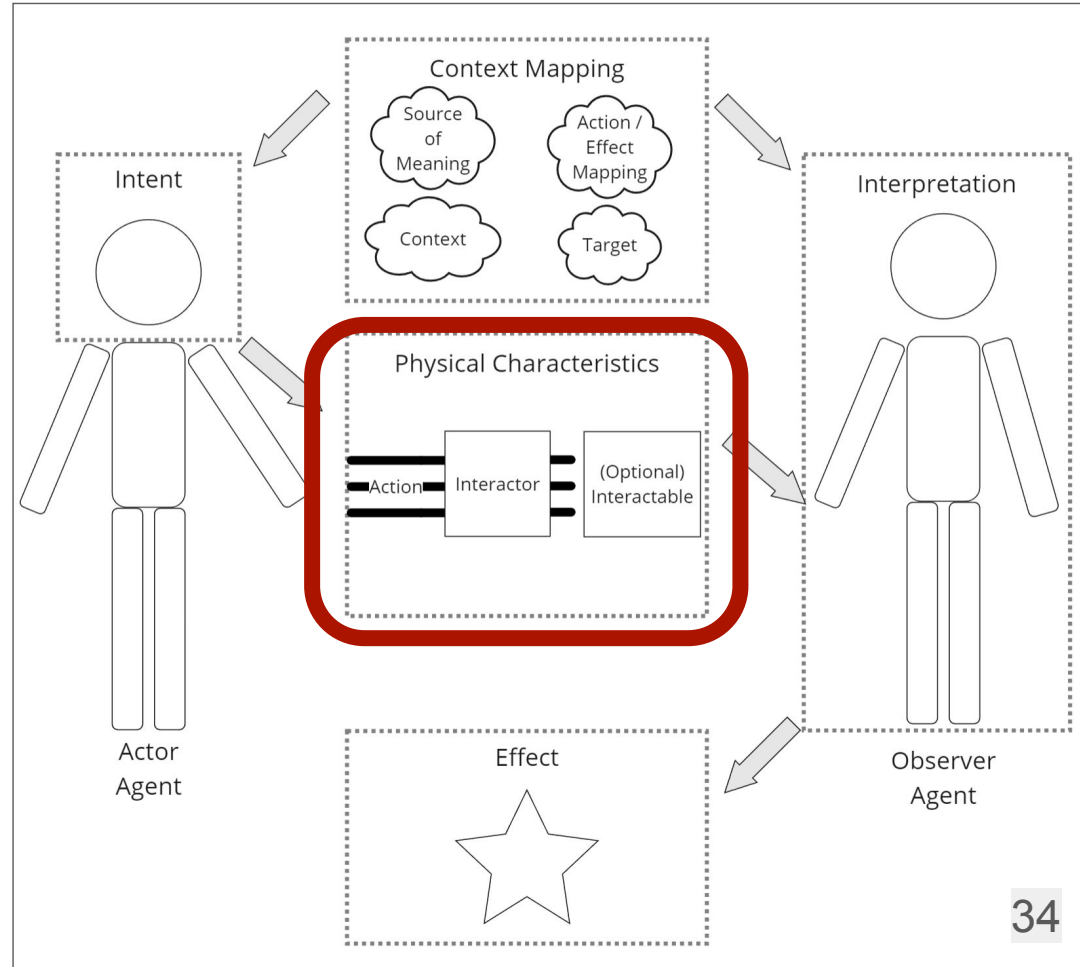
Spatial Interaction Model



Spatial Interaction Model

A model based on XR qualities

A model to apply design lenses

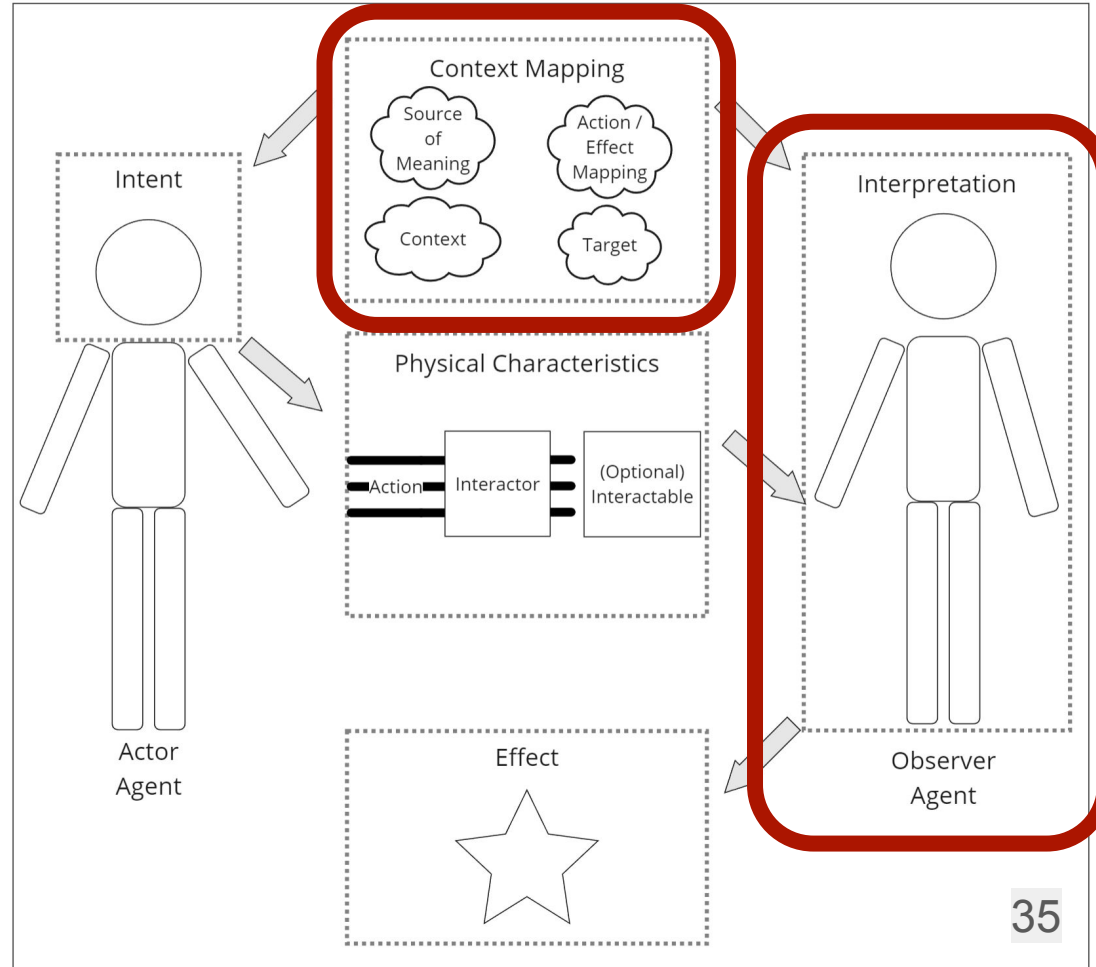


Spatial Interaction Model

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Spatial Interaction Model

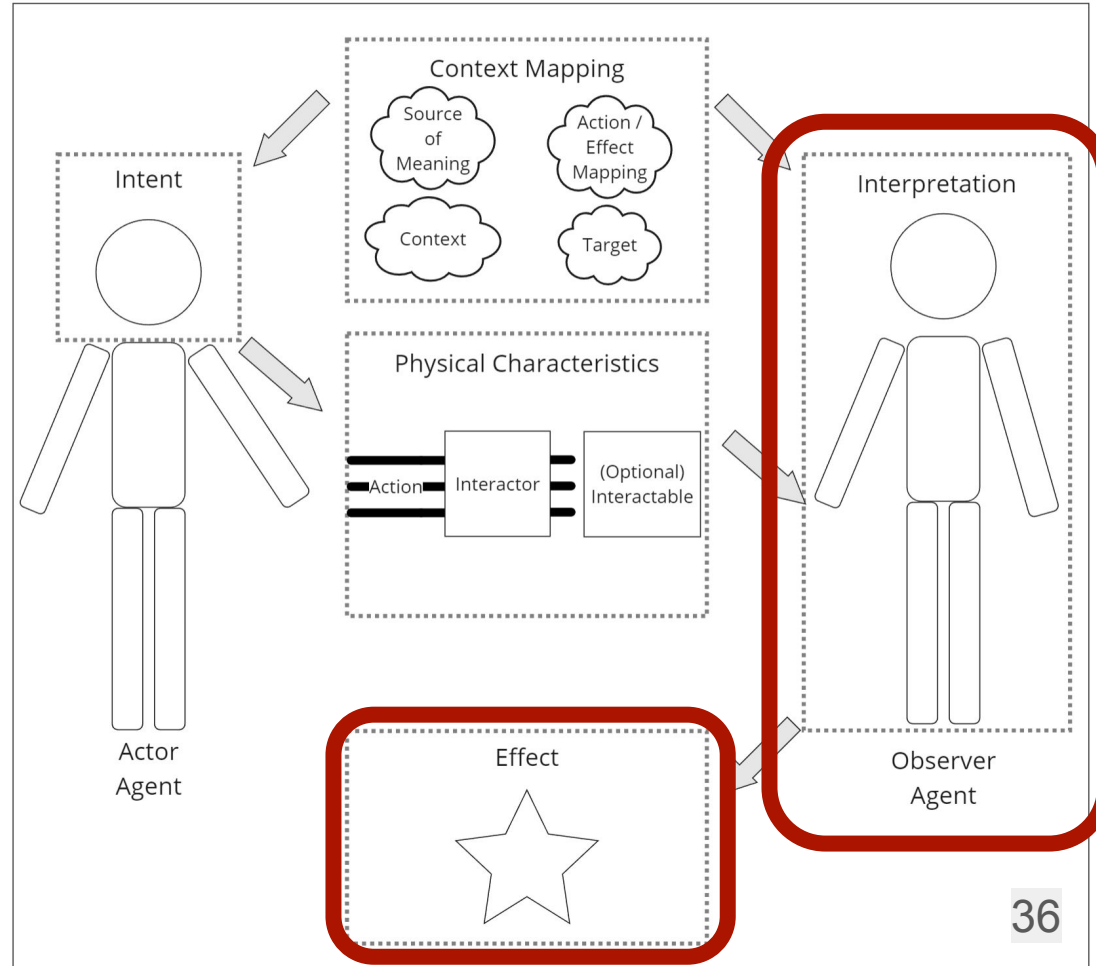


Spatial Interaction Model

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A model to apply design lenses

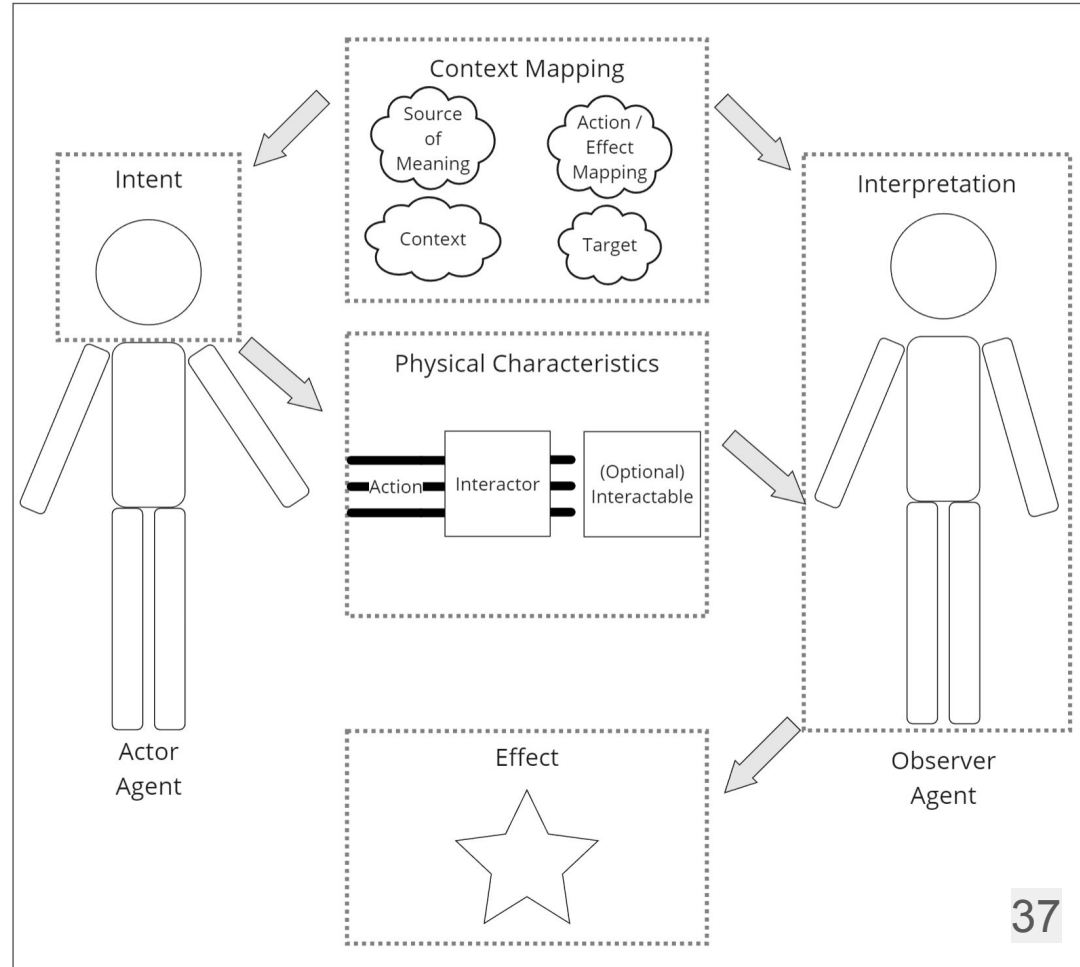
Spatial Interaction Model



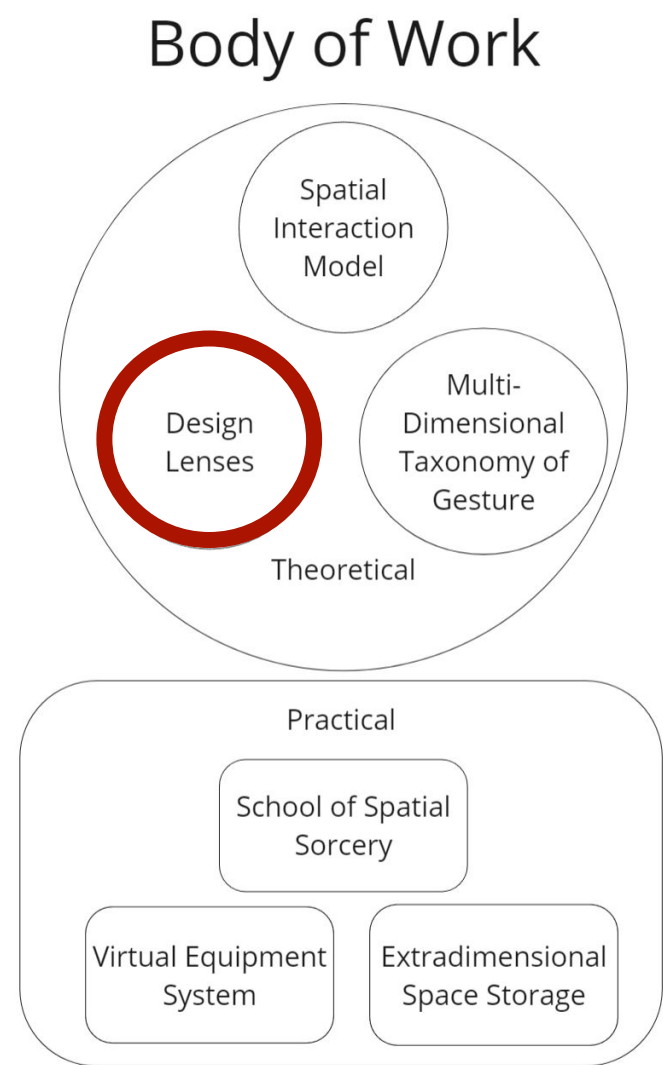
Spatial Interaction Model

A model based on XR qualities

A model to apply design lenses



Design Lenses



Design Lenses

Hyperphysical User Interface

Whole-Body Interaction

Extradimensional Space

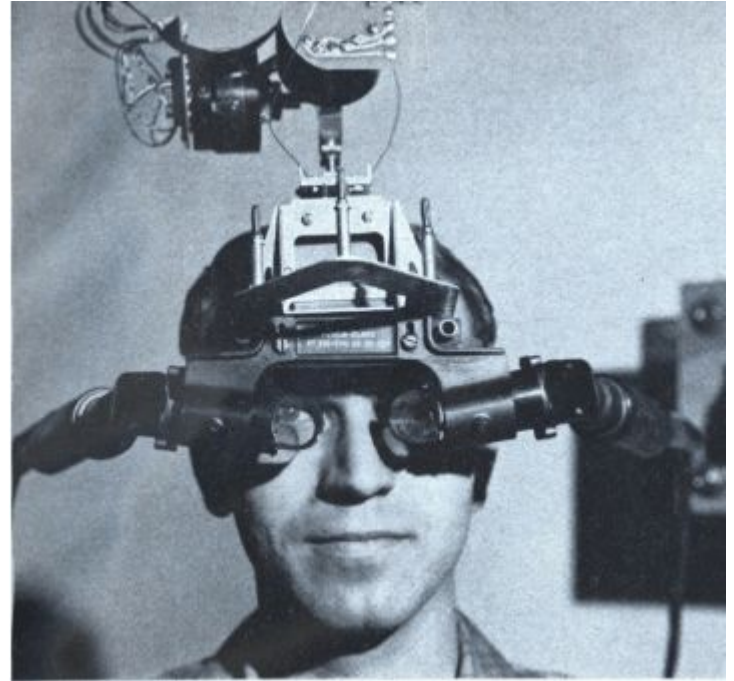


Design Lens

Hyperphysical User Interface

“The Ultimate Display”

In Ivan Sutherland’s classic article from 1965 “The Ultimate Display”, he stated **“There is no reason why the objects displayed by a computer have to follow the ordinary rules of physical reality with which we are familiar.”**



The Sword of Damocles by Ivan Sutherland

Aspects of Hyperphysicality

Manifestation -> Action -> Effect

Surrogate Object

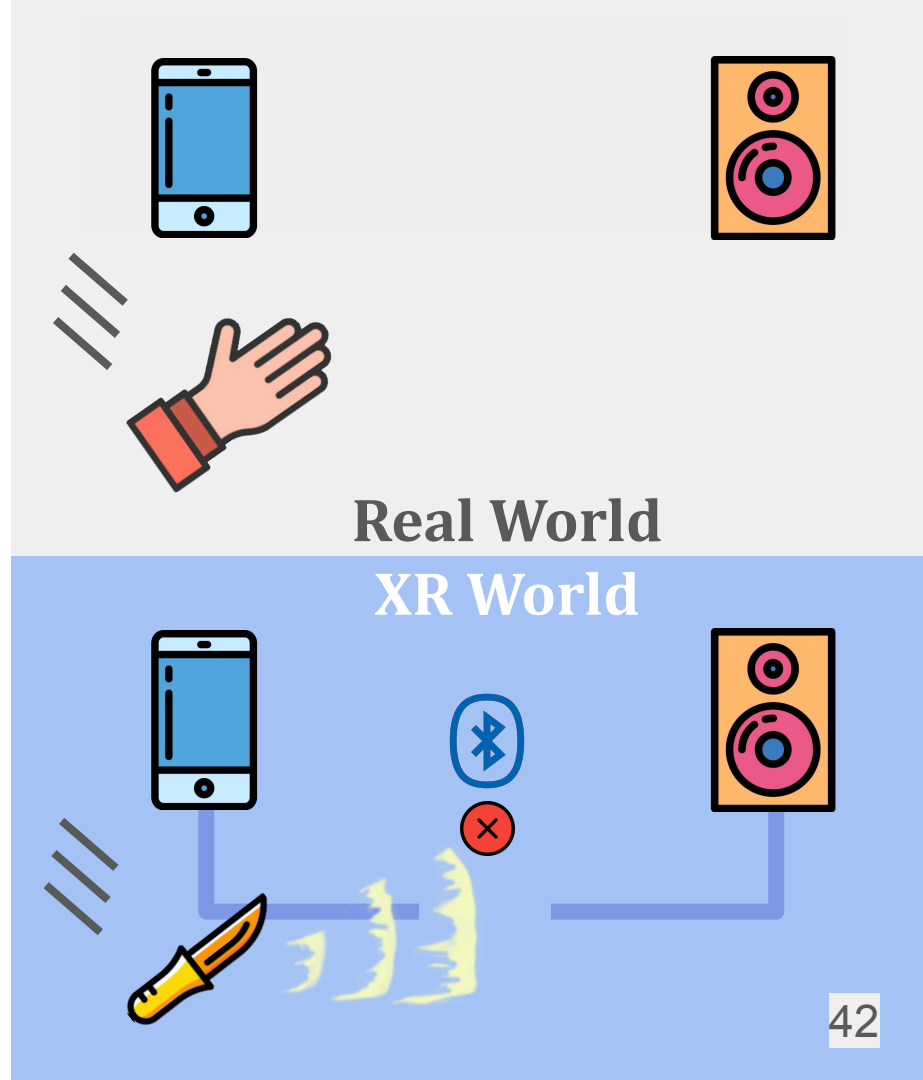
hand blade -> blade

Surrogate Action

chop -> disconnecting wave

Surrogate Effect

Chopped air-> disconnect)



Aspects of Hyperphysicality

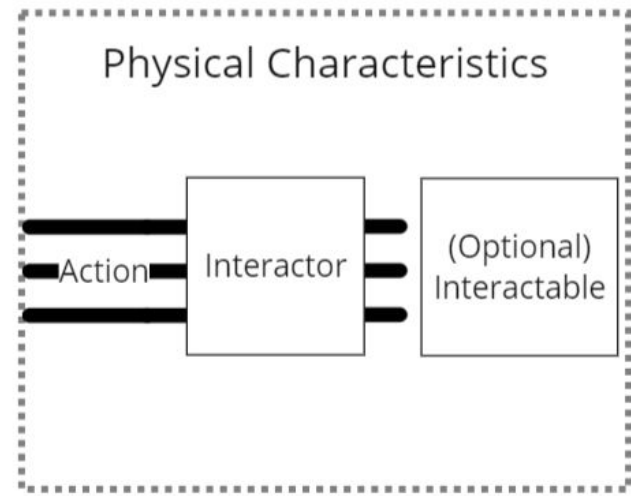
Manifestation -> Action -> Effect

Manifestation

Interactor(s)
Interactable(s)
Environment

Action

Effect



Hyperphysicality in Manifestation

Manifestation -> Action -> Effect



Manifestation -> Action -> Effect



XORTEX 2BXX

THE LAB

Manifestation -> Action -> Effect

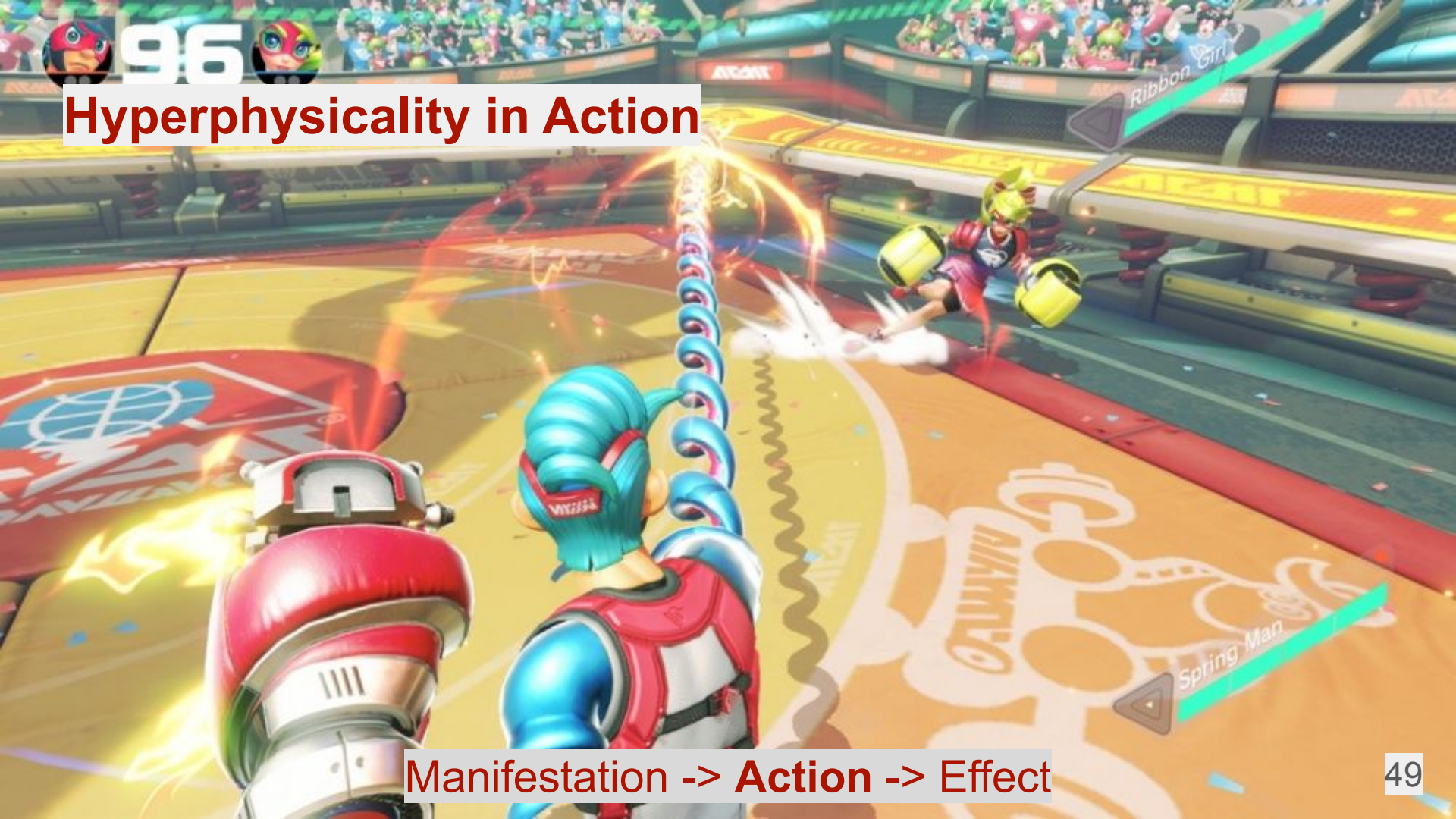


Manifestation -> Action -> Effect

Hyperphysicality in Action

Manifestation -> **Action** -> Effect

Hyperphysicality in Action



Manifestation -> **Action** -> Effect

Hyperphysicality in Action



Manifestation -> **Action** -> Effect

Other Examples in Hyperphysicality in Action

- Various Hand Gestures
 - Finger Gun
 - Stop (Block) Gesture
- Disembodied hand being controlled remotely
- Various Locomotion Techniques
 - Pull to Walk
 - Swing to Walk
 - Finger Walking

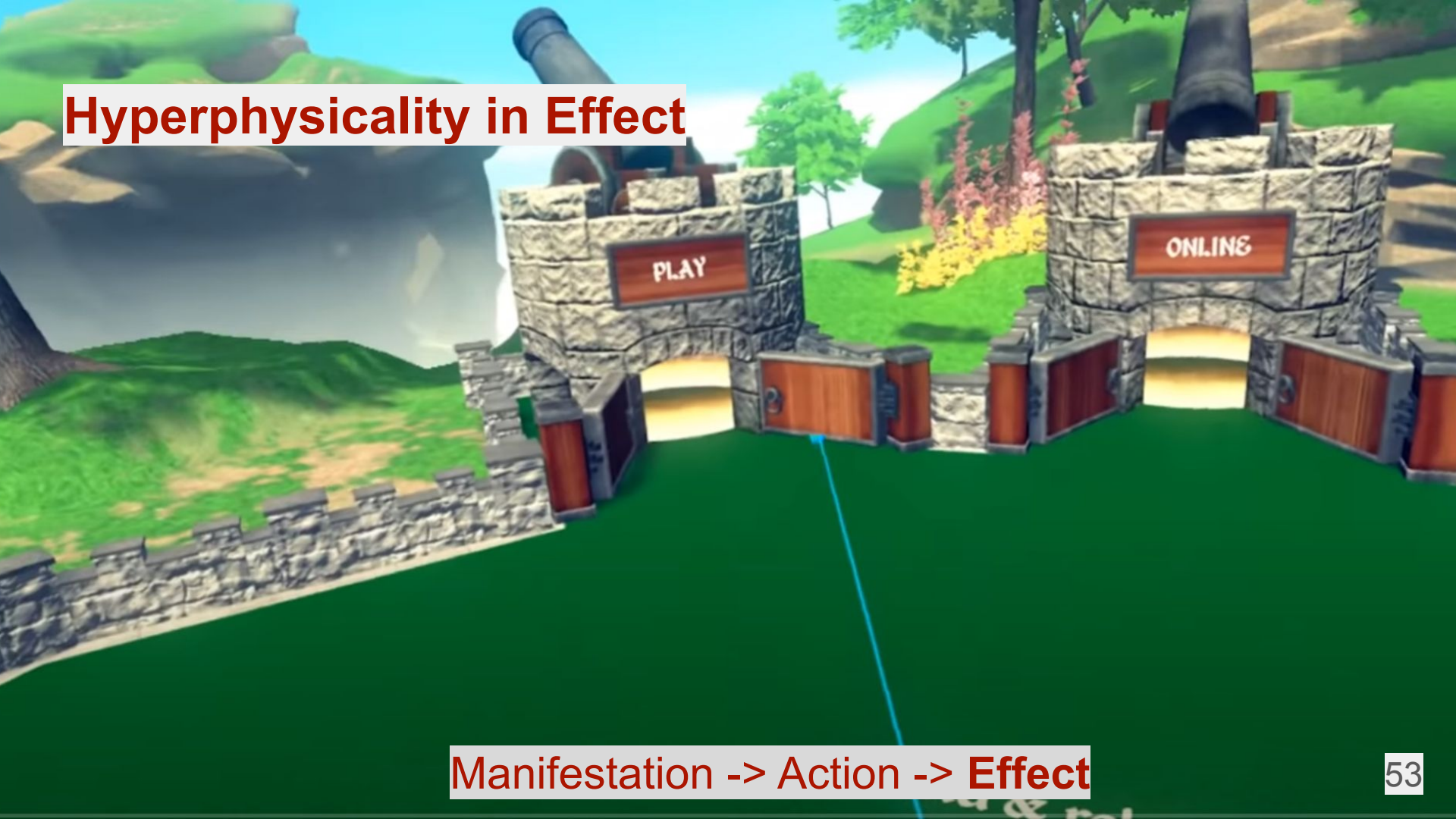


Manifestation -> **Action** -> Effect

Hyperphysicality in Effect

Manifestation -> Action -> **Effect**

Hyperphysicality in Effect



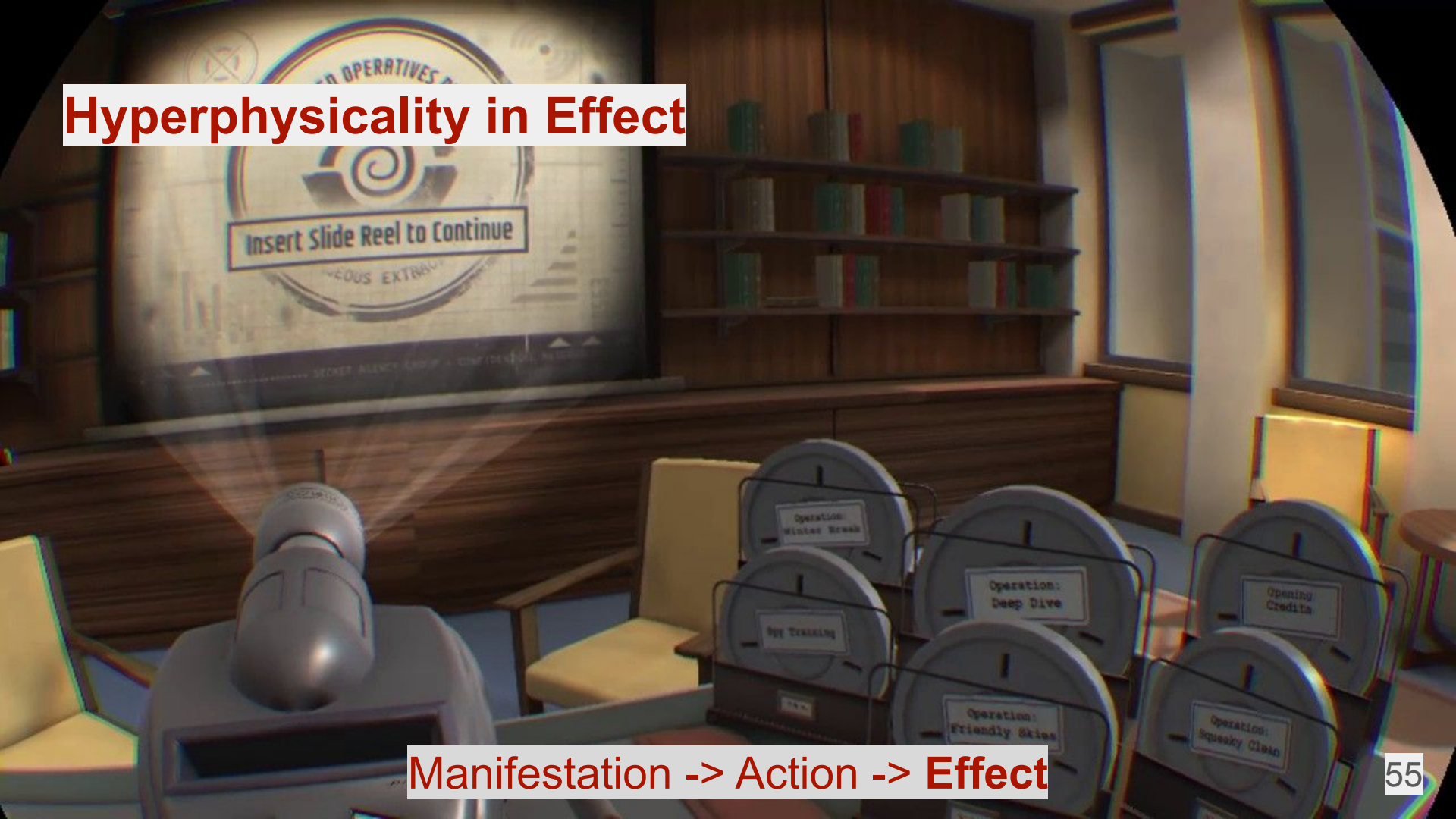
Manifestation -> Action -> **Effect**

Hyperphysicality in Effect



Manifestation -> Action -> Effect

Hyperphysicality in Effect



Manifestation -> Action -> **Effect**

Hyperphysical Lenses

- Lens of Surrogate Manifestation
- Lens of Surrogate Action
- Lens of Surrogate Effect
- Lens of Hyperphysical References

The Lens of Hyperphysical Reference



Consider common sources of seemingly impossible and fantastical phenomena with which the user may be familiar. Draw inspiration and establish common grounds using cartoon physics, the principles of stage magic, magic systems from real-life rituals or fantasy novels, technologies in science fiction, etc.

- *What source of hyperphysicality can be referenced to aid user understanding?*
- *How easily can this concept of hyperphysicality be taught to the user?*

Design Lens

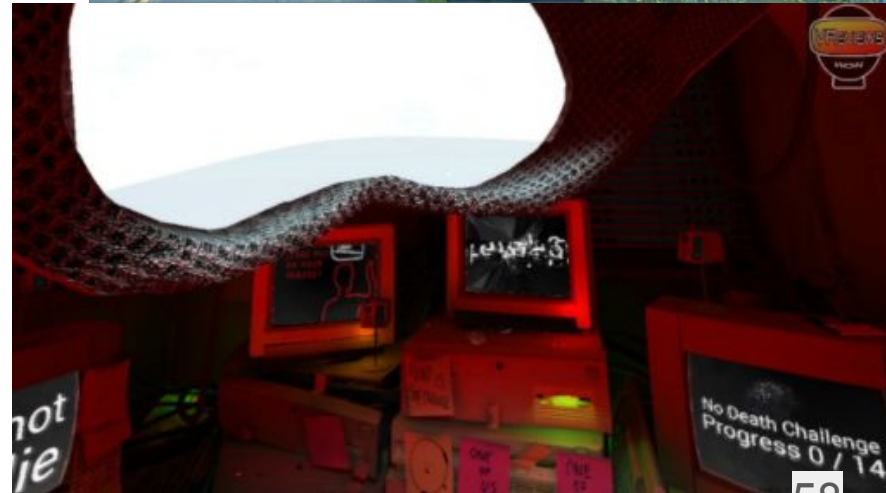
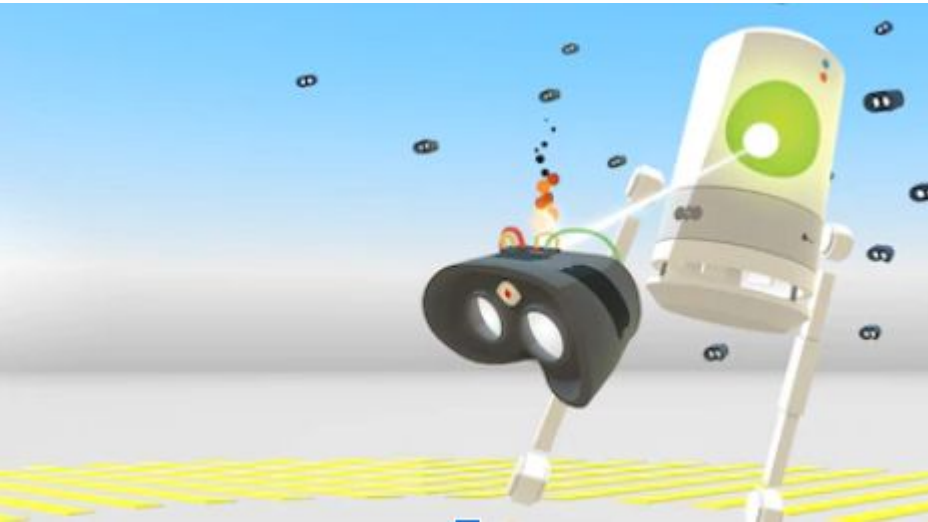
Whole-Body Interaction

Head as an Interactor or Interactable

The Lab - Metaphor for Entering another World

Fantastic Contraption - Storage Space

Various VR Games - putting food next to the mouth to eat



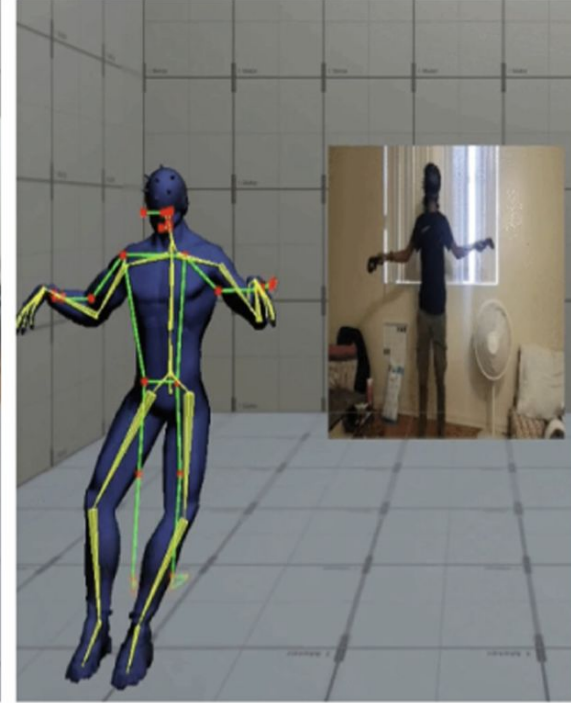
Hand as an Interactor or interactable



<https://twitter.com/pushmatrix/status/1229781239445389315>

By Daniel Beauchamp @pushmatrix

Other Body Parts Enabled by Advancing Technology

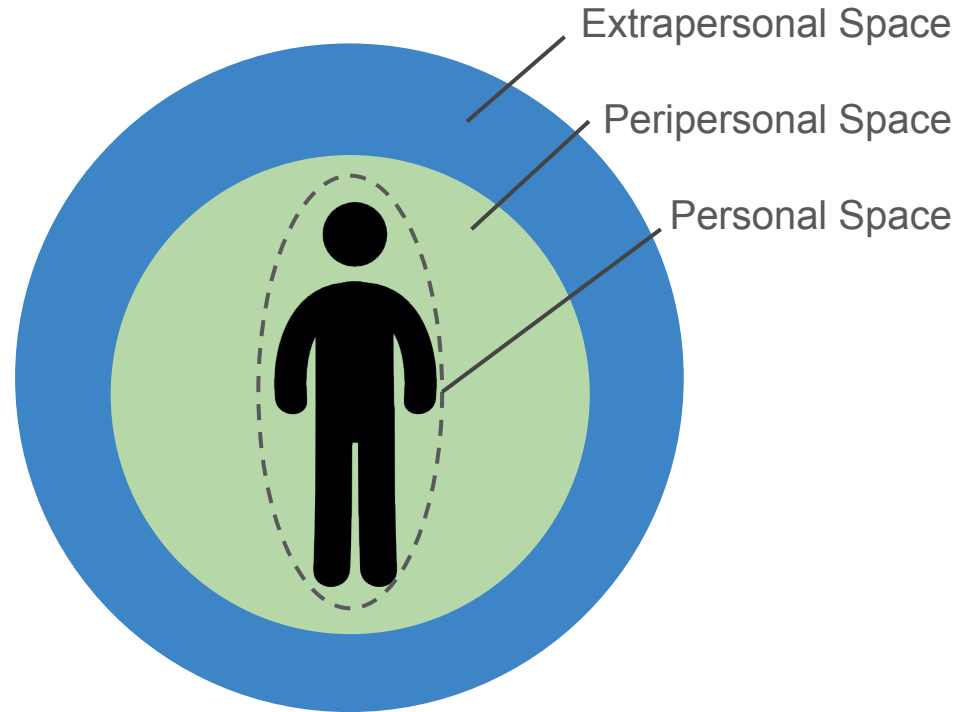


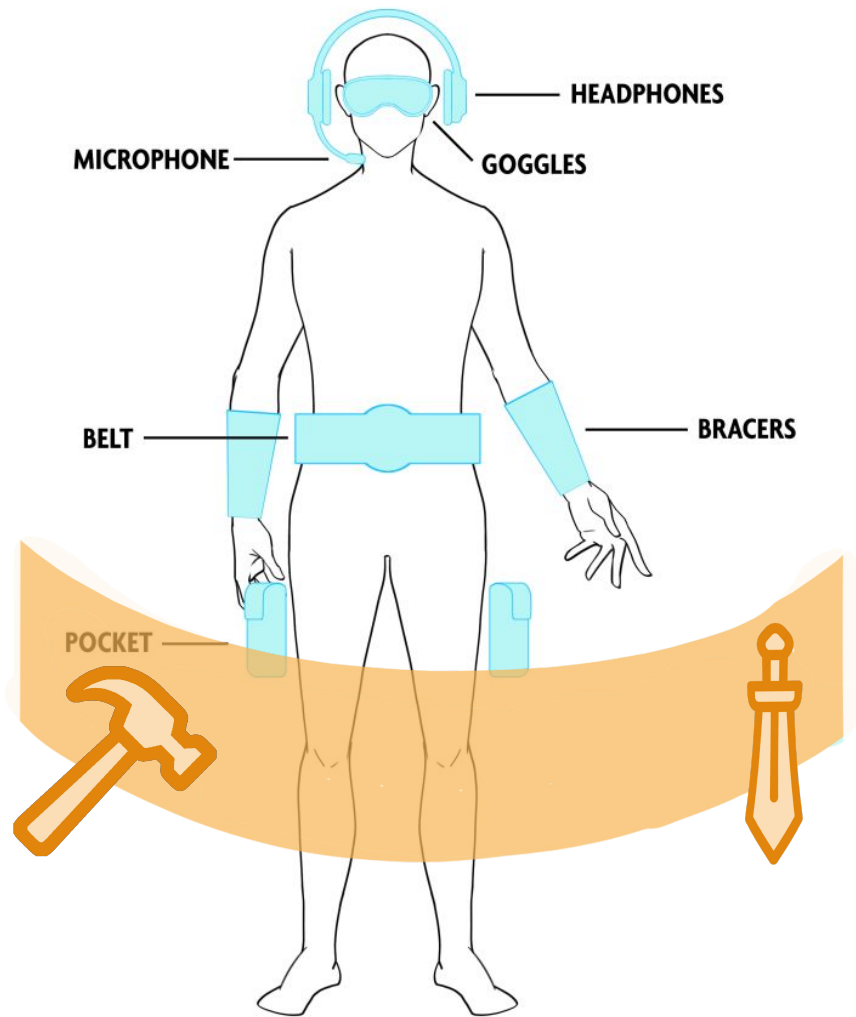
Personal, Peripersonal, and Extrapersonal Space

Personal space: the area immediately bordering the body

Peripersonal space: the area that is within the distance of the user's reach

Extrapersonal space: the area beyond the user's hand reach without help of tools





Whole-Body Interaction Lenses

Lens of Interaction Roles

Lens of Soma-Semantic

Lens of Body Capability

The Lens of Body Capability



Consider the strengths and weaknesses of this body part. Ask yourself these questions

- *Is this body part a good fit for the technique and task?*
- *Can this interaction technique be performed using a different body part?*
- *Can Hyperphysicality be used to provide accessibility for those with restricted body movement?*

Design Lens

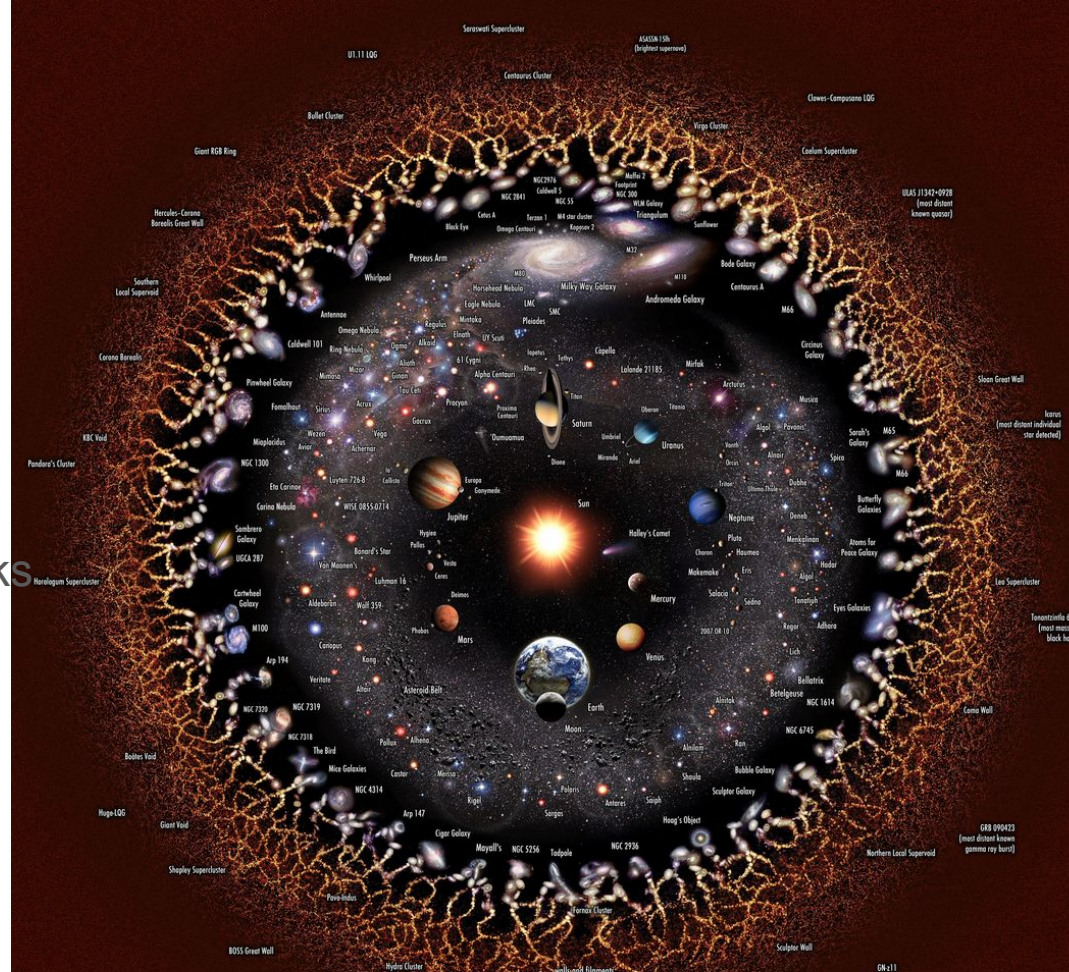
Extradimensional Space

Definition of Dimension

In Astrophysics, the term "universe" describes the **sum of all space and time that we live in.**

Universe, dimension, plane, world, space, or reality are often used in works of fiction interchangeably without a clear distinction or definition for each.

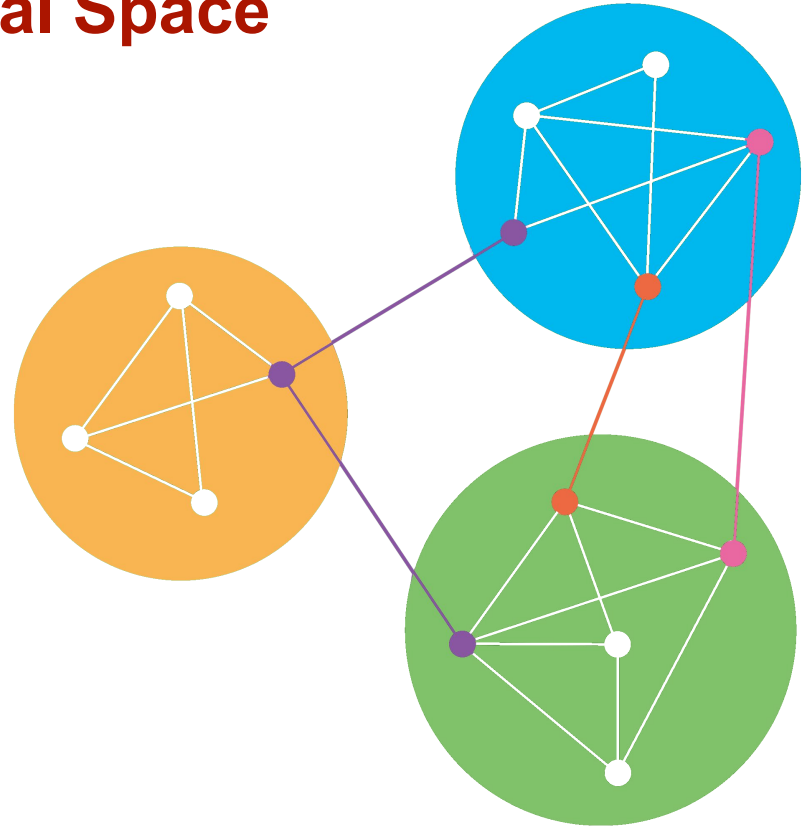
A dimension is the sum of all space and time that are connected physically.



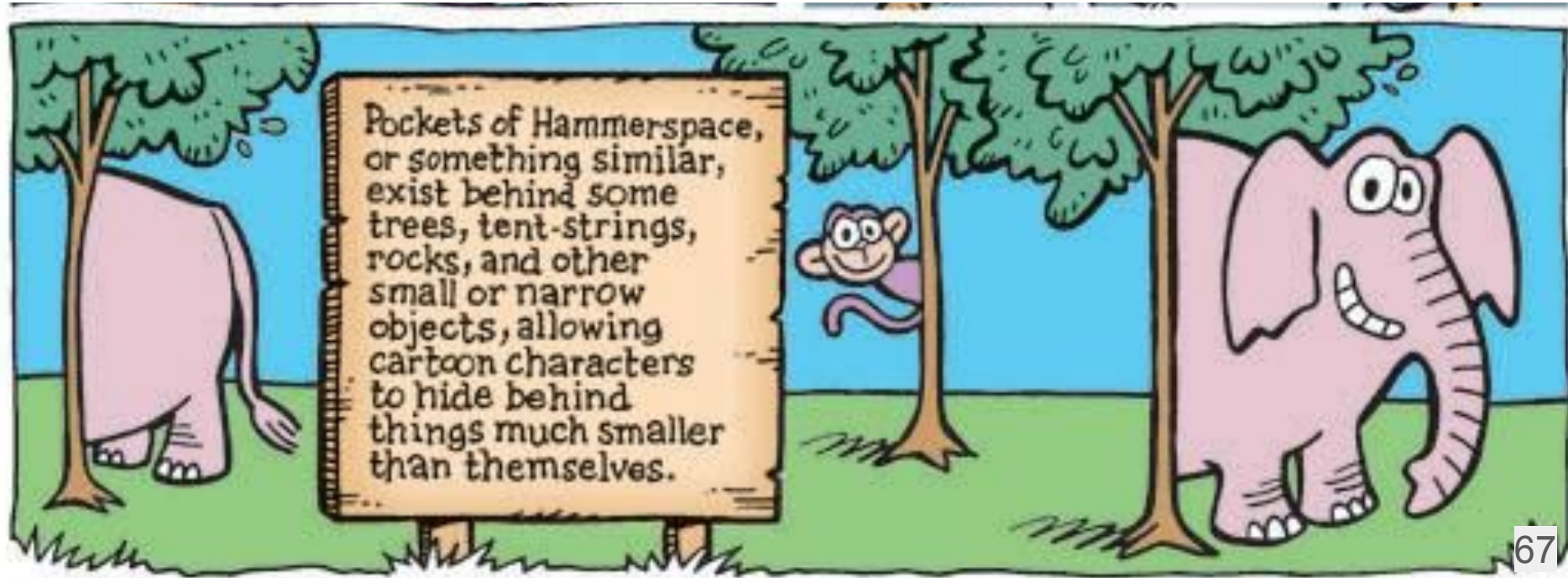
[https://commons.wikimedia.org/wiki/File:Extended_universe_logarithmic_illustration_\(English_annotated\).png](https://commons.wikimedia.org/wiki/File:Extended_universe_logarithmic_illustration_(English_annotated).png)

Definition of Extradimensional Space

Fiction work posits that there are **other distinct and separate sums of space and time that are not connected physically with our own**. This may be described using terms such as alternate, another, **extradimensional**, or parallel to refer to a dimension other than our own.



Hammerspace in Pop Culture



Extradimensional Space Lenses

Lens of Permission

Lens of Relevancy

Lens of Dimension Shift

Lens of Dimensional Sight

The Lens of Permission



Consider what are the restrictions when performing an interaction. Ask yourself these questions

- *Can this interaction technique access entities in extradimensional space?*
- *If not, should this interaction technique be an extradimensional interaction technique?*
- *What are the criteria to access entities in this extradimensional space?*

Extradimensional Space Lenses

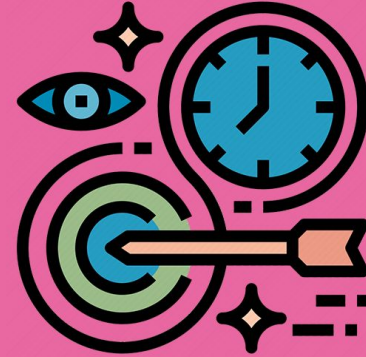
Lens of Permission

Lens of Relevancy

Lens of Dimension Shift

Lens of Dimensional Sight

The Lens of Relevancy



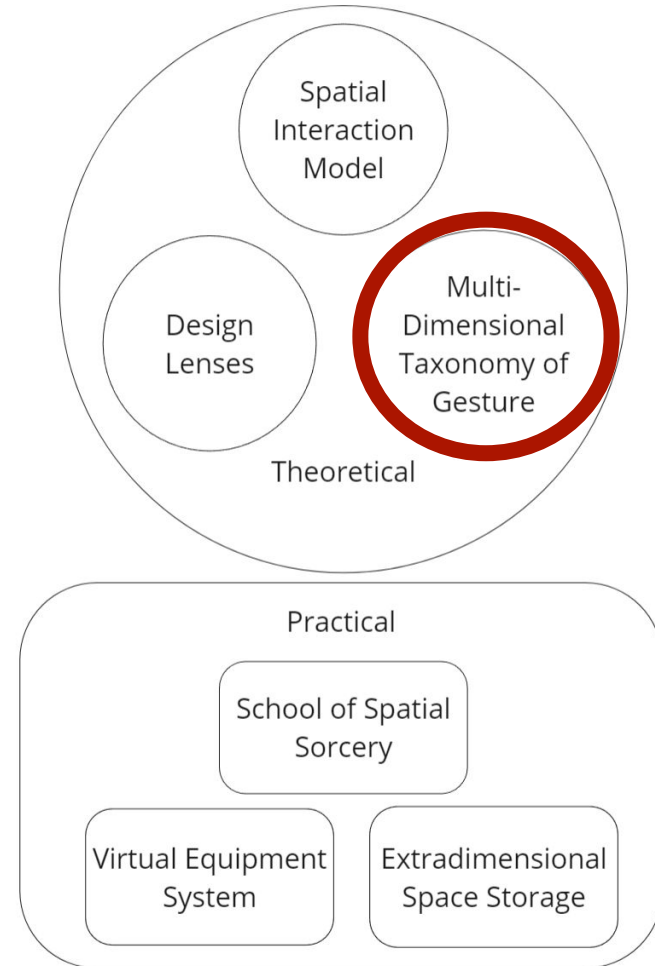
Consider what matters the most during an interaction.
Ask yourself these questions

- *Is this entity relevant to the current interaction?*
- *Should it be stored in another dimension for later use?*

Multi-Dimensional Taxonomy of Gesture

Powen Yao, Tian Yang, and Michael Zyda "Toward a Gesture System Architecture in Extended Reality Based on a Multi-dimensional Taxonomy of Gestures" HCII 2023

Body of Work



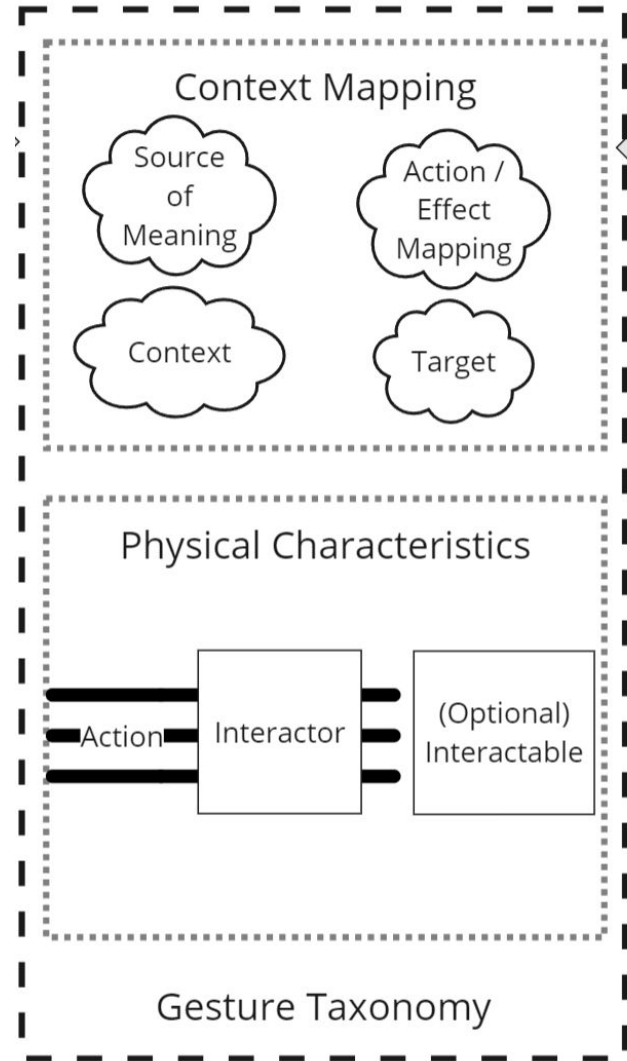
Introduction

Multi-Dimensional Taxonomy of
Gesture for Extended Reality

Based on Spatial Interaction
Model and the Design Lenses

Two classes of dimensions.

Gesture Mapping and
Physical Characteristics.



Prior Works in Taxonomy

Linguistics

Efron 1941, Kendon 1988, McNeill 1992

Human-Computer Interaction

Quek et al. 1994, Pavlovic 1997, Cassell 1998

Multi-Dimensional Gesture Taxonomy

Poggi 2001, Karam 2005, Wobbrock 2009 (Surface Gestures), Ruiz 2011 (Motion Gestures), Vafaei 2013 (VR and mid-air hand gestures)

Key Points

- **Inclusion of emergent qualities in XR**
- **Break down of the “Nature” Dimension**
- **System Architecture based on the Taxonomy**



Physical Characteristics

Physical Characteristics

Physical Characteristics can be viewed as **properties of the interactor and the action performed by the interactor.**

Put simply, Physical Characteristics are about the properties of the interactor and its actions.

Dimensions	Sub-dimensions	Categories	Sub-categories	Description
<i>Position</i>	<i>x</i>	<i>Relevant</i>		Gesture involves the x-axis of position
		<i>Irrelevant</i>		Gesture ignores the x-axis of position
	<i>y</i>	<i>Relevant</i>		Gesture involves the y-axis of position
		<i>Irrelevant</i>		Gesture ignores the y-axis of position
	<i>z</i>	<i>Relevant</i>		Gesture involves the z-axis of position
		<i>Irrelevant</i>		Gesture ignores the z-axis of position
<i>Rotation</i>	<i>x</i>	<i>Relevant</i>		Gesture involves the roll-axis of rotation
		<i>Irrelevant</i>		Gesture ignores the roll-axis of rotation
	<i>y</i>	<i>Relevant</i>		Gesture involves the pitch-axis of rotation
		<i>Irrelevant</i>		Gesture ignores the pitch-axis of rotation
	<i>z</i>	<i>Relevant</i>		Gesture involves the yaw-axis of rotation
		<i>Irrelevant</i>		Gesture ignores the yaw-axis of rotation
<i>Form</i>	<i>Static</i>			No motion/change is in gesture
	<i>Dynamic</i>			Motion/change occurs in gesture
<i>Interactor</i>	<i>User Body</i>	<i>Hand</i>		Arm is fixed, but palm or fingers move
		<i>Arm</i>		Arm moves (hand moves as well)
		<i>Head</i>		Gesture is performed by head movement
		<i>Shoulder</i>		Gesture is performed by shoulder movement
		<i>Foot</i>		Gesture is performed by foot movement
		<i>Eyes</i>		Gesture is performed by pupil movement
		<i>Mouth</i>		Gesture is performed by lip movement
	<i>Other body parts</i>		Gesture is performed by other body part	
	<i>Input Device</i>			Gesture utilizes Input Device as an interactor
<i>In-Environment Object</i>			Gesture utilizes In-Environment Object as an interactor	
<i>Multiplicity</i>	<i>Simple</i>			Gesture utilizes only one interactor
	<i>Multiple</i>			Gesture utilizes multiple interactors
<i>Action Symmetry</i>	<i>Symmetric</i>			Gesture utilizes multiple interactors performing similar motion
	<i>Asymmetric</i>			Gesture utilizes multiple interactors doing performing different motion
<i>Interactor Homogeneity</i>	<i>High</i>			Interactors are very similar in its form and function
	<i>Medium</i>			Interactors are only somewhat similar in its form and function
	<i>Low</i>			Interactors are not similar in its form and function
<i>Complexity</i>	<i>Simple</i>			Gesture involves an atomic gesture
	<i>Compound</i>			Gesture involves multiple atomic gestures
<i>Motion Threshold</i>	<i>None</i>			Gesture does not involve changes in position or rotation
	<i>Position / Angle</i>			Gesture involves changes in position/angle
	<i>Velocity</i>			Gesture involves changes in velocity/angular velocity
	<i>Acceleration</i>			Gesture involves changes in acceleration/angular acceleration
	<i>Jerk</i>			Gesture involves changes in jerk/angular jerk

Physical Characteristics - Interactor

<i>Form</i>	<i>Static</i>		No motion/change is in gesture
	<i>Dynamic</i>		Motion/change occurs in gesture
<i>Interactor</i>	<i>User Body</i>	<i>Hand</i>	Arm is fixed, but palm or fingers move
		<i>Arm</i>	Arm moves (hand moves as well)
		<i>Head</i>	Gesture is performed by head movement
		<i>Shoulder</i>	Gesture is performed by shoulder movement
		<i>Foot</i>	Gesture is performed by foot movement
		<i>Eyes</i>	Gesture is performed by pupil movement
		<i>Mouth</i>	Gesture is performed by lip movement
		<i>Other body parts</i>	Gesture is performed by other body part
	<i>Input Device</i>	Gesture utilizes Input Device as an interactor	
<i>In-Environment Object</i>	Gesture utilizes In-Environment Object as an interactor		
<i>Multiplicity</i>	<i>Simple</i>		Gesture utilizes only one interactor
	<i>Multiple</i>		Gesture utilizes multiple interactors
<i>Action Symmetry</i>	<i>Symmetric</i>		Gesture utilizes multiple interactors performing similar motion
	<i>Asymmetric</i>		Gesture utilizes multiple interactors performing different motion

Physical Characteristics - Additional Emergent Quality

	<i>Input Device</i>	Gesture utilizes Input Device as an interactor
	<i>In-Environment Object</i>	Gesture utilizes In-Environment Object as an interactor
<i>Multiplicity</i>	<i>Simple</i>	Gesture utilizes only one interactor
	<i>Multiple</i>	Gesture utilizes multiple interactors
<i>Action Symmetry</i>	<i>Symmetric</i>	Gesture utilizes multiple interactors performing similar motion
	<i>Asymmetric</i>	Gesture utilizes multiple interactors doing performing different motion
<i>Interactor Homogeniety</i>	<i>High</i>	Interactors are very similar in its form and function
	<i>Medium</i>	Interactors are only somewhat similar in its form and function
	<i>Low</i>	Interactors are not similar in its form and function
<i>Complexity</i>	<i>Simple</i>	Gesture involves an atomic gesture
	<i>Compound</i>	Gesture involves multiple atomic gestures
	<i>None</i>	Gesture does not involve changes in position or rotation

Physical Characteristics - Additional Emergent Quality

	<i>Input Device</i>	Gesture utilizes Input Device as an interactor
	<i>In-Environment Object</i>	Gesture utilizes In-Environment Object as an interactor
Multiplicity	<i>Simple</i>	Gesture utilizes only one interactor
	<i>Multiple</i>	Gesture utilizes multiple interactors
Action Symmetry	<i>Symmetric</i>	Gesture utilizes multiple interactors performing similar motion
	<i>Asymmetric</i>	Gesture utilizes multiple interactors doing performing different motion
Interactor Homogeneity	<i>High</i>	Interactors are very similar in its form and function
	<i>Medium</i>	Interactors are only somewhat similar in its form and function
	<i>Low</i>	Interactors are not similar in its form and function
Complexity	<i>Simple</i>	Gesture involves an atomic gesture
	<i>Compound</i>	Gesture involves multiple atomic gestures
	<i>None</i>	Gesture does not involve changes in position or rotation
	<i>Position / Angle</i>	Gesture involves changes in position/angle

Gesture Mapping

Gesture Mapping

Gesture Mapping can be viewed as **any quality that can be used as context to map an action to a different effect**

Put simply, Gesture Mapping is the context to decipher the physical characteristics within a gesture to determine the effect.

it's the **'how'** and **'what else'** to consider.

Dimensions	Sub-dimensions	Categories	Description
<i>Source of Meaning</i>		<i>Physical</i>	Gesture derives its meaning from laws of physics
		<i>Hyperphysical</i>	Gesture derives its meaning from an alternate laws of physics
		<i>Universal</i>	Gesture derives its meaning from a generally universal set of values
		<i>Cultural</i>	Gesture derives its meaning from shared cultural values
		<i>None</i>	Gesture does not derive its meaning from any particular source; its arbitrary
<i>Target</i>		<i>Has Target</i>	Gesture has at least a target to interact with
		<i>No Target</i>	Gesture has no target to interact with
<i>Action Mapping</i>		<i>Direct</i>	Direct Relationship between Intent and Action
		<i>Indirect</i>	Indirect Relationship to Gesture between Intent and Action
<i>Effect Mapping</i>		<i>Direct</i>	Direct Relationship between Intent and Effect
		<i>Indirect</i>	Indirect Relationship to Gesture between Intent and Effect
<i>Coordinate System</i>		<i>Object / Interactable</i>	Coordinate system to process the gesture is based on an object
		<i>Region</i>	Coordinate system to process the gesture is based on a region
		<i>World</i>	Coordinate system to process the gesture is based on the world
		<i>User</i>	Coordinate system to process the gesture is based on the user
		<i>Interactor</i>	Coordinate system to process the gesture is based on the interactors
		<i>Independent</i>	No particular coordinate system is needed to process the gesture
	<i>Mixed Dependencies</i>	Use combination of coordinate system	
<i>Interaction Context</i>		<i>Object</i>	Gestures require interaction with specific objects
		<i>Region</i>	Gestures require interaction with region-specific context
		<i>World</i>	Gesture require interaction with the world
		<i>User</i>	Gestures require interaction with the user
		<i>Mixed Interaction Context</i>	Gestures require interaction with multiple kinds of above components
	<i>No Context</i>	Gestures do not require interaction within any context	
<i>Temporal</i>		<i>Continuous</i>	Action/task is performed during gesture
		<i>Discrete</i>	Action/task is performed after completion of gesture
<i>Environment</i>	<i>Region</i>	<i>Region-Associated</i>	Effect of gesture is relevant to which region it is performed in
		<i>Region-Independent</i>	Effect of gesture is independent from region
<i>Social Context</i>		<i>Private</i>	Only me
		<i>Personal</i>	My friends
		<i>Social Groups</i>	My teammates
		<i>Public</i>	Anyone else
<i>User</i>	<i>Proximity</i>	<i>Personal Space</i>	Gesture is performed in user's Personal Space
		<i>Peripersonal Space</i>	Gesture is performed in user's Peripersonal Space
		<i>Extrapersonal Space</i>	Gesture is performed in user's Extrapersonal Space
		<i>Not Relevant</i>	Gesture is performed in any space
	<i>Posture</i>	<i>Standing</i>	Gesture is based on User in the standing posture
		<i>Sitting</i>	Gesture is based on User in the sitting posture
		<i>Lying Down</i>	Gesture is based on User in the lying posture
		<i>Other postures</i>	Gesture is based on User in other postures not listed above
	<i>Mobility</i>	<i>Stationary</i>	Gesture is based on if the User is stationary
<i>Mobile</i>		Gesture is based on if the User is travelling	
<i>Mobile/Transportation Method</i>		Gesture is based on the User's transportation method, e.g. bicycle, bus, car	
<i>Audience</i>		<i>Human</i>	Gesture has human as the audience
		<i>Rigid System</i>	Gesture has a rule-based program as the audience
		<i>Intelligent Agent</i>	Gesture has an intelligent agent similar to human

Gesture Taxonomy

Breaking down the “Nature Dimension”

“Nature” Dimension in Previous Taxonomies

The definition of Nature is **“the mapping from gestures to their meaning”**

Nature

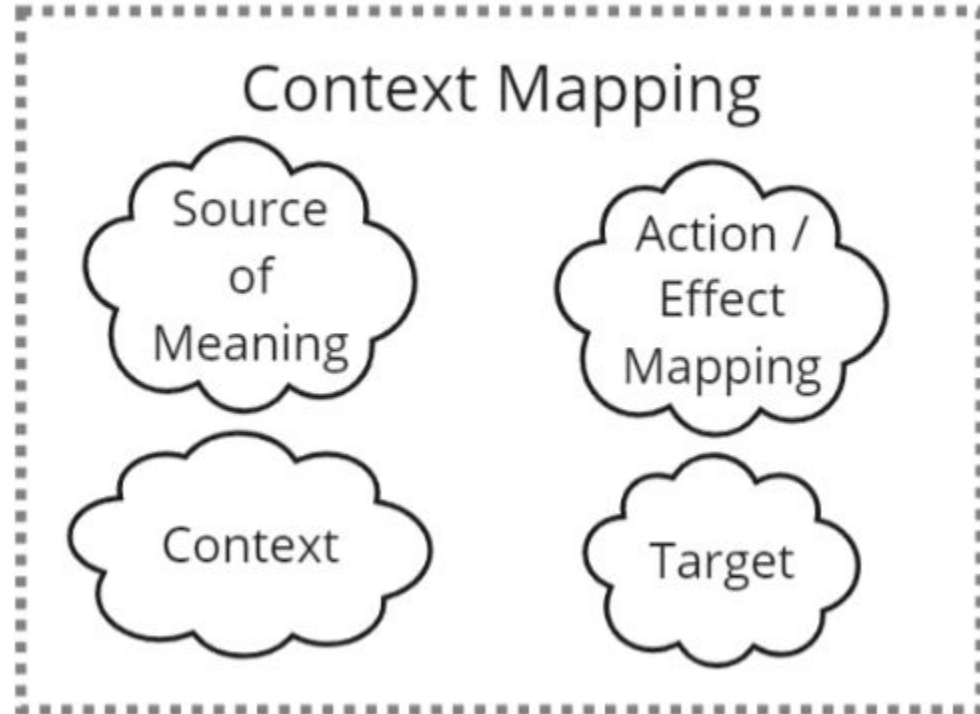
- Physical: Gesture acts physically on objects.
- Metaphorical: Gesture indicates a metaphor.
- Symbolic: Gesture visually depicts a symbol.
- Abstract: Gesture-referent mapping is arbitrary.

Additional Dimensions

We propose the addition of these dimensions to replace Nature:

- **Source of Meaning**
- **Target**
- **Action Mapping**
- **Effect Mapping**

These are included in the Spatial Interaction Model.



Gesture Mapping

Dimensions	Sub-dimensions	Categories	Description
<i>Source of Meaning</i>	<i>Physical</i>		Gesture derives its meaning from laws of physics
	<i>Hyperphysical</i>		Gesture derives its meaning from an alternate laws of physics
	<i>Universal</i>		Gesture derives its meaning from a generally universal set of values
	<i>Cultural</i>		Gesture derives its meaning from shared cultural values
	<i>None</i>		Gesture does not derives its meaning from any particular source; its arbitrary
<i>Target</i>	<i>Has Target</i>		Gesture has at least a target to interact with
	<i>No Target</i>		Gesture has no target to interact with
<i>Action Mapping</i>	<i>Direct</i>		Direct Relationship between Intent and Action
	<i>Indirect</i>		Indirect Relationship to Gesture between Intent and Action
<i>Effect Mapping</i>	<i>Direct</i>		Direct Relationship between Intent and Effect
	<i>Indirect</i>		Indirect Relationship to Gesture between Intent and Effect
<i>Coordinate System</i>	<i>Object/Hand</i>		Coordinate system to process the gesture is based on the object/hand
	<i>Region</i>		Coordinate system to process the gesture is based on a region
	<i>World</i>		Coordinate system to process the gesture is based on the world
	<i>User</i>		Coordinate system to process the gesture is based on the user
	<i>Intent</i>		Coordinate system to process the gesture is based on the intent

Source of Meaning Dimension

Nature is transformed to Source of Meaning dimension

Dimensions	Sub-dimensions	Categories	Description
<i>Source of Meaning</i>	<i>Physical</i>		Gesture derives its meaning from laws of physics
	<i>Hyperphysical</i>		Gesture derives its meaning from an alternate laws of physics
	<i>Universal</i>		Gesture derives its meaning from a generally universal set of values
	<i>Cultural</i>		Gesture derives its meaning from shared cultural values
	<i>None</i>		Gesture does not derives its meaning from any particular source; its arbitrary
<i>Target</i>	<i>Has target</i>		Gesture has at least a target to interact with
	<i>No Target</i>		Gesture has no target to interact with
<i>Action Mapping</i>	<i>Direct</i>		Direct Relationship between Intent and Action
	<i>Indirect</i>		Indirect Relationship to Gesture between Intent and Action
<i>Effect Mapping</i>	<i>Direct</i>		Direct Relationship between Intent and Effect
	<i>Indirect</i>		Indirect Relationship to Gesture between Intent and Effect
	<i>Object / Interactable</i>		Coordinate system to process the gesture is based on an object

Target Dimension

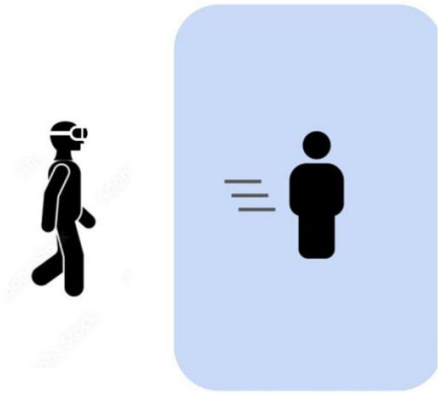
In the previous taxonomies' Nature dimension, physical is the only category with a target.

However, consider a thumbs up at a User Interface to show approval.

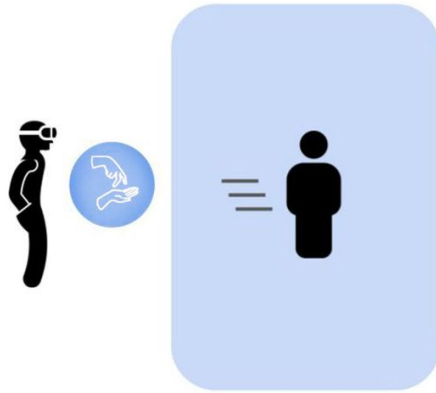


Action Mapping and Effect Mapping Dimension

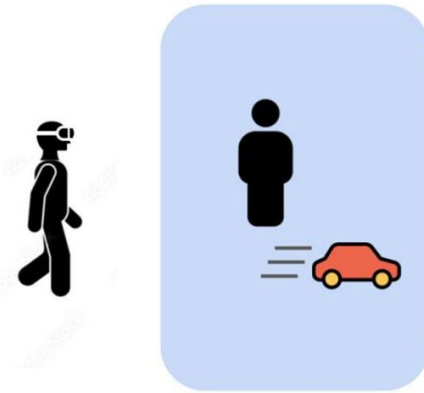
Dimensions	Sub-dimensions	Categories	Description
<i>Source of Meaning</i>	<i>Physical</i>		Gesture derives its meaning from laws of physics
	<i>Hyperphysical</i>		Gesture derives its meaning from an alternate laws of physics
	<i>Universal</i>		Gesture derives its meaning from a generally universal set of values
	<i>Cultural</i>		Gesture derives its meaning from shared cultural values
	<i>None</i>		Gesture does not derives its meaning from any particular source; its arbitrary
<i>Target</i>	<i>Has Target</i>		Gesture has at least a target to interact with
	<i>No Target</i>		Gesture has no target to interact with
<i>Action Mapping</i>	<i>Direct</i>		Direct Relationship between Intent and Action
	<i>Indirect</i>		Indirect Relationship to Gesture between Intent and Action
<i>Effect Mapping</i>	<i>Direct</i>		Direct Relationship between Intent and Effect
	<i>Indirect</i>		Indirect Relationship to Gesture between Intent and Effect
<i>Coordinate System</i>	<i>Object</i>		Coordinate system to process the gesture is based on the object
	<i>Region</i>		Coordinate system to process the gesture is based on a region
	<i>World</i>		Coordinate system to process the gesture is based on the world
	<i>User</i>		Coordinate system to process the gesture is based on the user
	<i>Intent</i>		Coordinate system to process the gesture is based on the intent



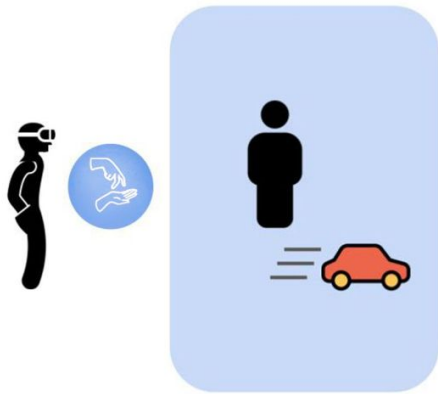
(1)



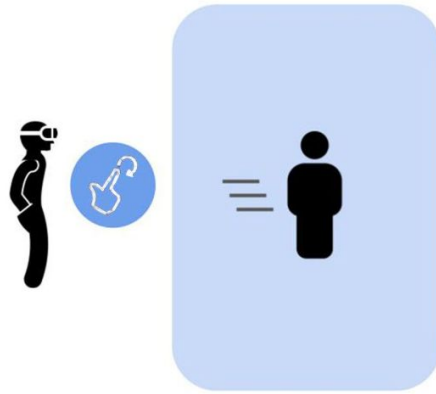
(2)



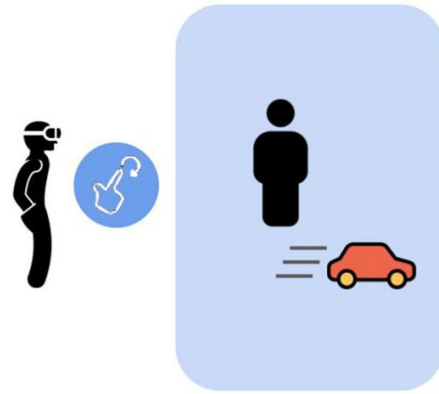
(3)



(4)



(5)



(6)

Case 1

User avatar moves when the user's legs move.

Nature: Physical

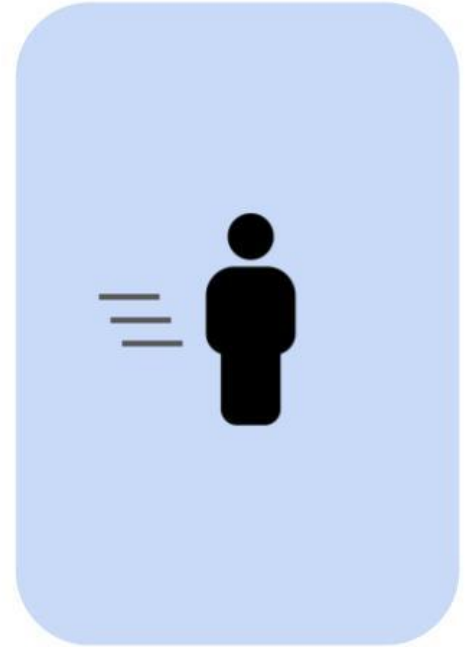
vs.

Source of Meaning: Physical

Action Mapping: Direct

Effect Mapping: Direct

Target: None (self)



Case 2

User avatar moves when the user's fingers mimic legs and move.

Nature: Metaphor

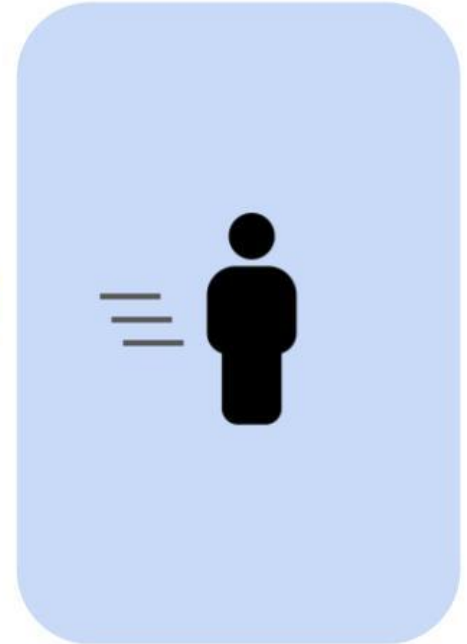
vs.

Source of Meaning: Physical

Action Mapping: Indirect

Effect Mapping: Direct

Target: None (self)



Case 3

A car moves when the user's legs move

Nature: Arbitrary

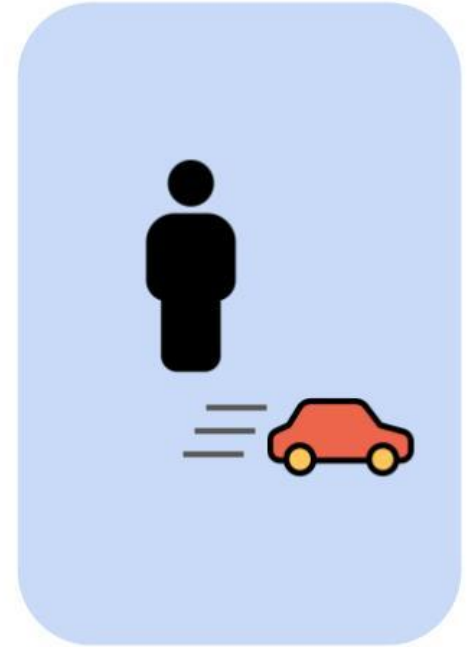
vs.

Source of Meaning: Physical

Action Mapping: Direct

Effect Mapping: Indirect

Target: Car



Case 4

A car moves when the user's fingers mimic legs and move

Nature: Arbitrary

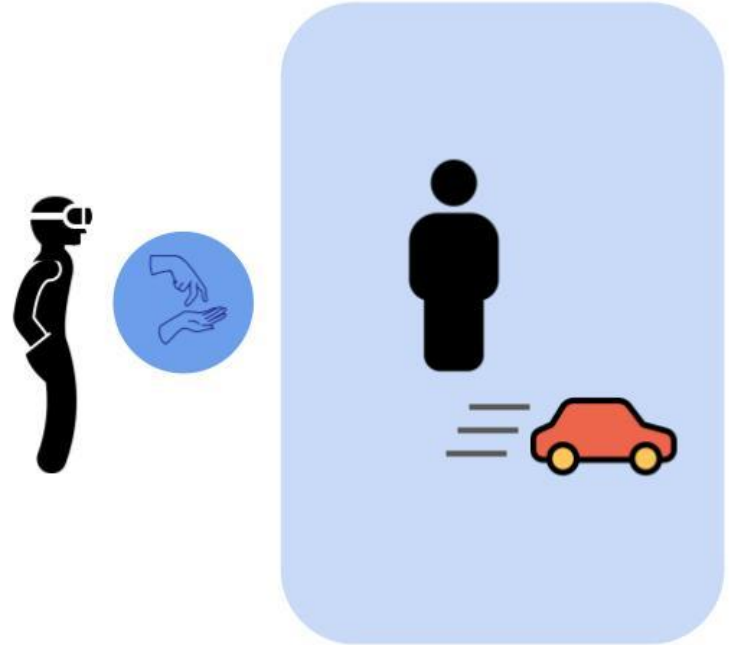
vs.

Source of Meaning: Physical

Action Mapping: Indirect

Effect Mapping: Indirect

Target: Car



Case 5

User avatar moves when the user draws a symbol (wheel) to represent run

Nature: Metaphor

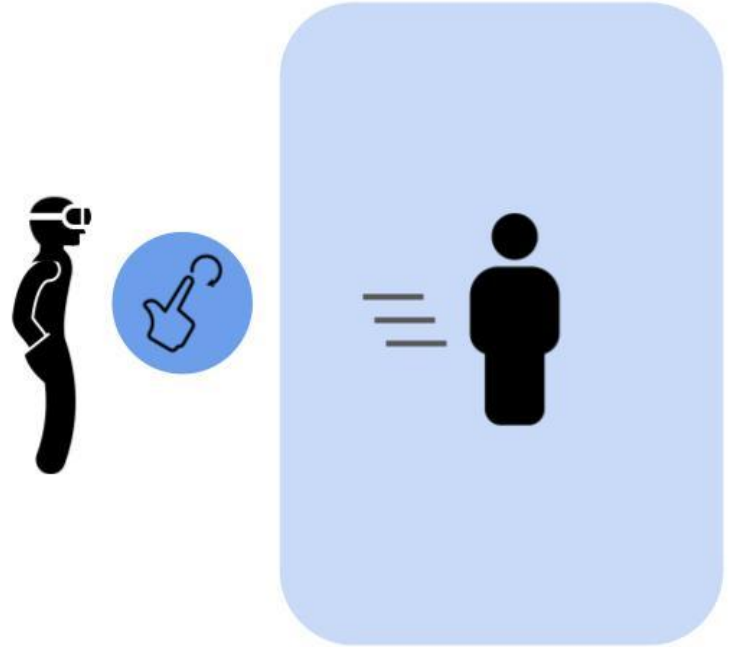
vs.

Source of Meaning: Cultural

Action Mapping: Indirect

Effect Mapping: Direct

Target: None (Self)



Case 6

A car moves when the user draws a symbol (wheel) to represent run.

Nature: Arbitrary.

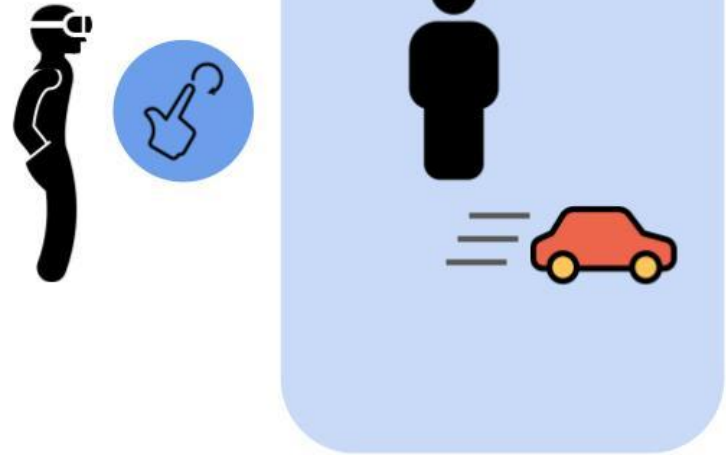
vs.

Source of Meaning: Cultural

Action Mapping: Indirect

Effect Mapping: Indirect

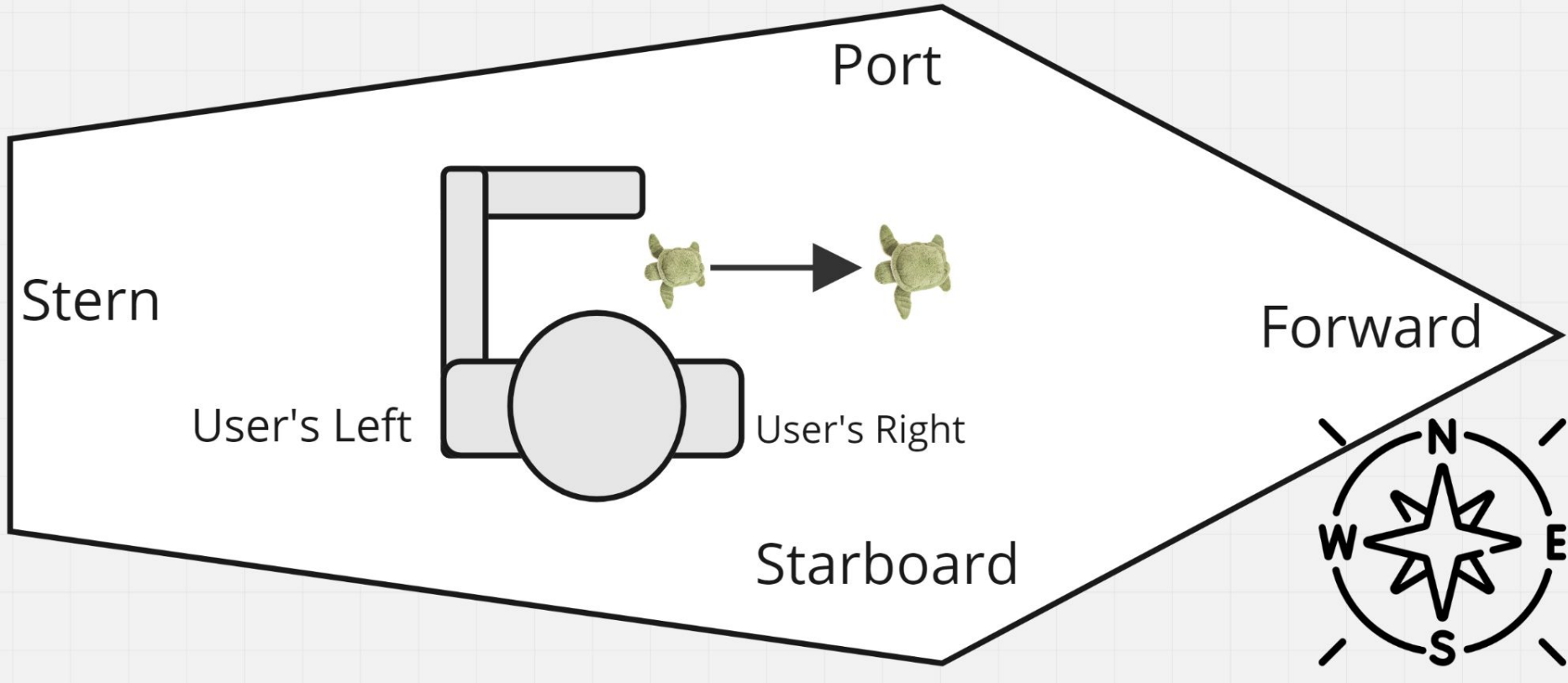
Target: Car

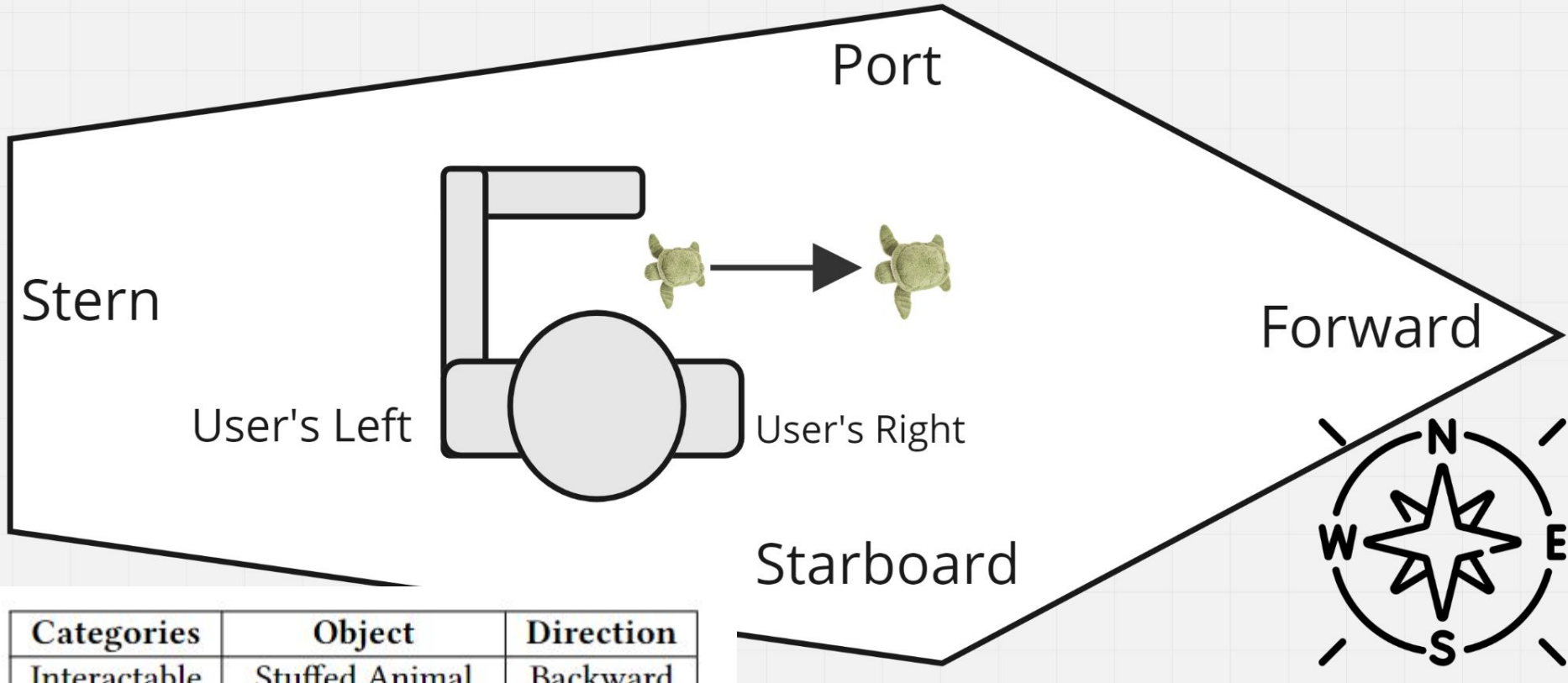


Gesture Mapping Continued

Gesture Mapping

<i>Effect Mapping</i>	<i>Direct</i>	Direct Relationship between Intent and Effect
	<i>Indirect</i>	Indirect Relationship to Gesture between Intent and Effect
<i>Coordinate System</i>	<i>Object / Interactable</i>	Coordinate system to process the gesture is based on an object
	<i>Region</i>	Coordinate system to process the gesture is based on a region
	<i>World</i>	Coordinate system to process the gesture is based on the world
	<i>User</i>	Coordinate system to process the gesture is based on the user
	<i>Interactor</i>	Coordinate system to process the gesture is based on the interactors
	<i>Independent</i>	No particular coordinate system is needed to process the gesture
	<i>Mixed Dependencies</i>	Use combination of coordinate system
<i>Interaction Context</i>	<i>Object</i>	Gestures require interaction with specific objects
	<i>Region</i>	Gestures require interaction with region-specific context
	<i>World</i>	Gestures require interaction with the world
	<i>User</i>	Gestures require interaction with the user
	<i>Mixed Interaction Context</i>	Gestures require interaction with multiple kinds of above components





Categories	Object	Direction
Interactable	Stuffed Animal	Backward
Interactor	User's Left Hand	Forward
User	User	Right
Region	Ship	Forward
World	World	East

Gesture Mapping - Interaction Context

		<i>Independent</i>	No particular coordinate system is needed to process the gesture
		<i>Mixed Dependencies</i>	Use combination of coordinate systems
Interaction Context		<i>Object</i>	Gestures require interaction with specific objects
		<i>Region</i>	Gestures require interaction with region-specific context
		<i>World</i>	Gestures require interaction with the world
		<i>User</i>	Gestures require interaction with the user
		<i>Mixed Interaction Context</i>	Gestures require interaction with multiple kinds of above components
		<i>No Context</i>	Gestures do not require interaction within any context
Temporal		<i>Continuous</i>	Action/task is performed during gesture
		<i>Discrete</i>	Action/task is performed after completion of gesture
Environment	Region	<i>Region-Associated</i>	Effect of gesture is relevant to which region it is performed in
		<i>Region-Independent</i>	Effect of gesture is independent from region
Social Context		<i>Private</i>	Only me
		<i>Personal</i>	My friends
		<i>Social Groups</i>	My teammates
		<i>Public</i>	Anyone else

Gesture Mapping - Environmental, Social Contexts

<i>Interaction Context</i>		<i>Object</i>	Gestures require interaction with specific objects
		<i>Region</i>	Gestures require interaction with region-specific context
		<i>World</i>	Gestures require interaction with the world
		<i>User</i>	Gestures require interaction with the user
		<i>Mixed Interaction Context</i>	Gestures require interaction with multiple kinds of above components
		<i>No Context</i>	Gestures do not require interaction within any context
<i>Temporal</i>		<i>Continuous</i>	Action/task is performed during gesture
		<i>Discrete</i>	Action/task is performed after completion of gesture
<i>Environment</i>	<i>Region</i>	<i>Region-Associated</i>	Effect of gesture is relevant to which region it is performed in
		<i>Region-Independent</i>	Effect of gesture is independent from region
<i>Social Context</i>		<i>Private</i>	Only me
		<i>Personal</i>	My friends
		<i>Social Groups</i>	My teammates
		<i>Public</i>	Anyone else
		<i>Personal Space</i>	Gesture is performed in user's Personal space

“OK” Sign

OK (America)

Money (Japan)

Mudra (seal of consciousness in yoga)

Sun (North American Plains Indian Sign Language)

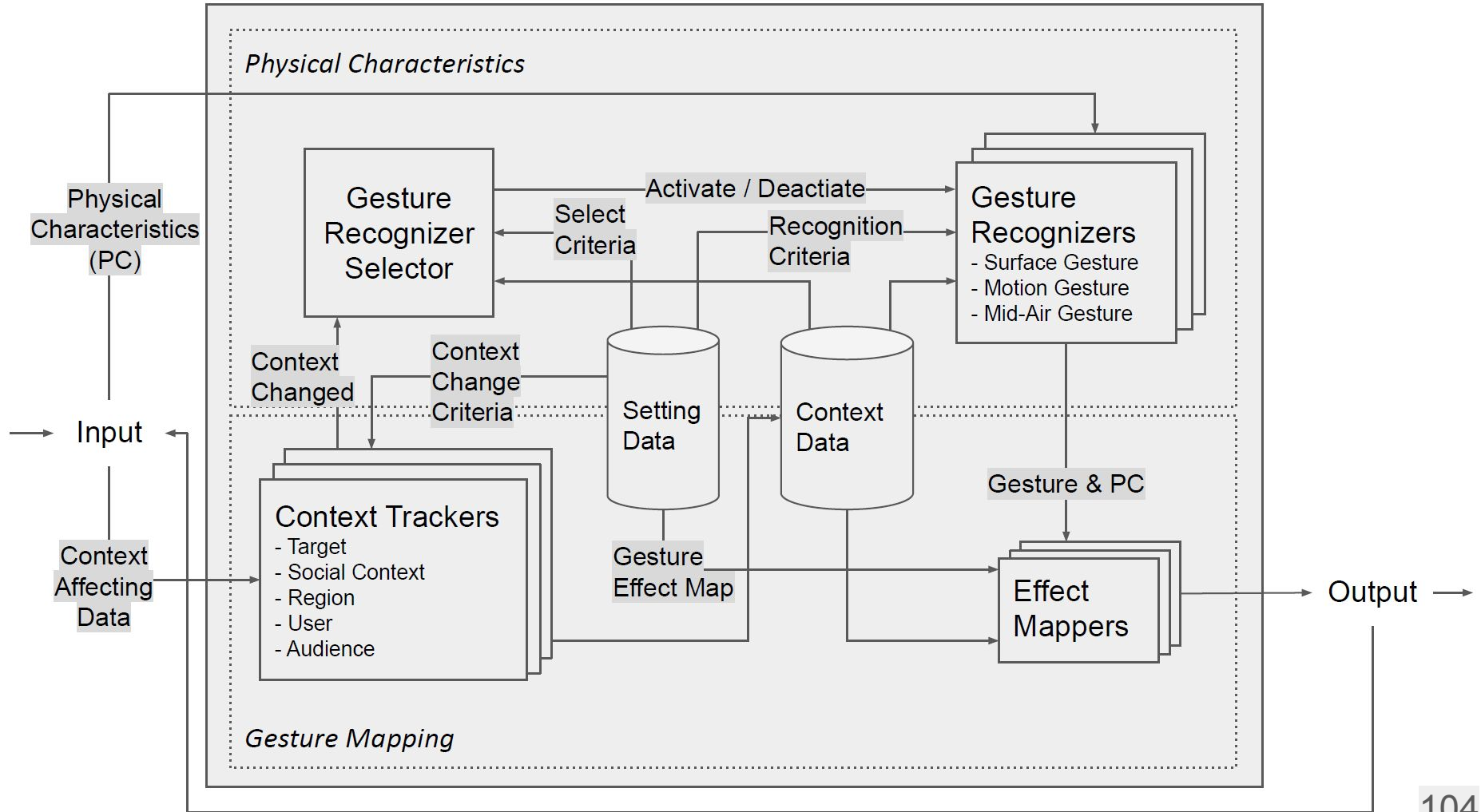
And many more..

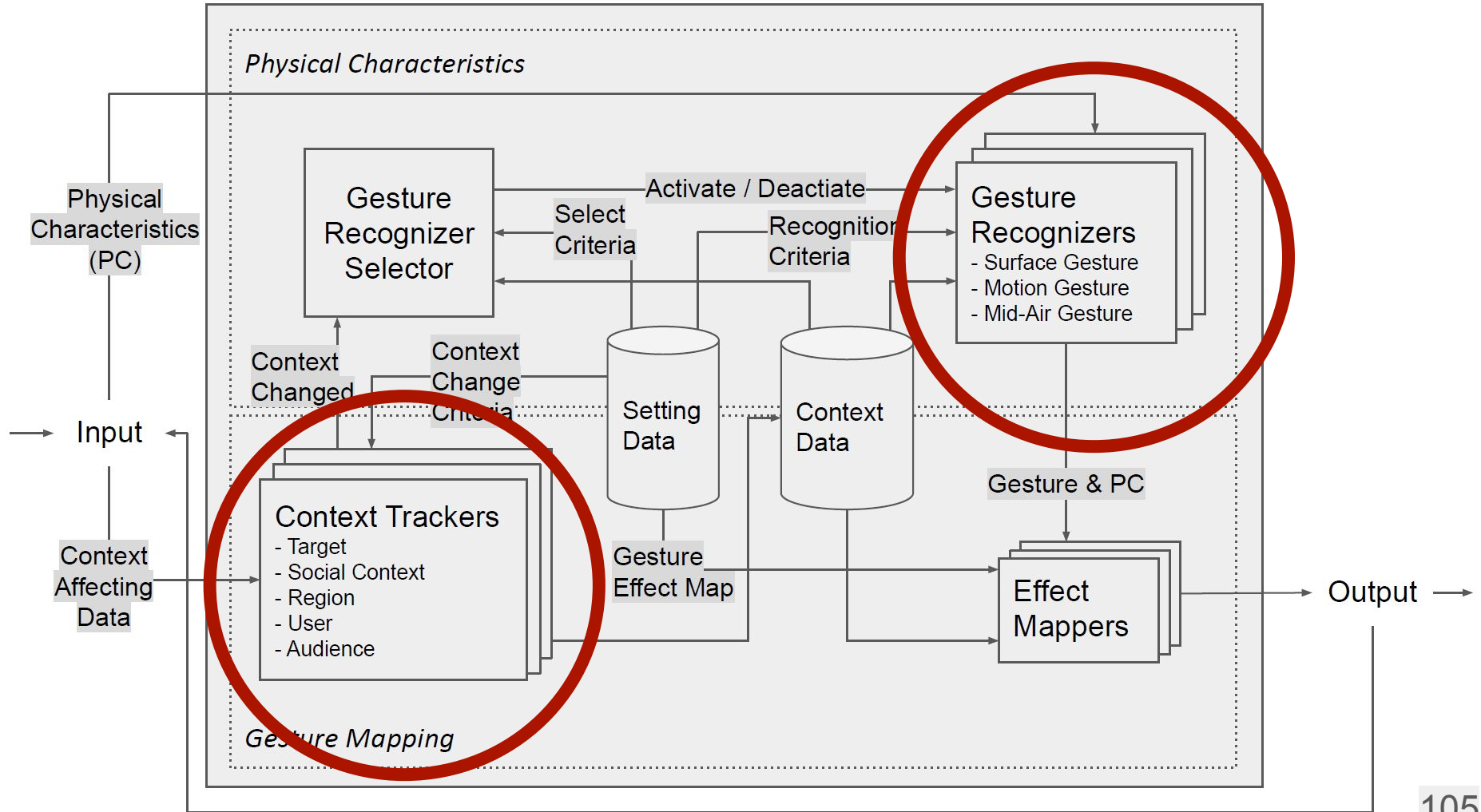


Gesture Mapping - User Contexts

<i>Social Context</i>		<i>Personal</i>	My friends
		<i>Social Groups</i>	My teammates
		<i>Public</i>	Anyone else
<i>User</i>	<i>Proximity</i>	<i>Personal Space</i>	Gesture is performed in user's Personal Space
		<i>Peripersonal Space</i>	Gesture is performed in user's Peripersonal Space
		<i>Extrapersonal Space</i>	Gesture is performed in user's Extrapersonal Space
		<i>Not Relevant</i>	Gesture is performed in any space
	<i>Posture</i>	<i>Standing</i>	Gesture is based on User in the standing posture
		<i>Sitting</i>	Gesture is based on User in the sitting posture
		<i>Lying Down</i>	Gesture is based on User in the lying posture
		<i>Other postures</i>	Gesture is based on User in other postures not listed above
	<i>Mobility</i>	<i>Stationary</i>	Gesture is based on if the User is stationary
		<i>Mobile</i>	Gesture is based on if the User is travelling
<i>Mobile/Transportation Method</i>		Gesture is based on the User's transportation method, e.g. bicycle, bus, car	
<i>Audience</i>		<i>Human</i>	Gesture has human as the audience
		<i>Rigid System</i>	Gesture has a rule-based program as the audience
		<i>Intelligent Agent</i>	Gesture has an intelligent agent similar to human

Gesture System Architecture

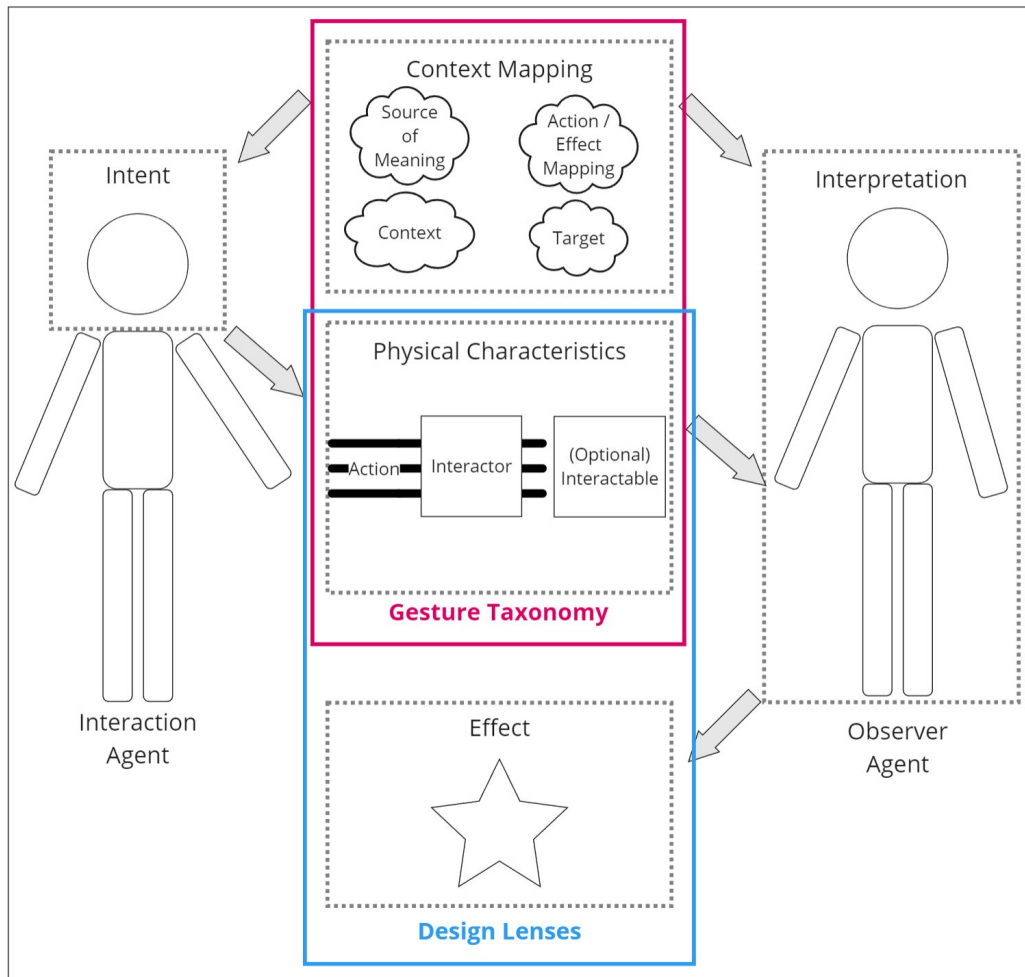




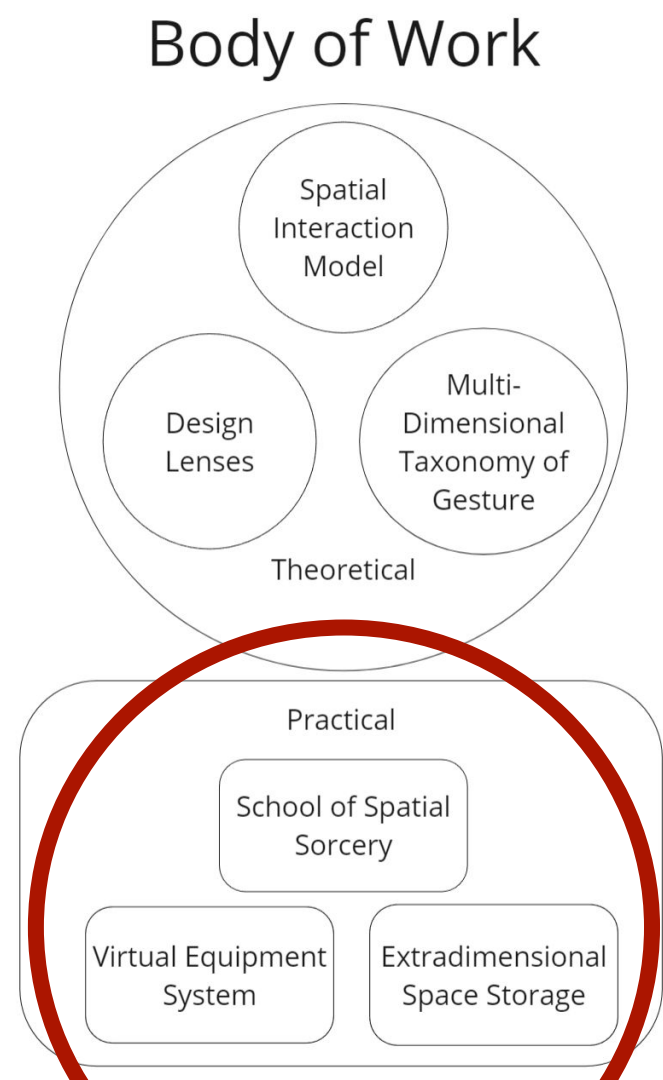
Putting It All Together

- **Spatial Interaction Model**
- **Design Lenses**
- **Gesture Taxonomy**

Spatial Interaction Model



Practical Components



School of Spatial Sorcery

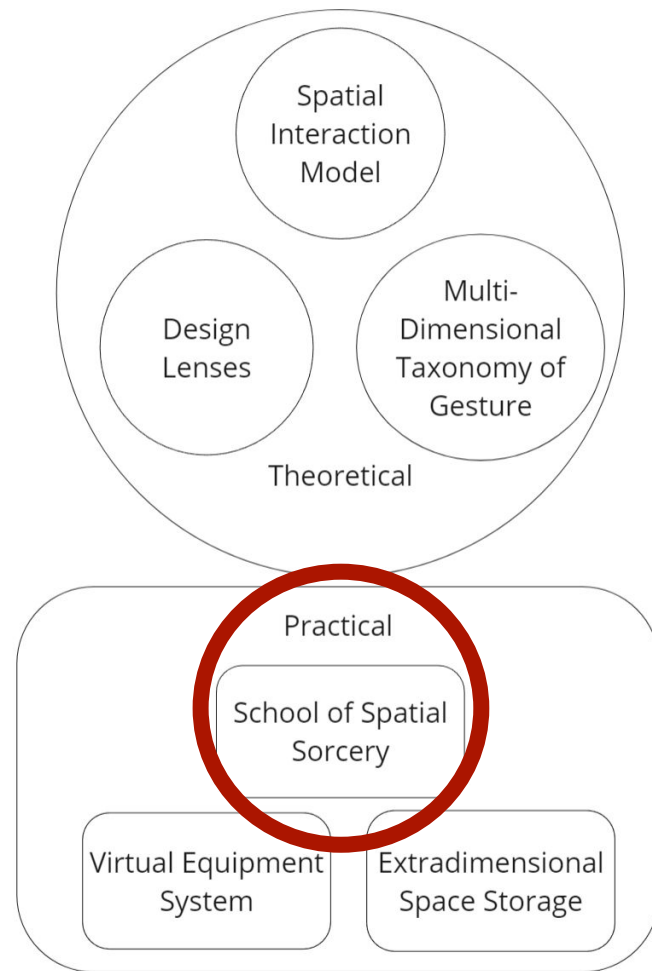
Smart Home / Simulated Environment (Precursor to School of Spatial Sorcery)

Zezen Xu, **Power Yao**, and Vangelis Lympouridis. "Virtual Control Interface: A System for Exploring AR and IoT Multimodal Interactions Within a Simulated Virtual Environment". HCII 2021

Power Yao et al. "Toward Using Multi-Modal Machine Learning for User Behavior Prediction in Simulated Smart Home for Extended Reality". IEEE VR 2022

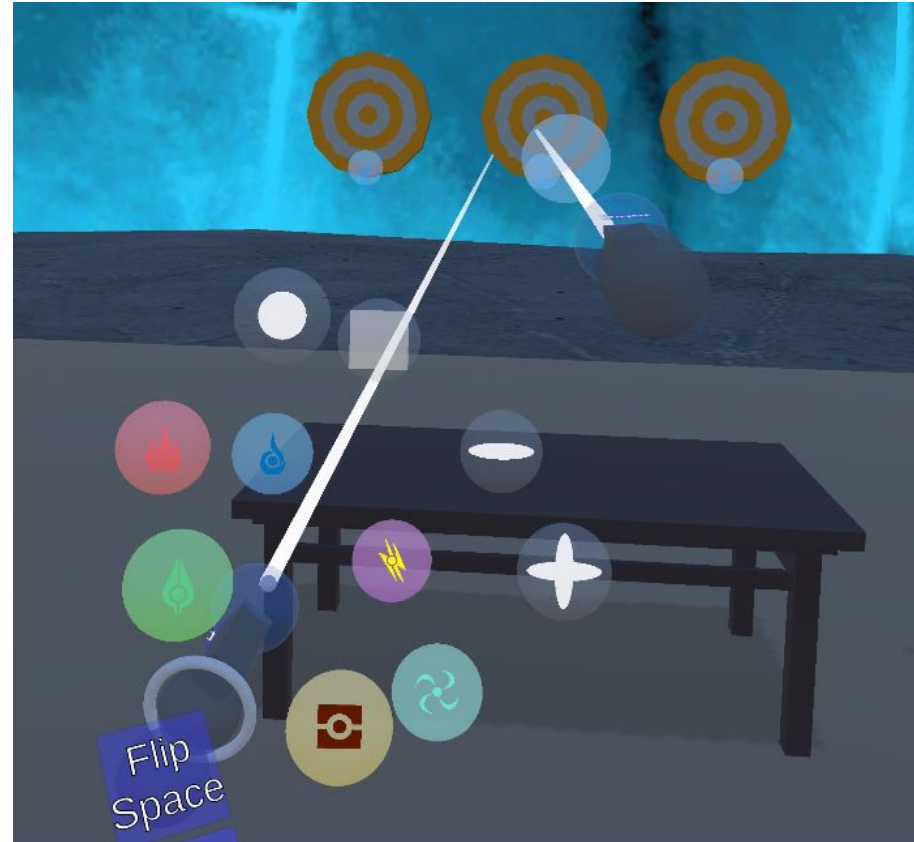
Power Yao et al. "Using Multi-modal Machine Learning for User Behavior Prediction in Simulated Smart Home for Extended Reality". VAMR 2022 / HCII 2022

Body of Work



Introduction

The School of Spatial Sorcery is an exploration of spatial interactions using the creation of spells as a **substitute** for day-to-day interaction tasks.



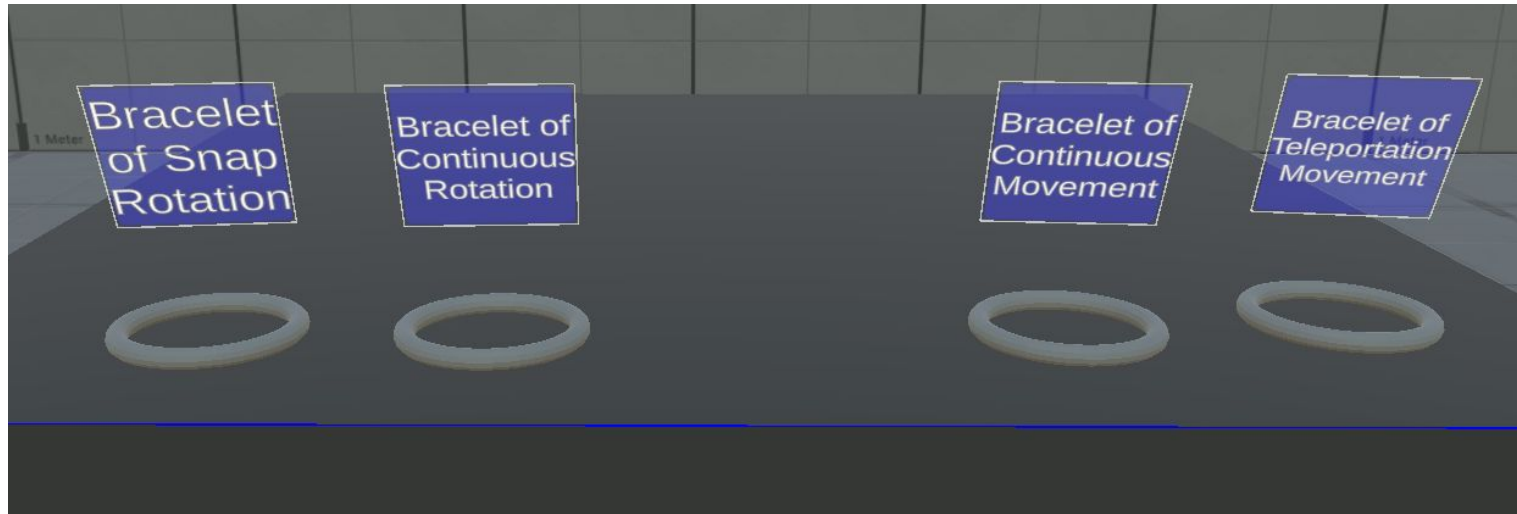
Arcane Symbols of Elements and of Shapes



Equipment as Metaphor for Having Abilities

Handheld Equipment

Wearable Equipment

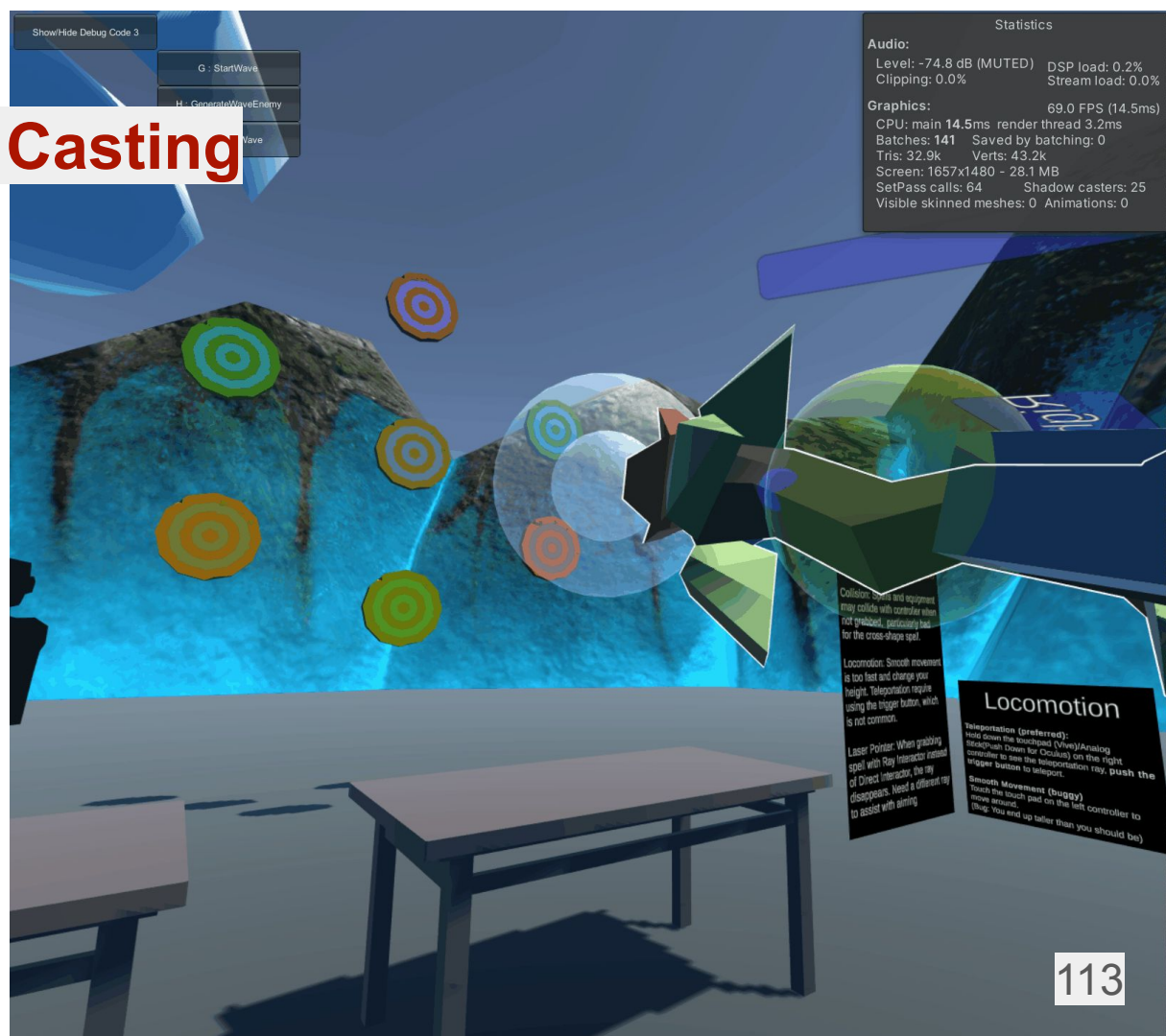


Handheld Equipment

Wand of Rotational Casting

Cast different elemental spells as you change the rotation of the Roll Axis.

Comes in Positional variety and the Angular Jerk variety.



Spellbooks

Spellbooks are storage for arcane symbols.

Spellbooks can also be stored in storages.

Spellbook (Simple)

Upon picking up the spellbook with the Grip Button, you will see a collection of spell symbols floating on top of the spellbook.

Simply grab one of the spell symbols with the other controller using the grip button, then release the grip button to cast the spell.

Spellbook (Combination)

Upon picking up the spellbook, you will see a collection of element symbols as well as a collection of type symbols floating on top of the spellbook.

To cast a spell, you must select an element and a shape before a spell will be created.



Wearable Equipment

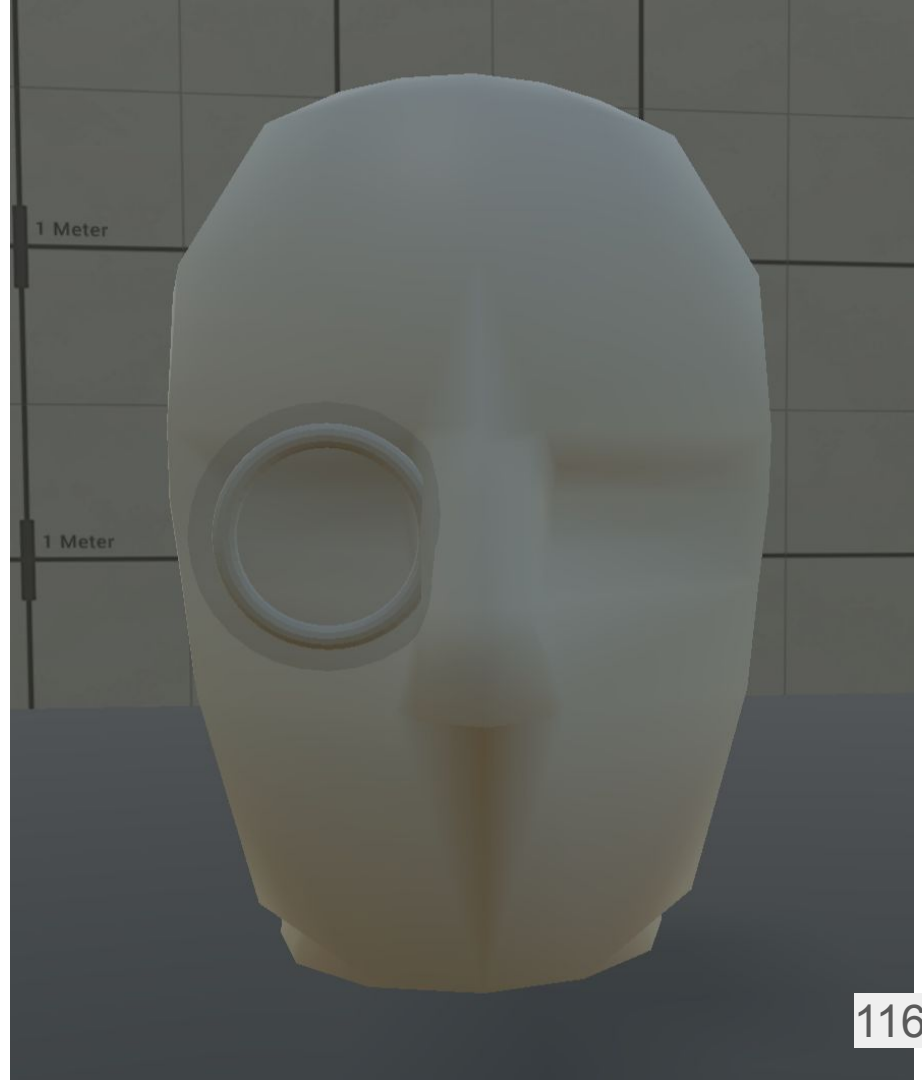
Extradimensional Sight

Extradimensional Sight allows the user to see information hidden away in another dimension.

This prevents the user from being overwhelmed by information.

User can access information based on their needs.

Managed through **Monocles**

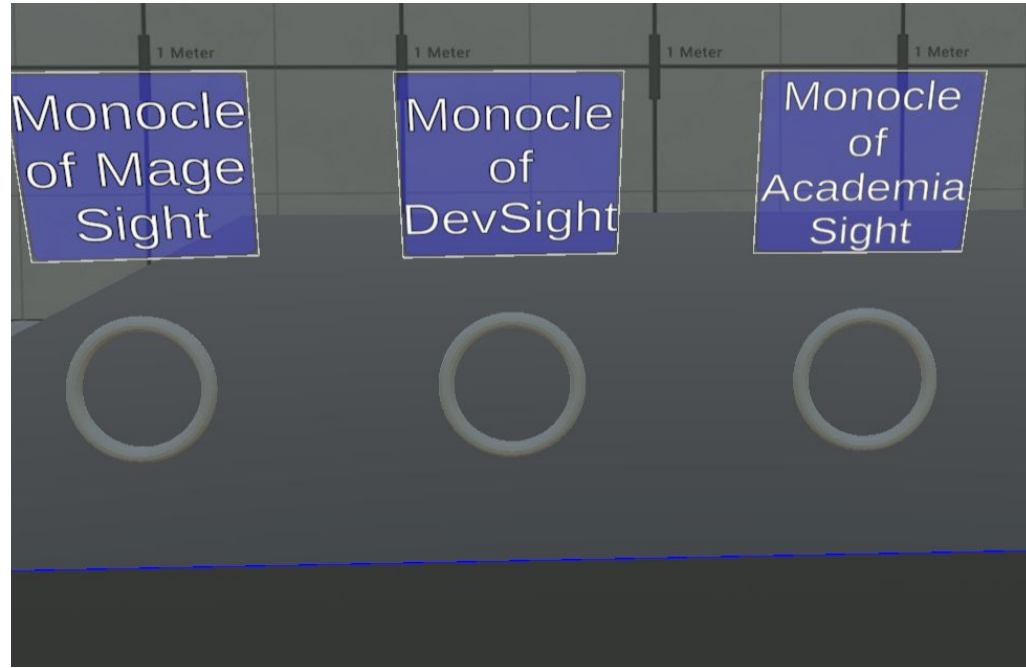


Monocle of Extradimensional Sight

Mage Sight: See ghosts, secret doors, or enemy elemental weaknesses.

Developer Sight: See and interact with user interfaces for debugging, such as a command console or level reset button.

Scholar Sight: See info about an item or a technique, such as relevant works, citations, or a summary of significance to academia.

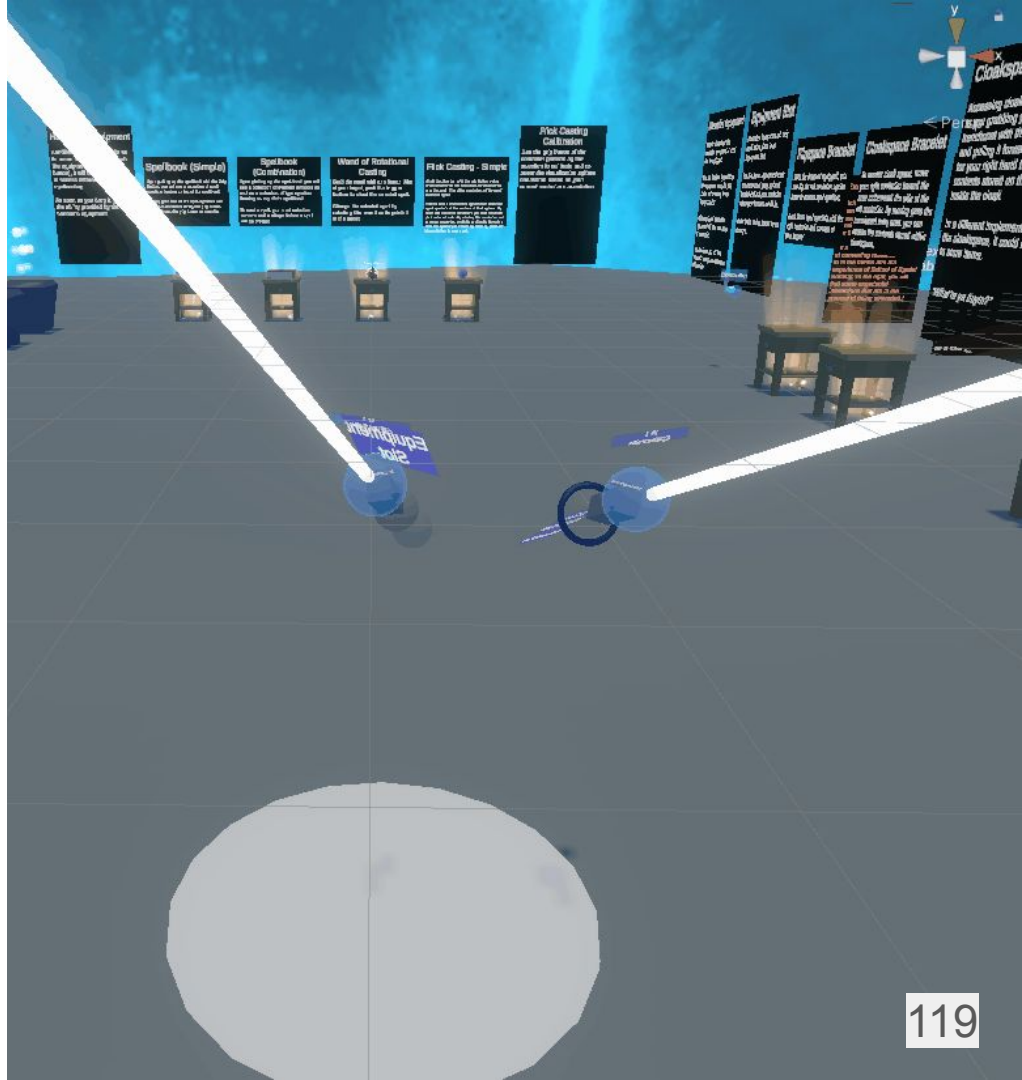


Simple Extradimensional Storage

Type	Implementation	Description
Flipspace	Flipspace	Access by flipping an interactable upside-down
Reachspace	Sleevespace, Cloakspace	Access by passing the interactor through an Entry
Slidedoorspace	Lapel Space, Trunk Space	Access by first grabbing a handle to open the space, then by reaching in
Drawerspace	Chest Space	Access by first grabbing a handle to pull out the space, the spatial location of the content changes as the handle position changes

Flipspace

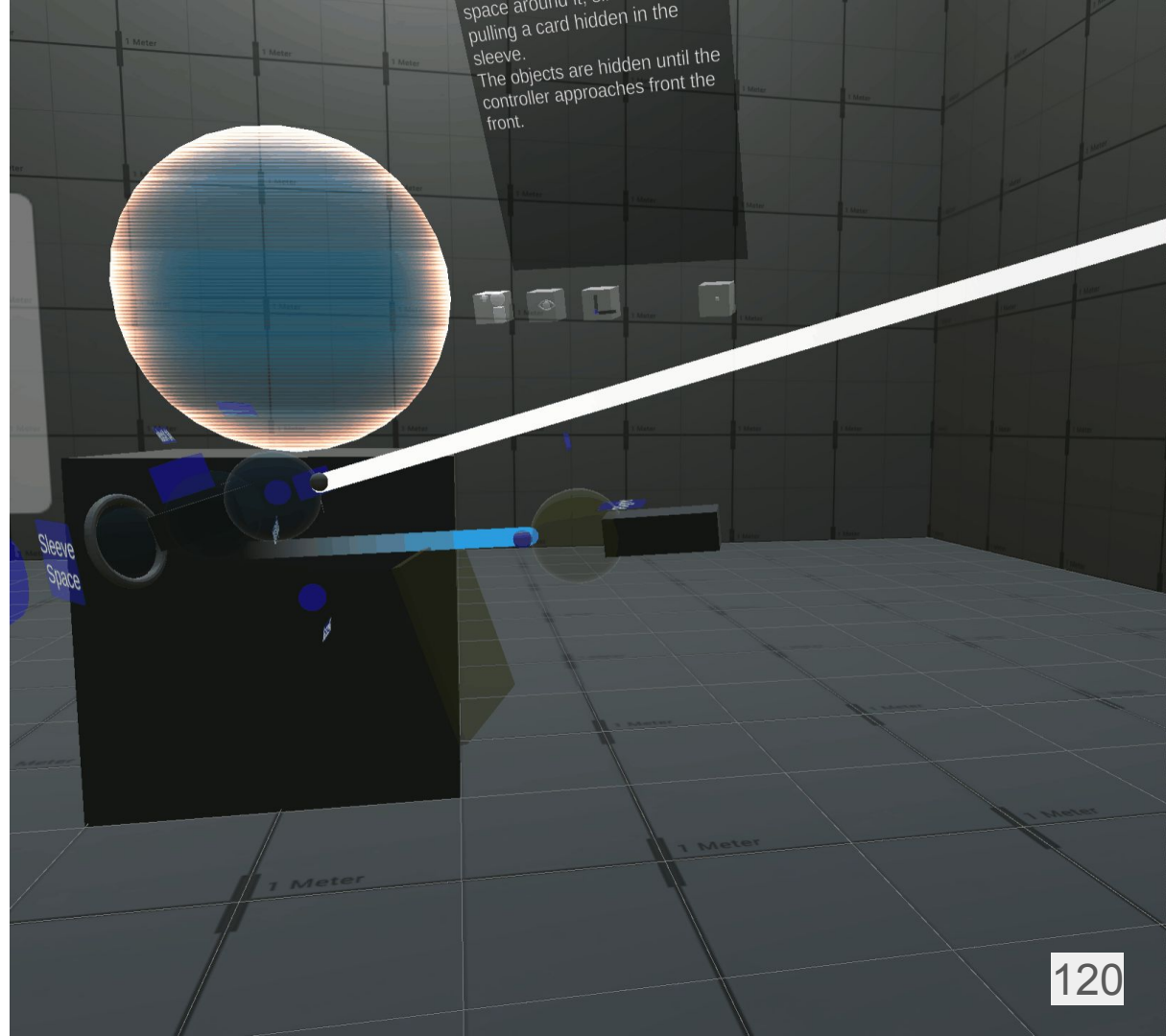
Access arcane symbols by flipping the controller upside down.



Sleevespace

Reachspace at user's wrist

Access by simply **reaching** past the entry



Cloakspace

Reachspace at below user's forearm

Access by simply **reaching** past the entry



Simple Extradimensional Storage

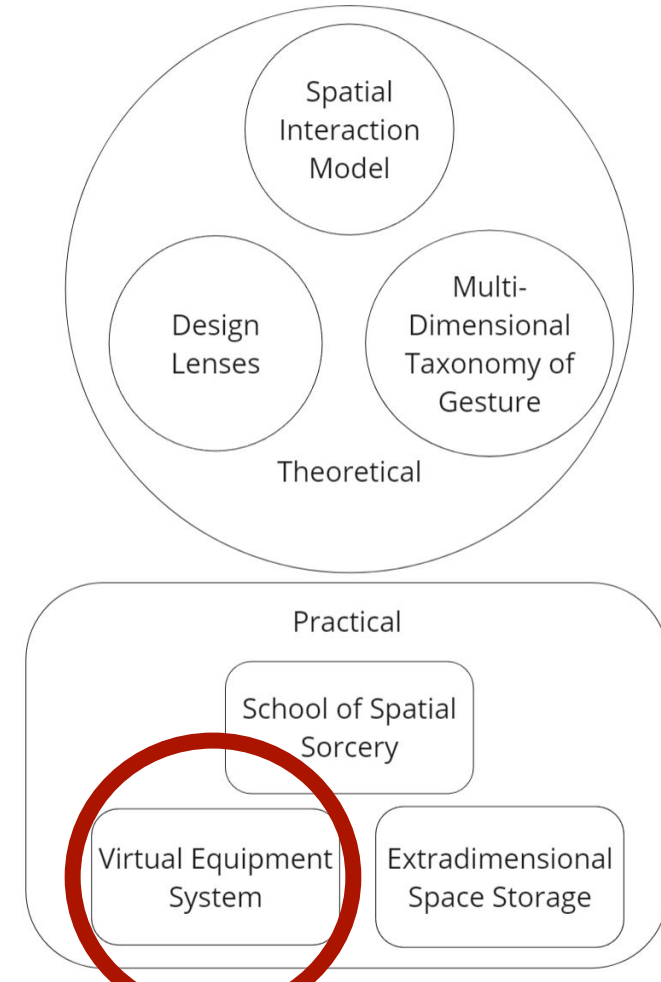
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Simple Extradimensional Storage

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Drawerspace	Chest Space	Access by first grabbing a handle to pull out the space, the spatial location of the content changes as the handle position changes

Virtual Equipment System

Body of Work



(Work listed on next slide)

VES Contribution

Powen Yao, Tian Zhu, and Michael Zyda. “Adjustable Pointer in Virtual Reality for Ergonomic Interaction”. IEEE VR 2020

Powen Yao, Tian Zhu, and Michael Zyda. “Designing Virtual Equipment Systems for VR”. HCII 2020

Powen Yao et al. “Interfacing with Sensory Options Using a Virtual Equipment System”. SUI 2020

Powen Yao, Vangelis Lympouridis, and Michael Zyda. “Virtual Equipment System: Expansion to Address Alternate Contexts”. HCII 2021

Powen Yao, Vangelis Lympouridis, and Michael Zyda. “Virtual Equipment System: Face Mask and Voodoo Doll for User Privacy and Self-Expression Options in Virtual Reality”. IEEE VR 2021

Powen Yao, Shitong Shen, and Michael Zyda. “Virtual Equipment System: First Evaluation of Egocentric Virtual Equipment for Sensory Settings”. VAMR 2022/HCII 2022

Introduction

Virtual Equipment System makes use of visual **metaphors** to guide users on how to interact with their equipment and the associated functionalities based on the look and feel of the equipment.

Virtual Equipment System can be integrated and implemented across different devices and systems to be part of a **universal user interface** for different extended realities.



Summary of VES

1. Manifestation

- a. **Egocentric Equipment can exist in peripersonal and extrapersonal space**
- b. **Egocentric Equipment can include traditional Exocentric Equipment and Workspace**
- c. Equipment in alternate space (list-space, tab-space, etc)

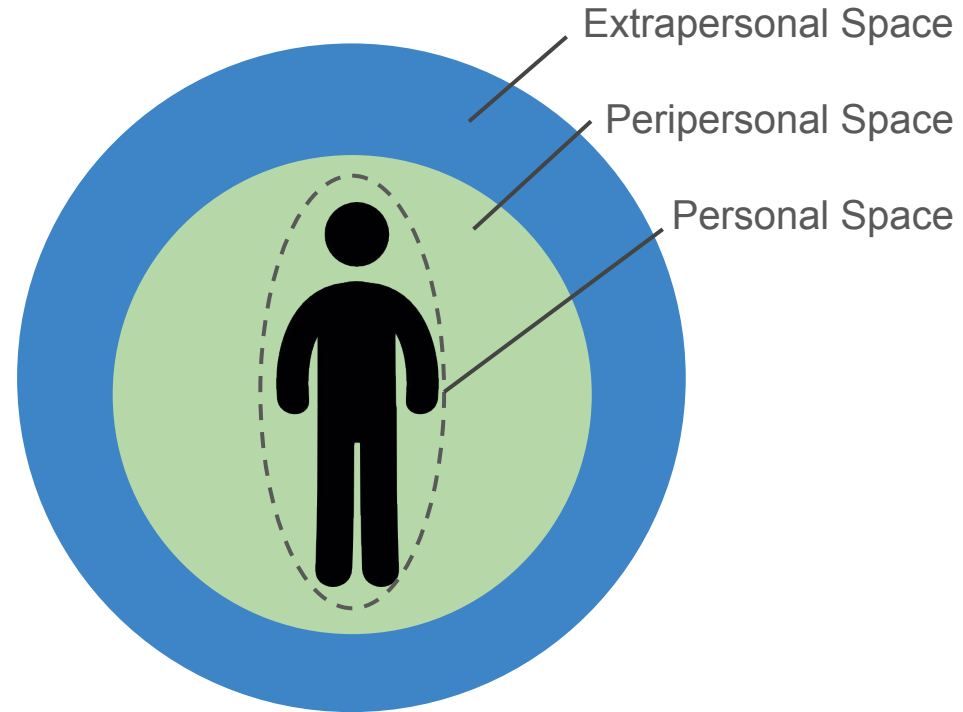
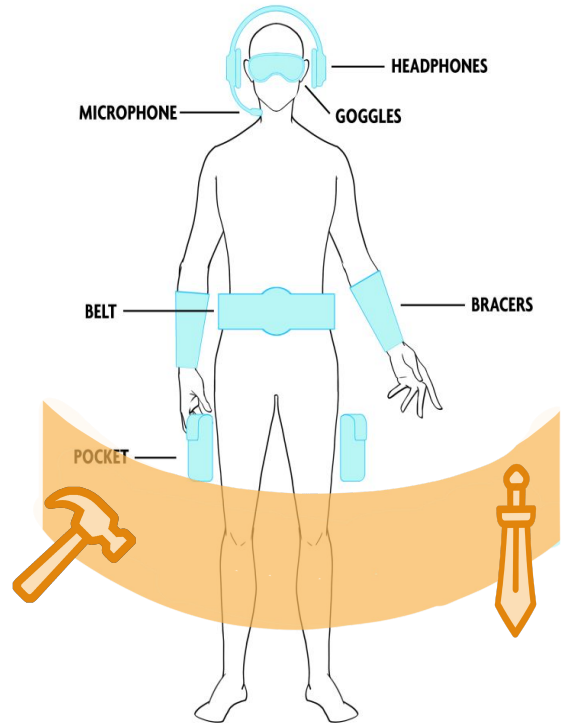
2. Action

- a. **Multiple Egocentric Equipment can be stored in the same Equipment Slot**
- b. **Egocentric Equipment in the same physical space, but in a different dimension**
- c. Accessing equipment not stored in physical space via multi-modal interaction
- d. Hybrid Interaction with other techniques

3. Effect

- a. **Alt Node Interaction**
- b. **Equipment Gestures (Motion, Surface, Tap, etc)**
- c. **Examples of different contexts**
 - i. Sensory Set - Sensory Setting, Privacy Set - Privacy Options, Avatar Set - Avatar Presence

Manifestation: Equipment in Personal, Peripersonal, and Extrapersonal Space



Effect: Applying VES to Different Contexts

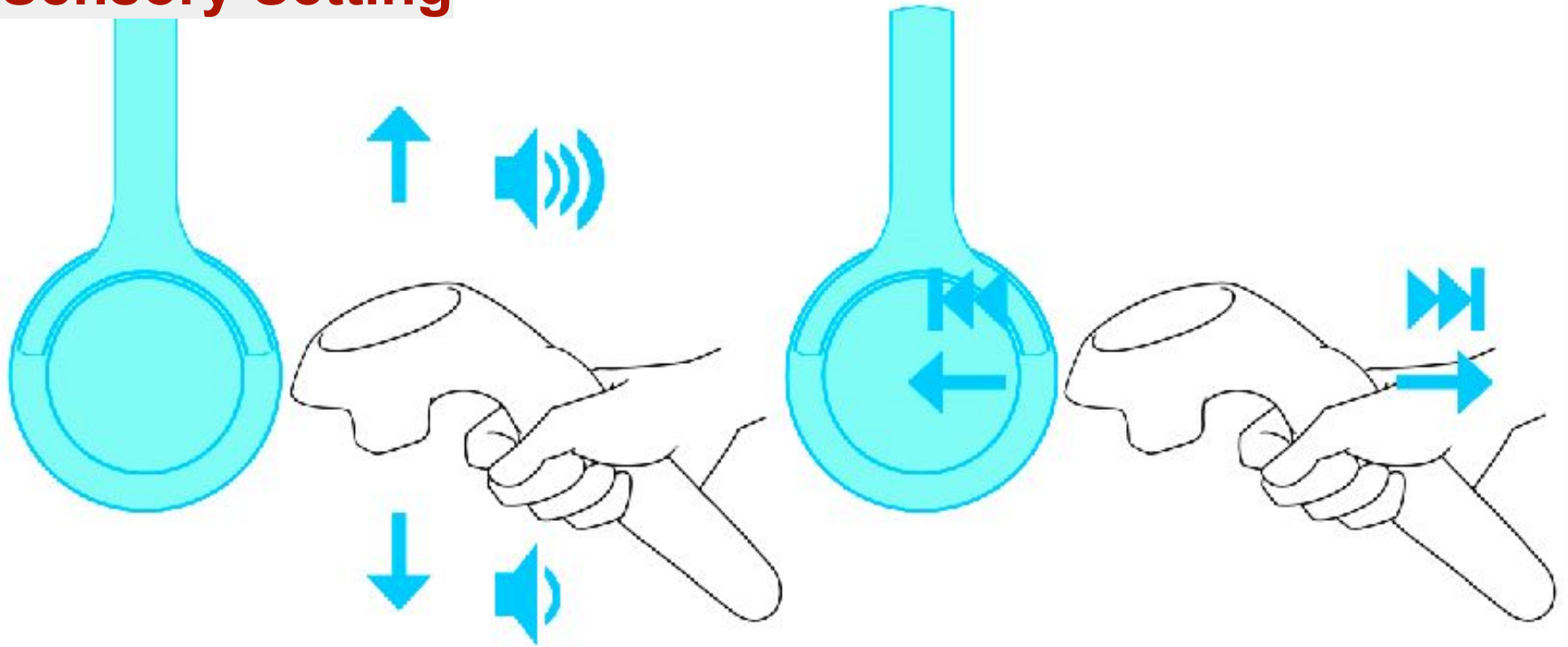
With the hyperphysical effects, we can apply VES to different contexts with different sets of Equipment.

Multiple Equipment Sets can be worn at a time.

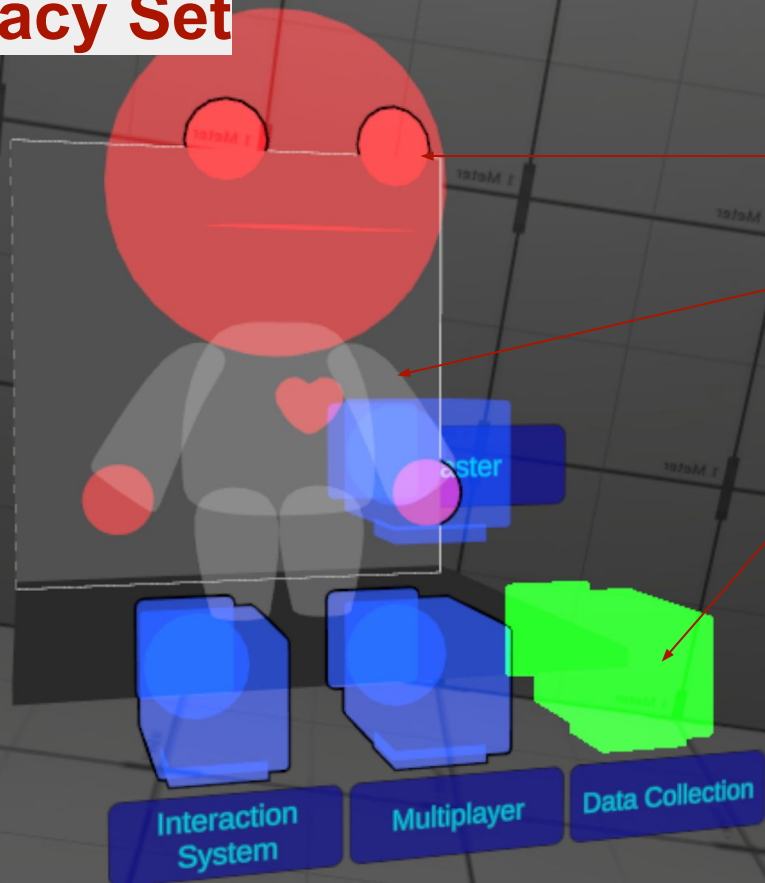
Equipment Sets

- **Sensory Set for Incoming Sensory Data**
- **Privacy Set for Outgoing User Data (Privacy)**
- Management Set for VES Management
- Cosmetic Set for Outgoing User Data (Cosmetic)
- **Avatar Set for Using Alternate Avatars**
- Dev Set for Development or Debug
- App/Game-Specific Set

Sensory Setting

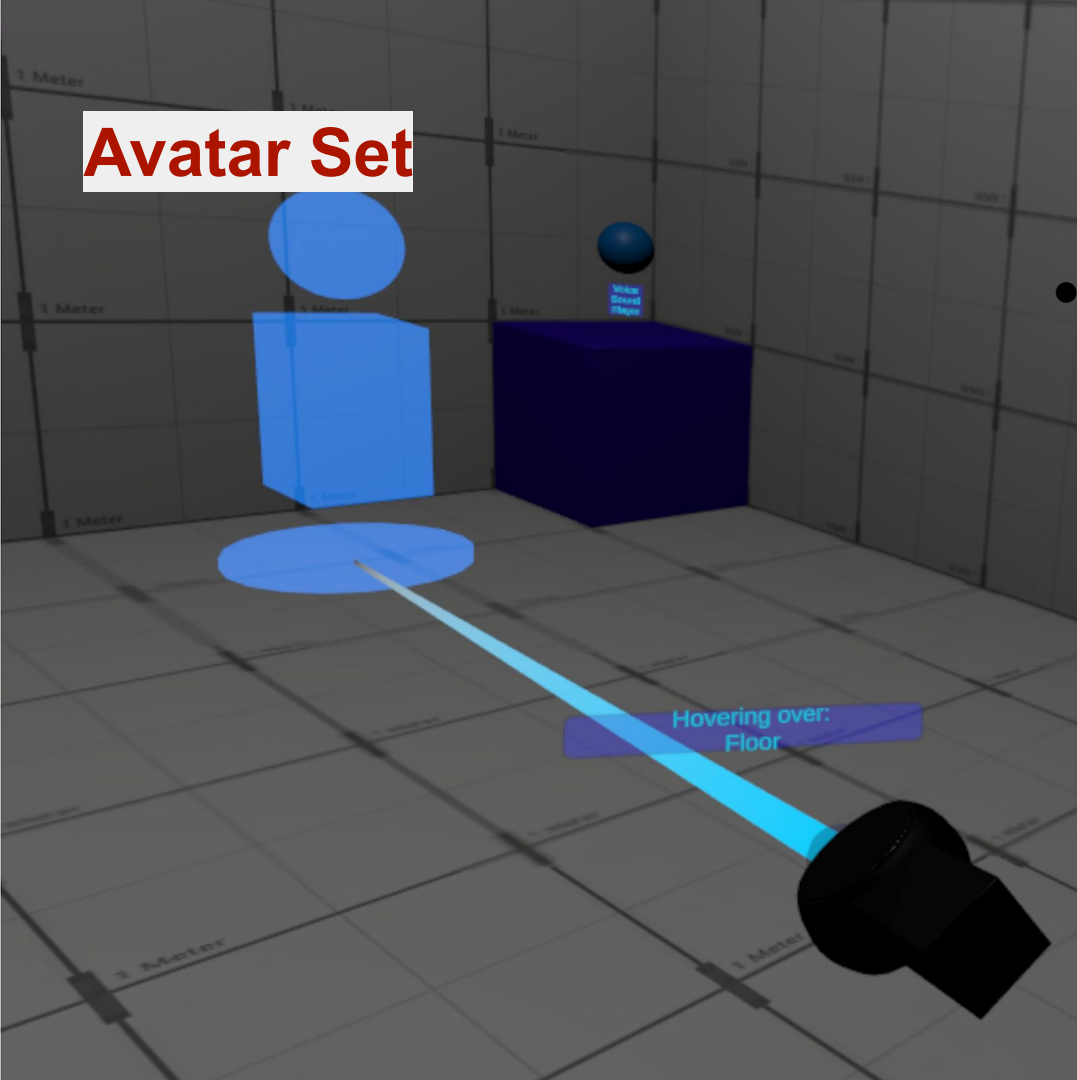


Privacy Set



- In red are body parts with tracking disabled.
- In gray are body parts that are not tracked.
- The green camera represents the perspective in which we are seeing the user's privacy data status.

Avatar Set



- User placing an **Alternate Avatar** in the virtual environment by interacting with the **Avatar Doll** at the back of the user's head

Action: Multiple Equipment Sets

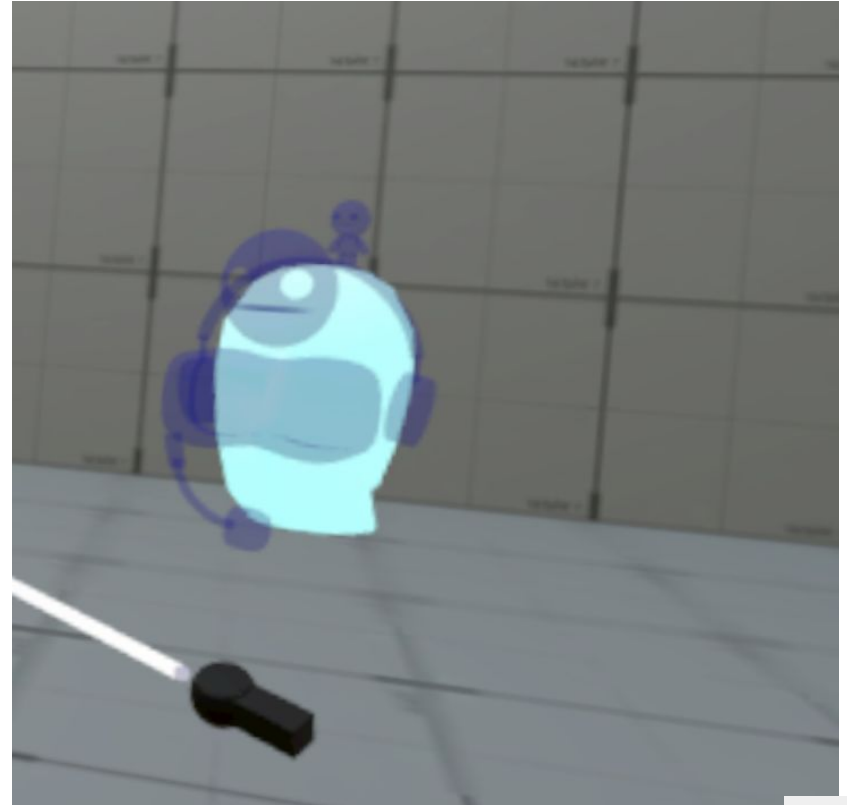
Equipment Set

- Sensory Set
- Privacy Set
- Avatar Set

Eye Location

- Sensory Set - Adjust Brightness
- Privacy Set - Turn on/off eye tracking
- Avatar Set - Create Eye Avatars

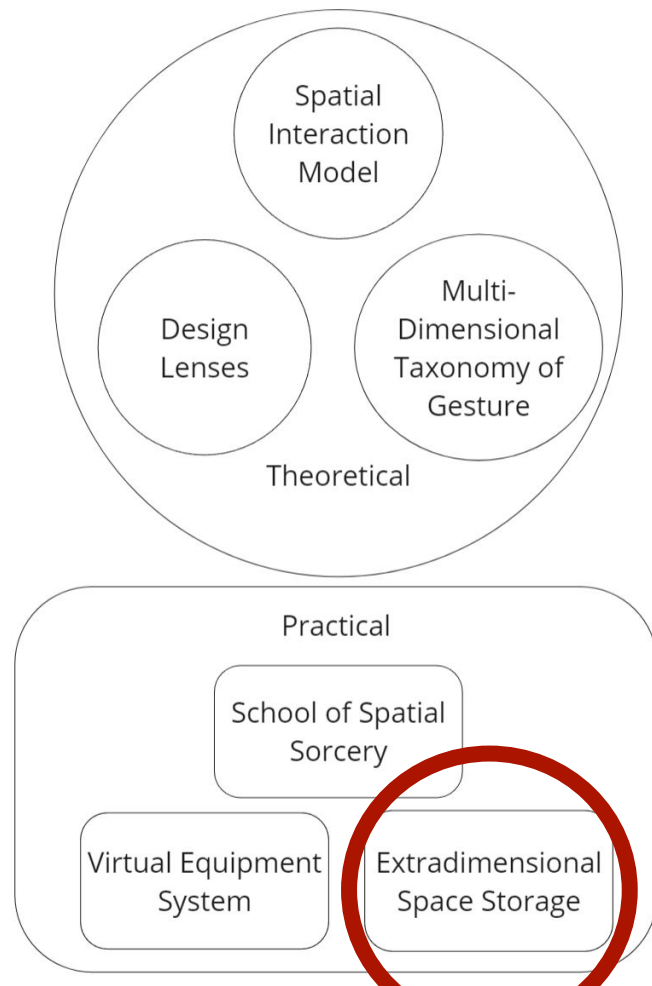
They utilize many of the same locations!
Need for **extradimensional space!**



Extradimensional Space Storage

Poweren Yao, Zhankai Ye, and Michael Zyda. "Virtual Equipment System: Toward Bag of Holding and Other Extradimensional Storage in Extended Reality". VAMR 2022 / HCII 2022

Body of Work



EDS Storage in Pop Culture



4th dimension pocket from the anime Doraemon



From the Trading Card Game Magic the Gathering

5 Components of a Storage System

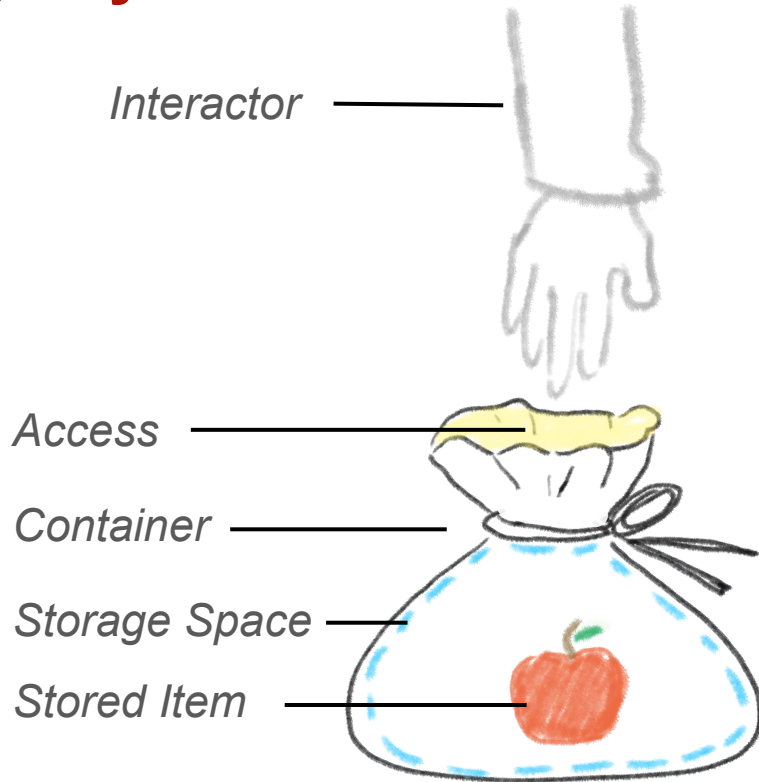
Access

Container

Storage space

Stored Item

Interactor



Extradimensional Space Storage

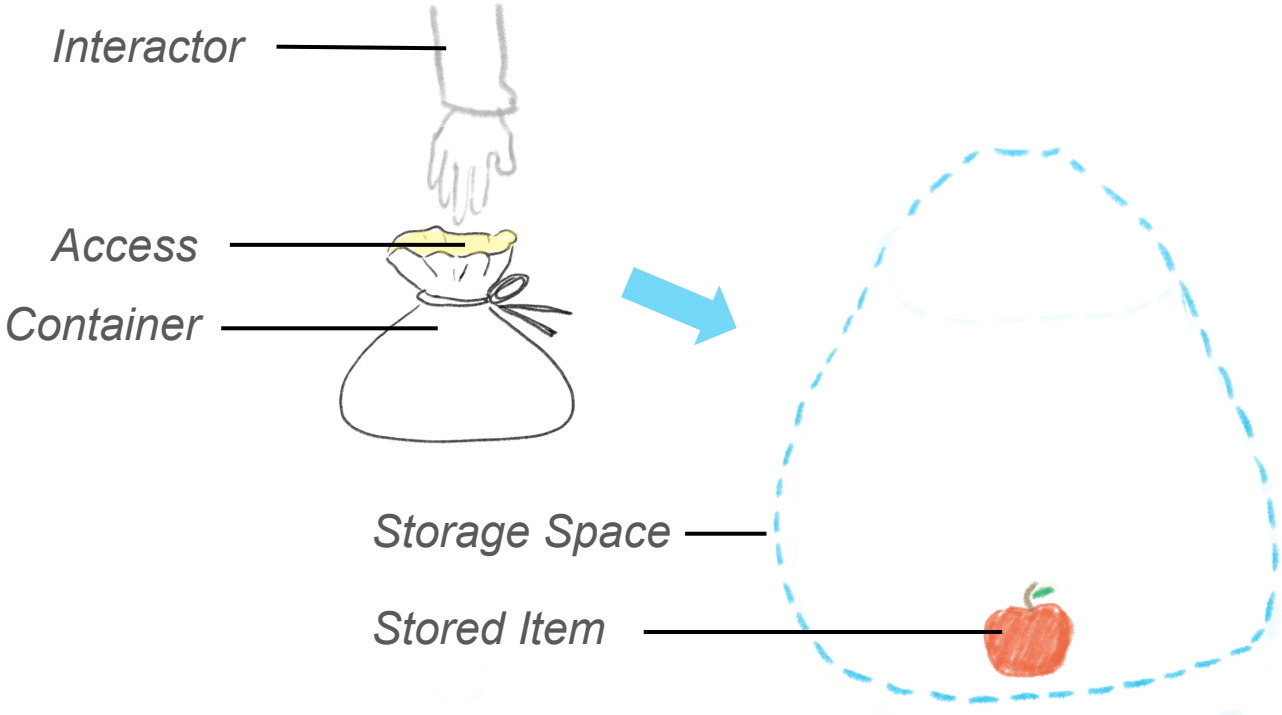
Access

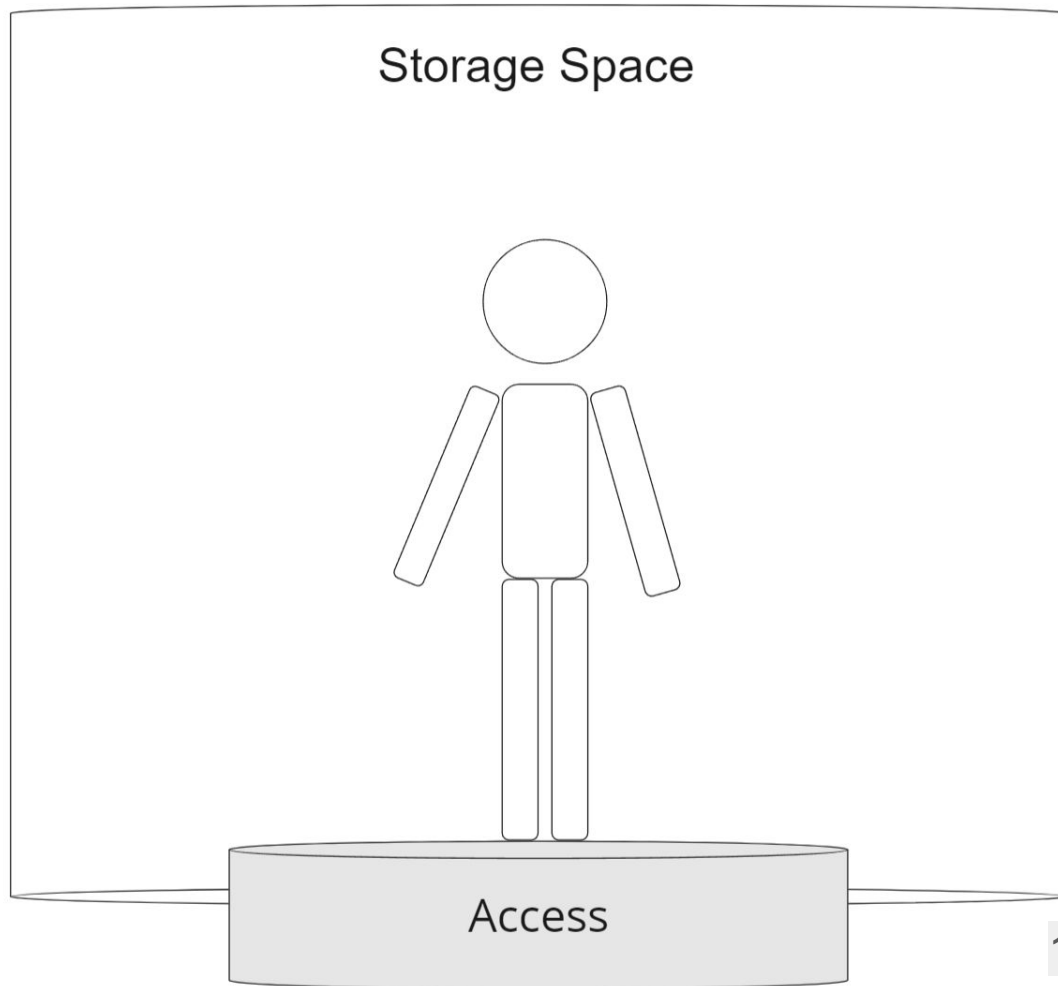
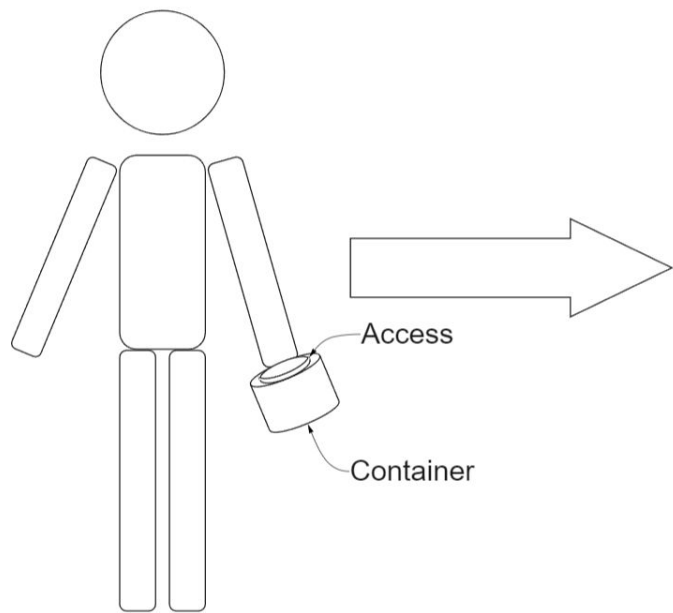
Container

Storage space

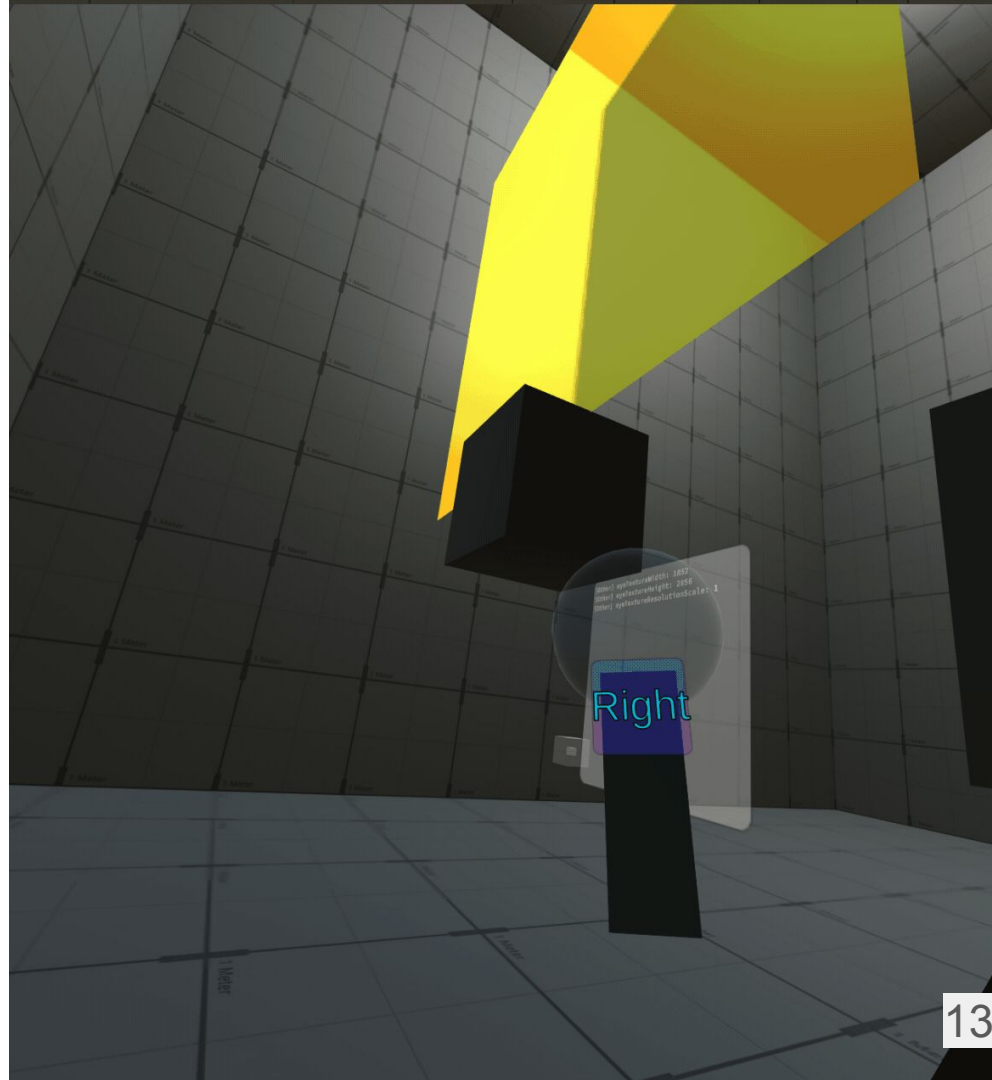
Stored Item

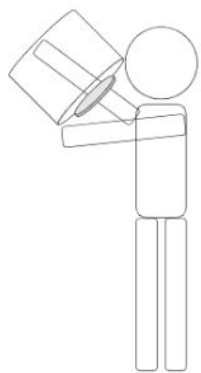
Interactor



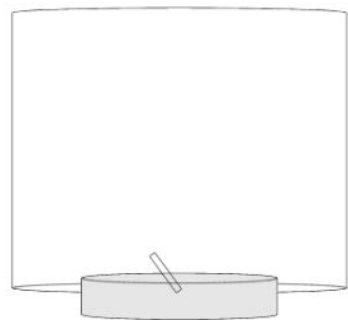


EDS Storage

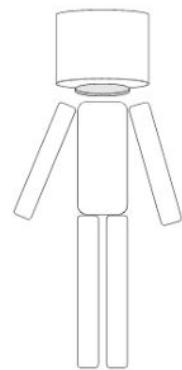




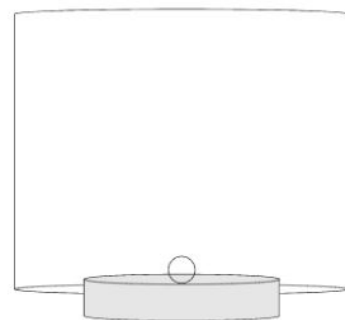
Outside



Inside



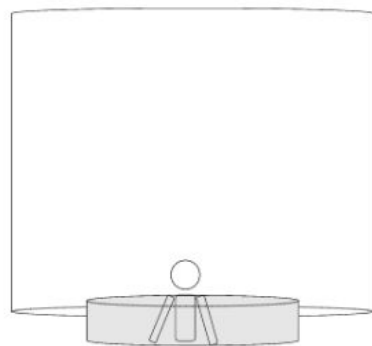
Outside



Inside



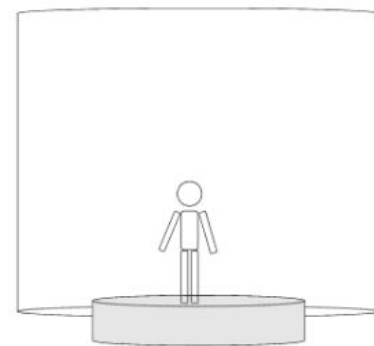
Outside



Inside



Outside

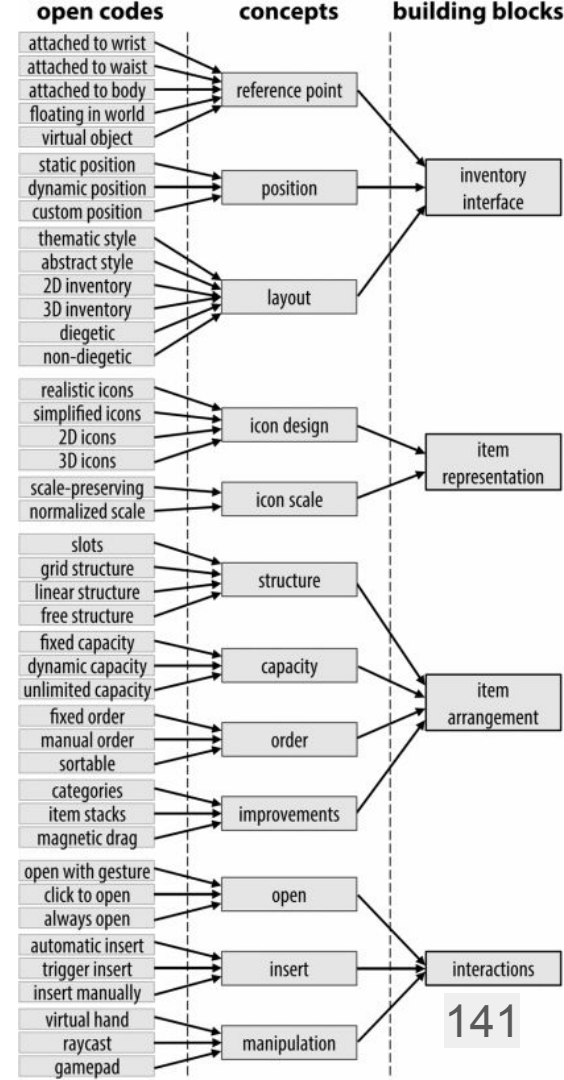


Inside

Taxonomy of Inventory Systems

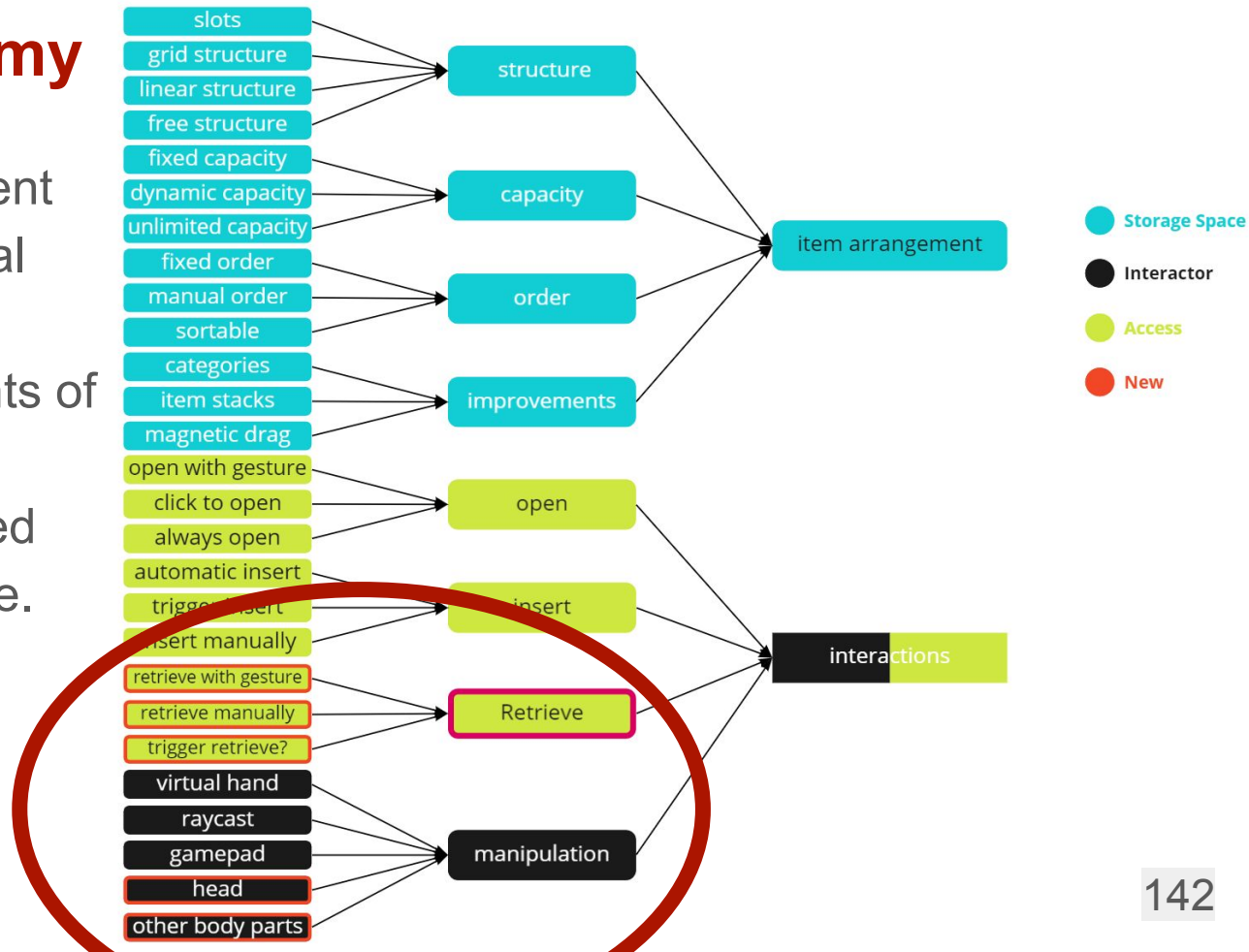
Cmentowski et al. performed Game Analysis using Grounded Theory Analysis

Cmentowski, Sebastian, Andrey Krekhov, and Jens Krüger. "I Packed My Bag and in It I Put...": A Taxonomy of Inventory Systems for Virtual Reality Games." 2021 IEEE COG



Modified Taxonomy

Based on our independent work of Extradimensional Space Storage, we introduce the components of interactor, interactable (access, container, stored Item), and storage space.



(Continued)

Interactor

Access

Container

Storable

Storage space

Open Codes

Concepts

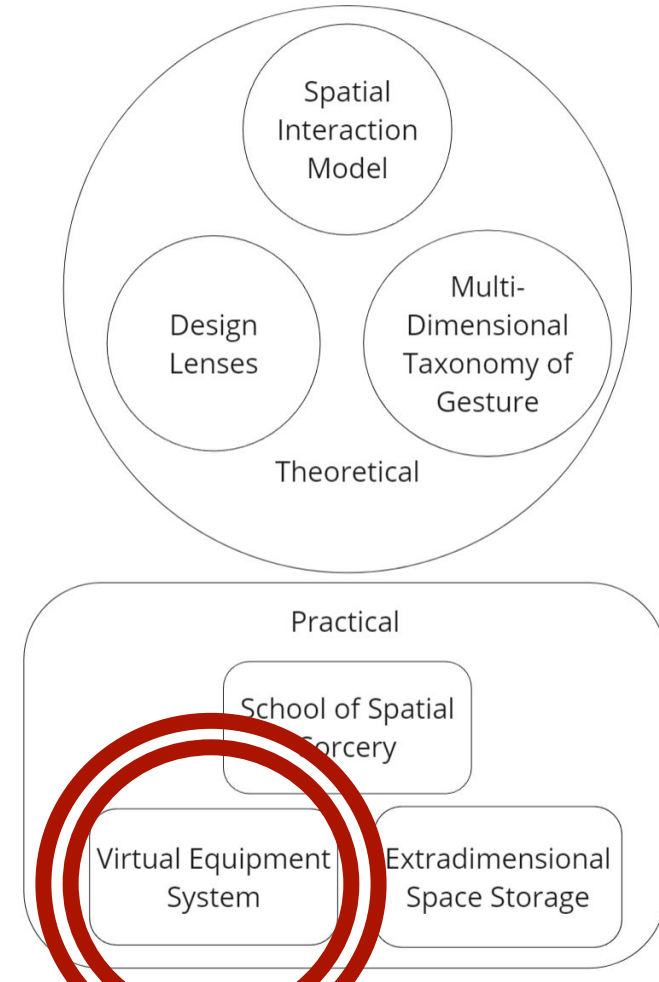
Building Blocks



- Container
- Storage Space
- Stored Item
- New

Evaluation VES User Study

Body of Work



Introduction

We conducted a **within-subjects user study** followed by a questionnaire based on modified **NASA-TLX**.

In it, we compared **different interaction techniques** for adjusting audio volume. We also examined the effect of having Virtual Equipment in **different locations** within personal and peripersonal space.

We performed statistical analyses on the collected data, such as the Kruskal-Wallis H Test. Results suggests that there are definitive differences among the different classes of techniques.

Overall, some class of techniques are better in one aspect (duration required), while worse in another (motion required).

Research Questions

RQ1: How do the techniques compare in terms of efficiency?

RQ2: How do the techniques compare in the effort required for each interaction technique?

RQ3: What makes users prefer one technique over another?

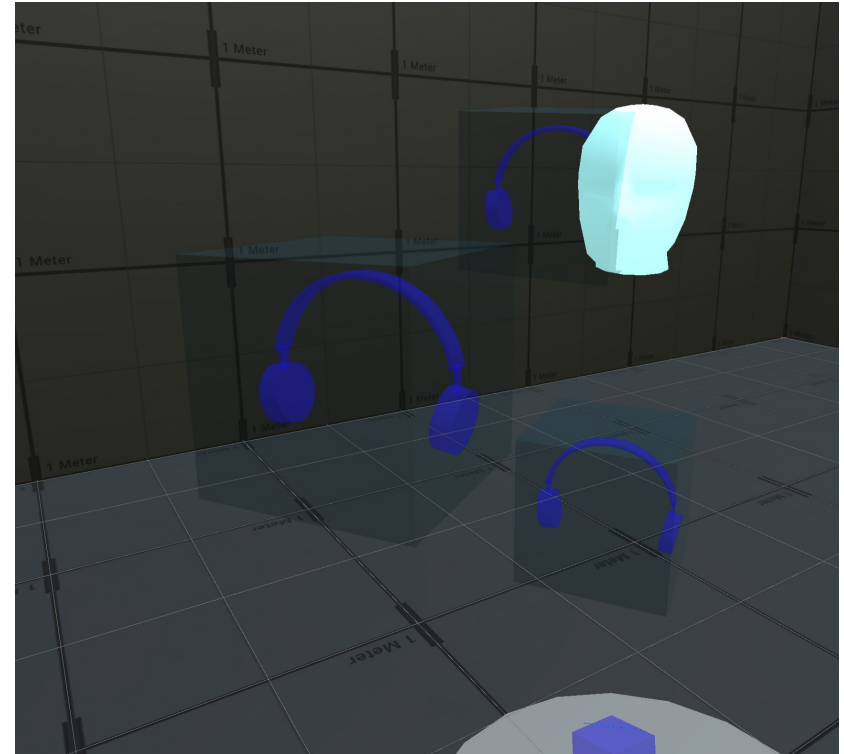
VES User Study Interaction Techniques

Use of Virtual Equipment in Different Spaces

Virtual Headphones by the
user's ear in Personal Space

Virtual Headphones by the
user's waist in Personal Space

Virtual Headphones in
1 o'clock direction in
Peripersonal Space



Interaction Techniques

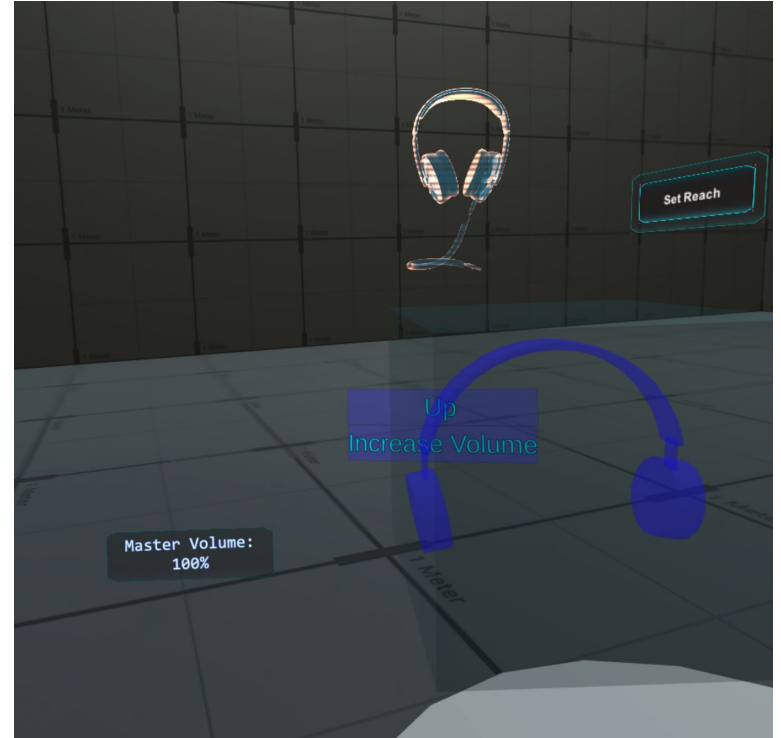
- Motion Gesture (as applied to 3 locations)
- Surface Gesture (as applied to 3 locations)
- Alt Node
- Menu

Task Type	Shorthand	Description
1	Headphones + Motion	Personal Equipment (Ear) Motion Gesture
2	Headphones + Surface	Personal Equipment (Ear) Surface Gesture
3	Waist + Motion	Personal Equipment (Waist) Motion Gesture
4	Waist + Surface	Personal Equipment (Waist) Surface Gesture
5	Peri + Motion	Peripersonal Equipment Motion Gesture
6	Peri + Surface	Peripersonal Equipment Surface Gesture
7	Alt Node + Slider	Moving a slider on a 2D Menu for Audio, through the use of Alt Node
8	Menu Button + Sliders	Moving a slider on a 2D Menu for Audio, through a menu button on the VR Controller

Motion Gesture

When the user grabs any of the Virtual Headphones and moves it up and down, this would trigger its Equipment Motion Gesture.

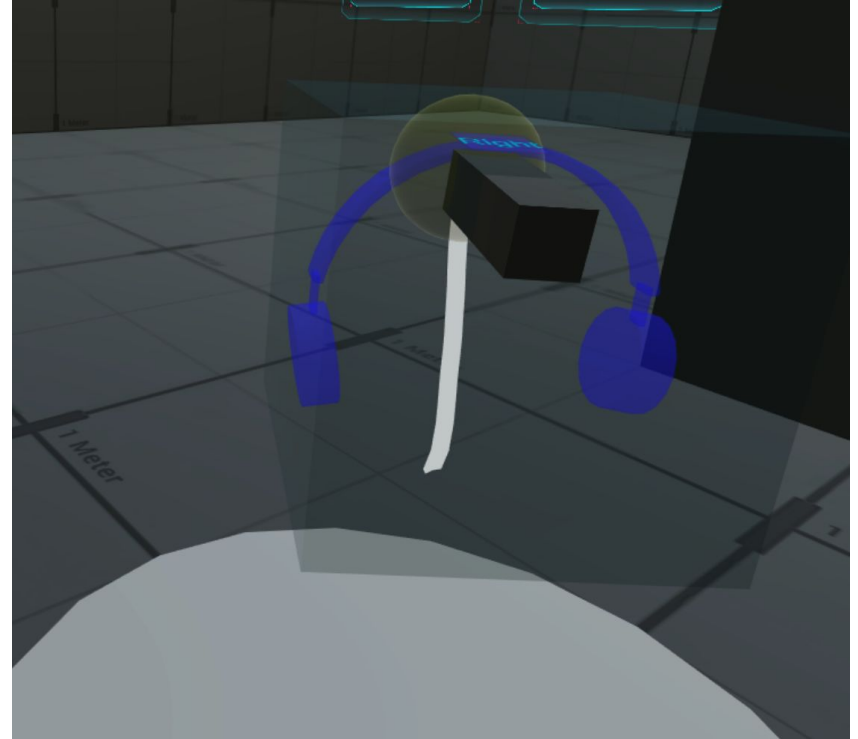
The up and down gestures correspond to the increase or decrease of the system's audio volume, respectively.



Surface Gesture

When the user pushes the trigger button and moves the controller, this draws a white line where the motion controller's tip is. As the user lets go, the white line is interpreted to determine which Equipment Surface Gesture it was.

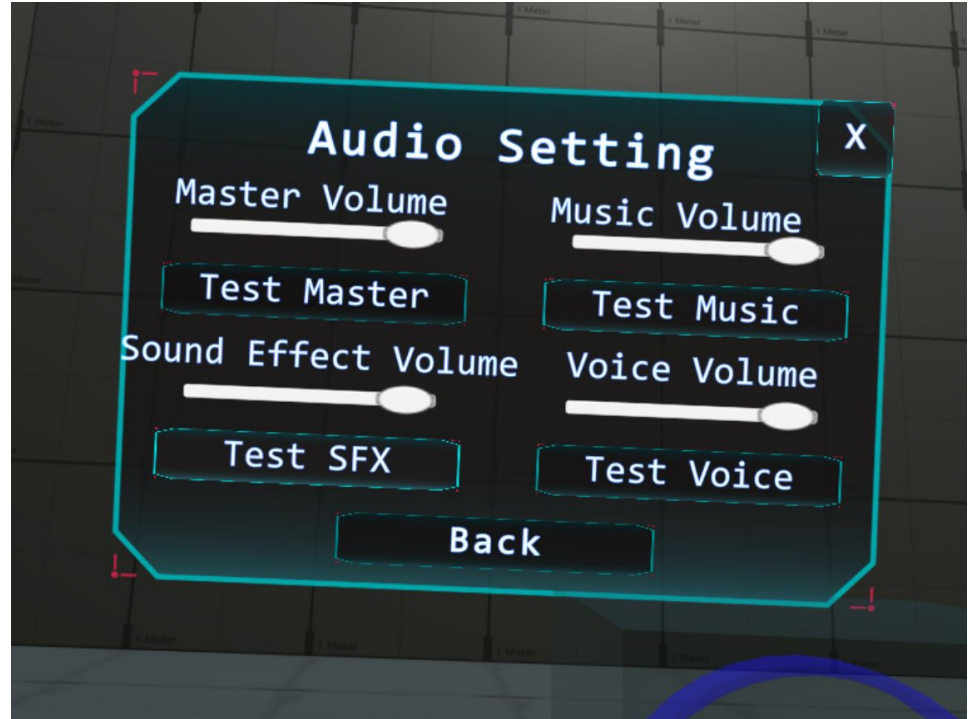
The up and down gestures correspond to the increase or decrease of the system's audio volume.



2D Menu (Traditional)

2D Menu is the most common way to adjust audio settings other than having physical buttons on the VR headset.

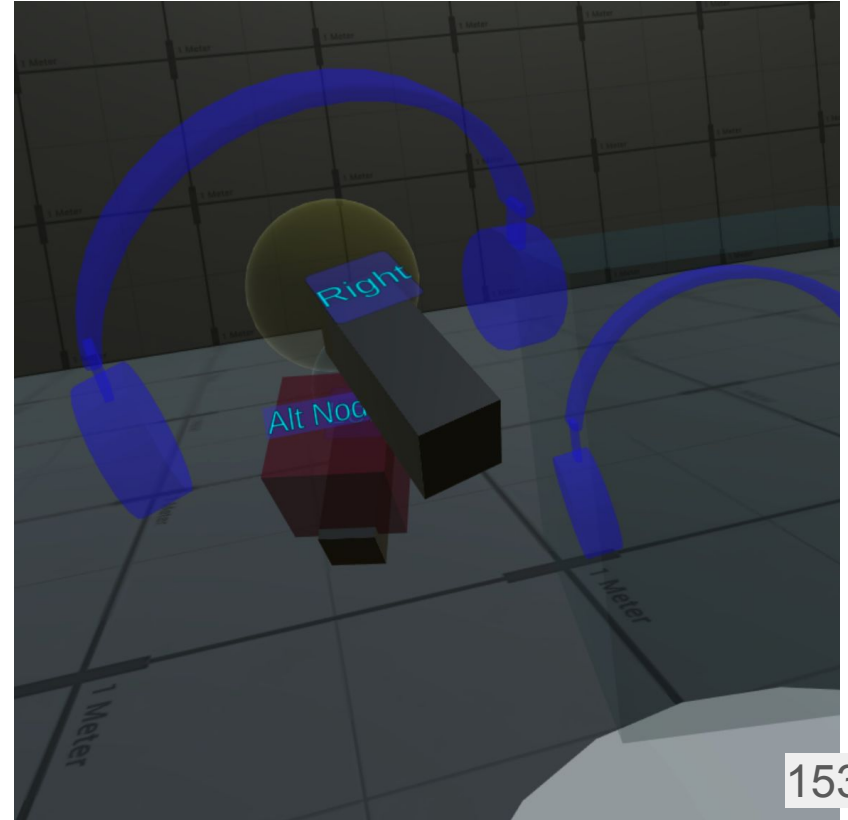
The user would push the menu button on the controller. Then use the ray interactor to navigate through the General Menu, Settings Menu, then Audio Settings Menu to adjust the Master volume.



Alt Node

User can grab the Virtual Headphones and dropping it in the Alt Node (think Alt Key). This summons the detailed setting menu associated with that Virtual

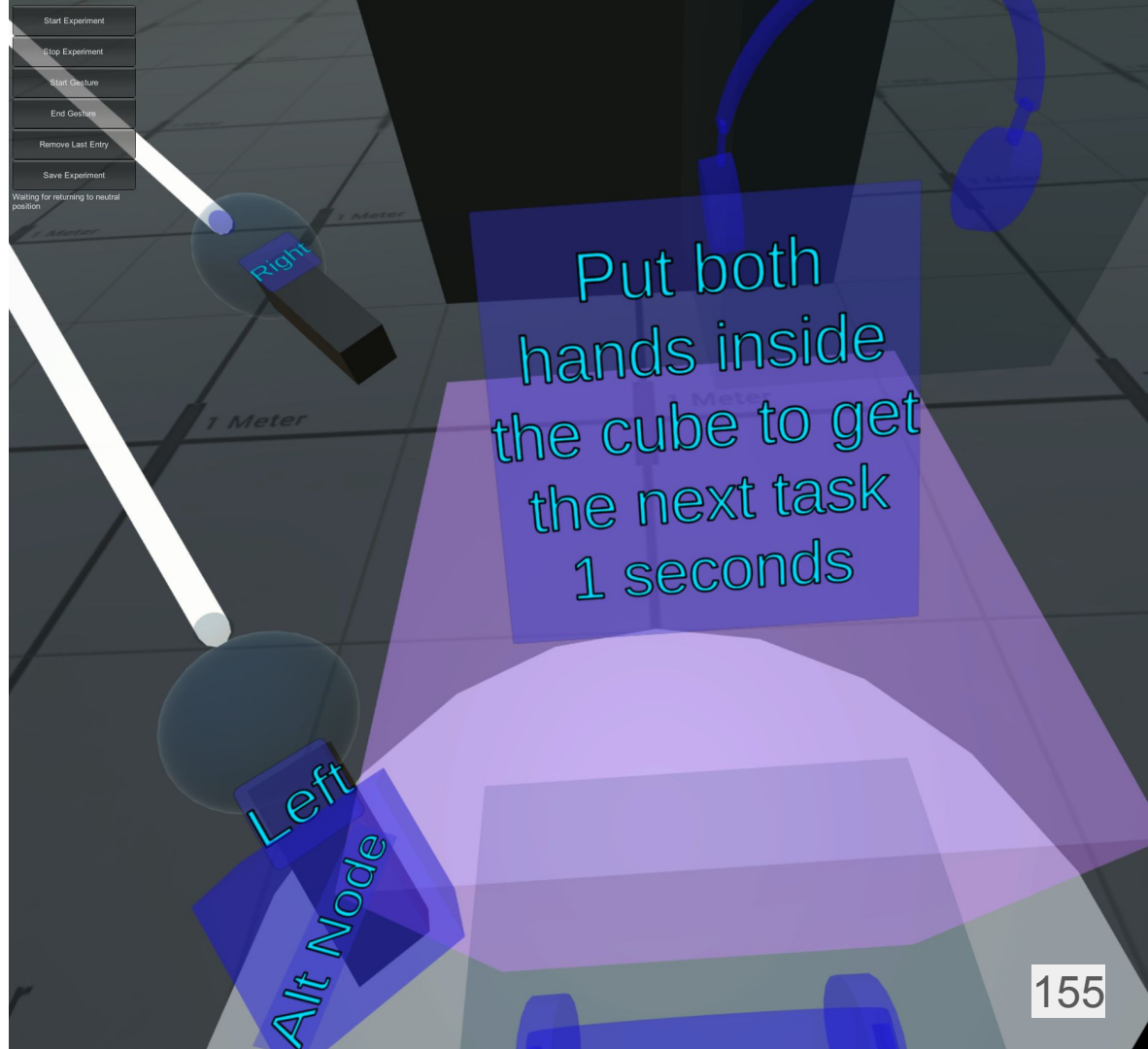
In the case of a Virtual Headphone, it is an detailed Audio Settings Menu. The user can then adjust the master volume



VES User Study Methods

Pink Cube

The user needs to place both controllers inside the pink cube to initiate a task.

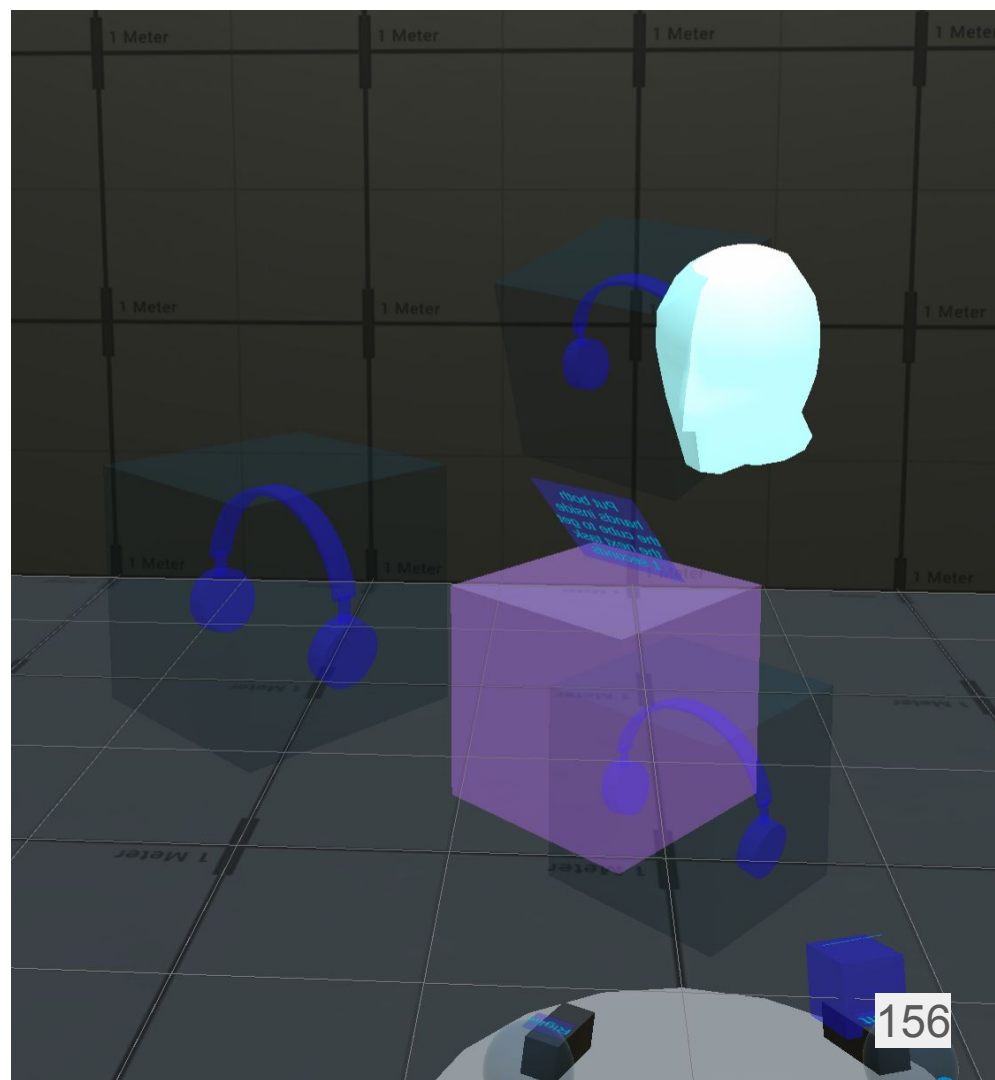


Pink Cube

To avoid giving any location too much advantage, the pink cube is placed in the center of the equipment.

This roughly places the pink cube 49.5 cm away from the ear, 28 cm away from the waist, and 48.9cm away from the peripersonal location.

Location	x	y	z
Personal Equipment (Ear)	0.15	0	-0.07
Personal Equipment (Waist)	0	-0.6	0
Peripersonal Equipment	0.2	0.2	0.6



Eight Tasks

The user is given one of the eight tasks at random. After the user has performed each of the eight tasks once, the user will be asked to do a 9th task with any method they like.

Task Type	Shorthand	Description
1	Headphones + Motion	Personal Equipment (Ear) Motion Gesture
2	Headphones + Surface	Personal Equipment (Ear) Surface Gesture
3	Waist + Motion	Personal Equipment (Waist) Motion Gesture
4	Waist + Surface	Personal Equipment (Waist) Surface Gesture
5	Peri + Motion	Peripersonal Equipment Motion Gesture
6	Peri + Surface	Peripersonal Equipment Surface Gesture
7	Alt Node + Slider	Moving a slider on a 2D Menu for Audio, through the use of Alt Node
8	Menu Button + Sliders	Moving a slider on a 2D Menu for Audio, through a menu button on the VR Controller

VES User Study Evaluation

Demographic

Eleven participants (N=11, mean age: 27.1, SD: 4.43, male/female 9/2) volunteered for the experiment.

Due to the COVID-19 pandemic, the experiment instructions were sent to the participants. It was conducted remotely at their homes with the participant's own VR equipment.

The VR devices include HTC Vive, HTC Vive Cosmos, Valve Index, Oculus Rift S, and Oculus (now Meta) Quest 1 and 2.

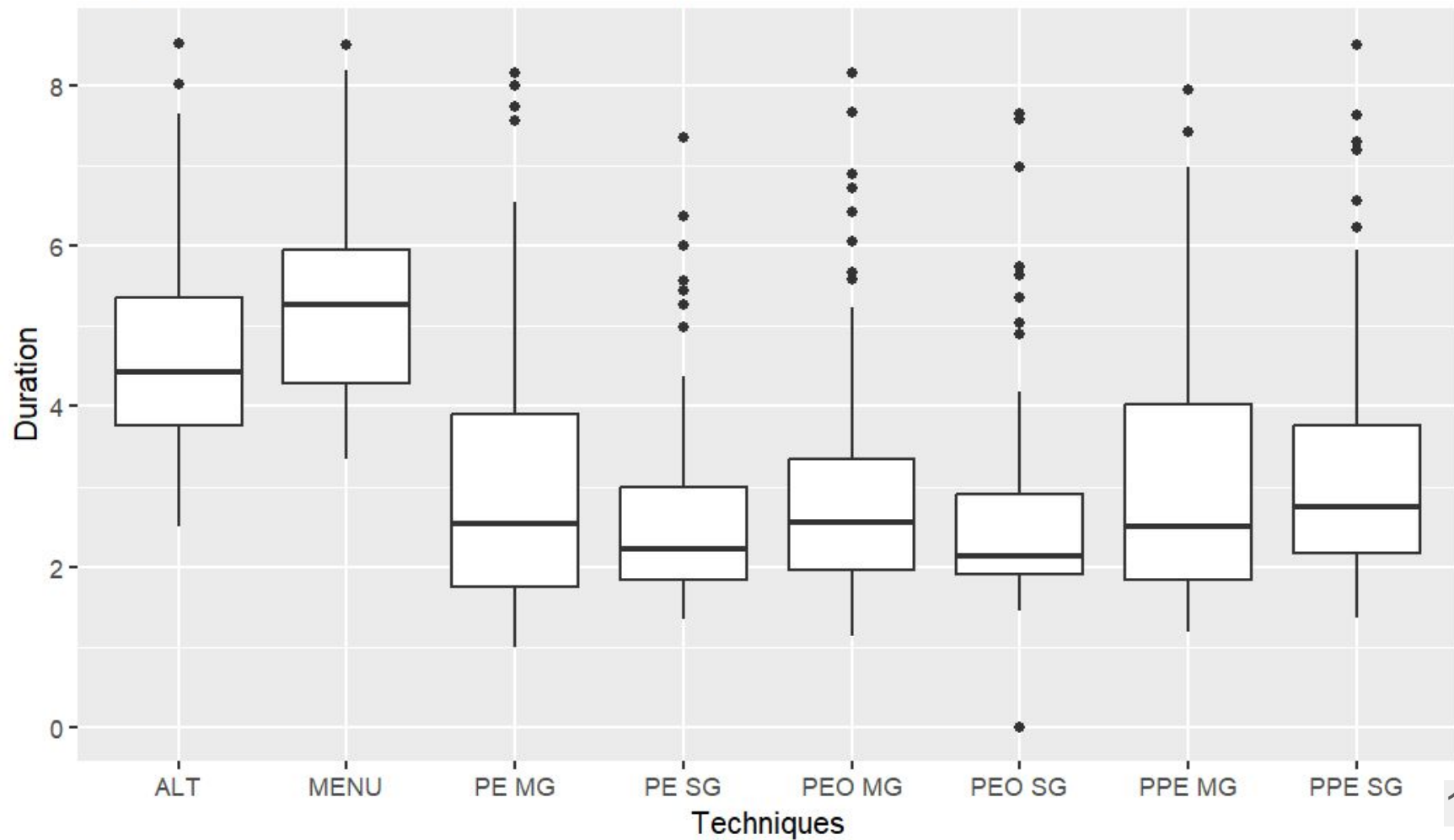
Statistical Analysis

The data did not follow a normal distribution as shown by plotting Normal Quantile-Quantile Plots and using the Sharpiro-Wilk Test..

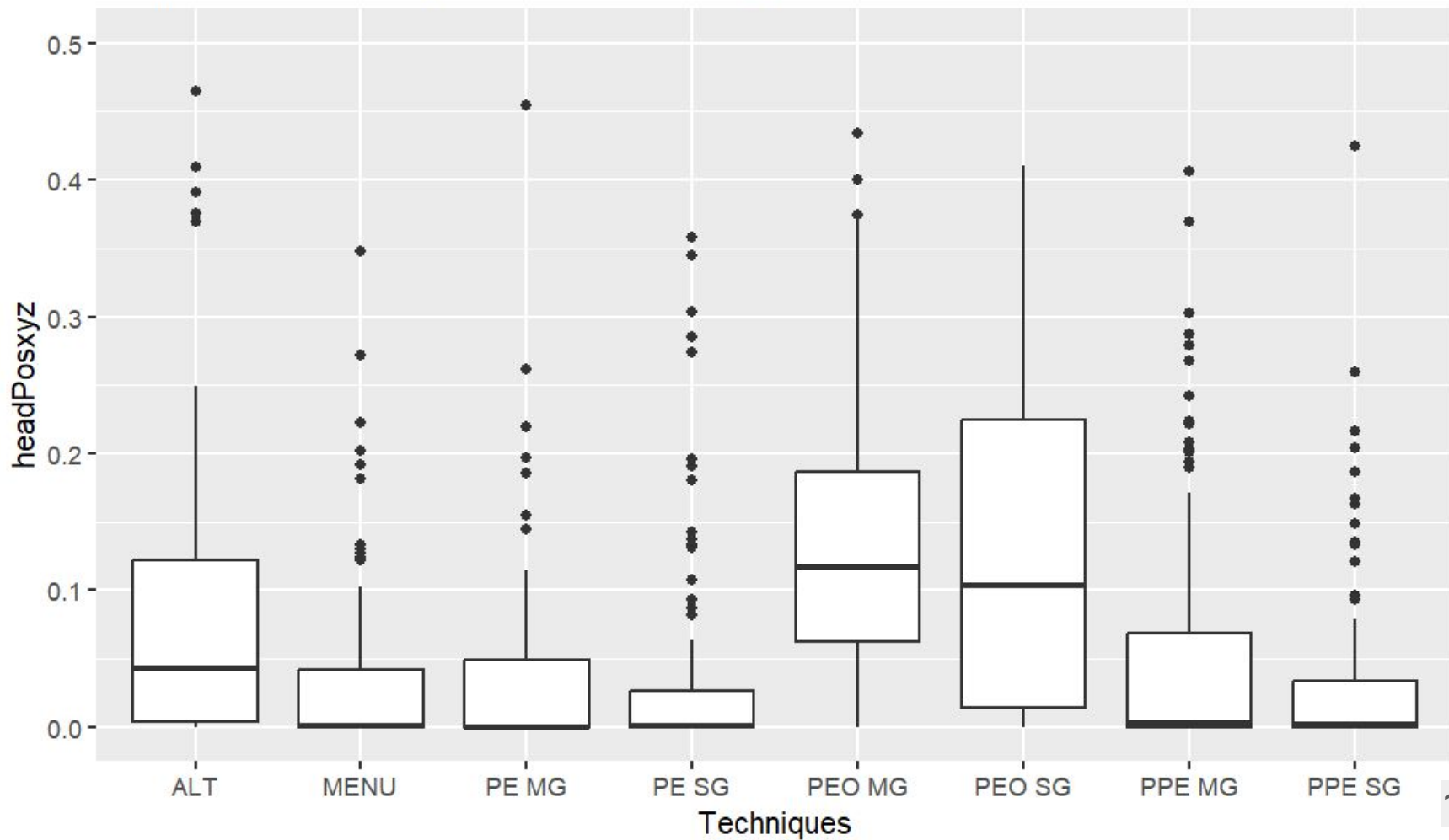
We used the Kruskal-Wallis test to compare the different techniques. We found that we had a p-value of 0.1481. **However**, if we remove the first block of the data (out of the 10 blocks), the p-value changes to 0.0001244.

This suggests that 1) despite the tutorials, participants were still learning in the first block, and 2) there is a significant difference between these techniques once we account for the learning that occurred in the first block

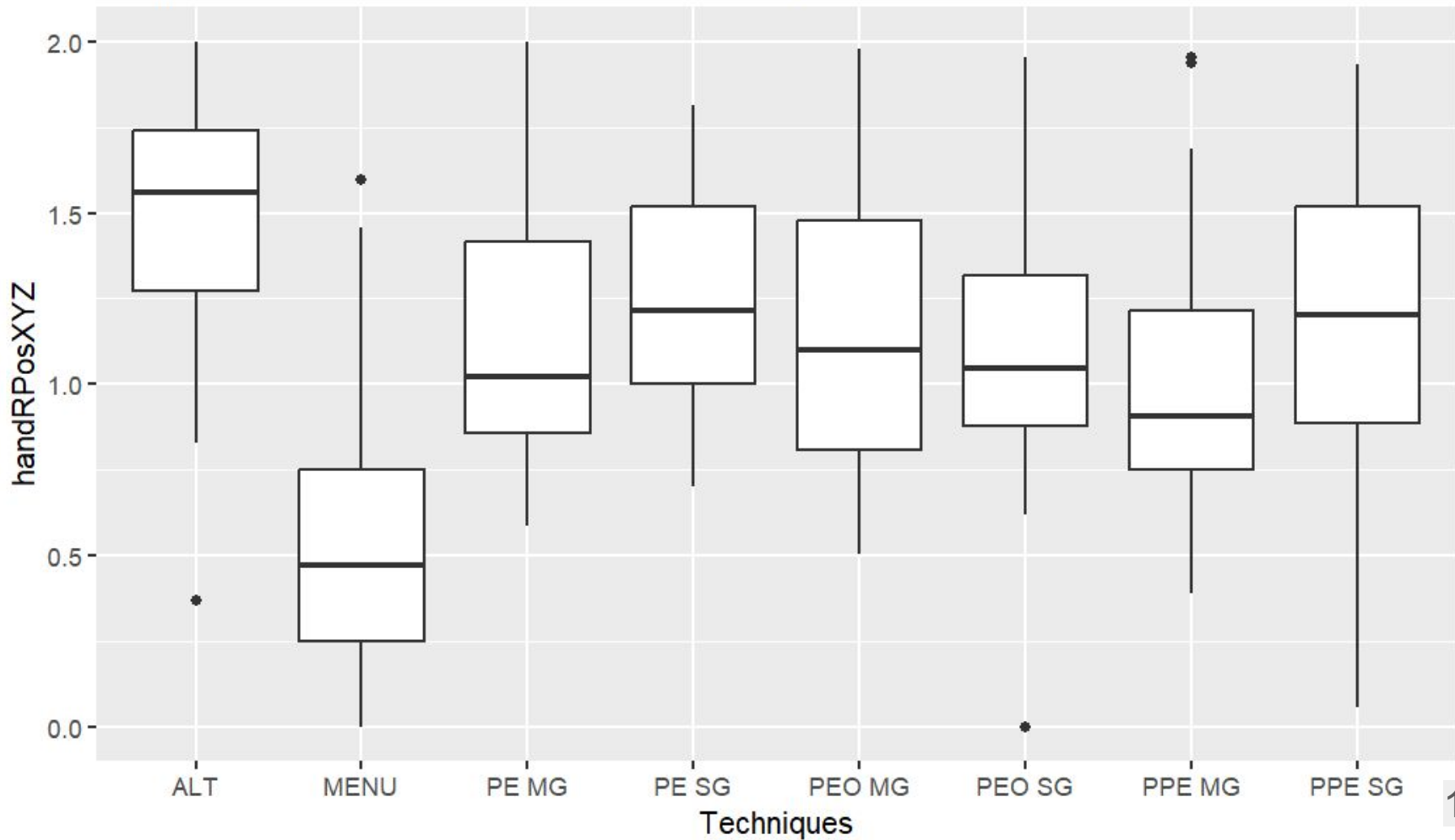
boxplot of duration of different techniques



boxplot of headPosxyz of different techniques

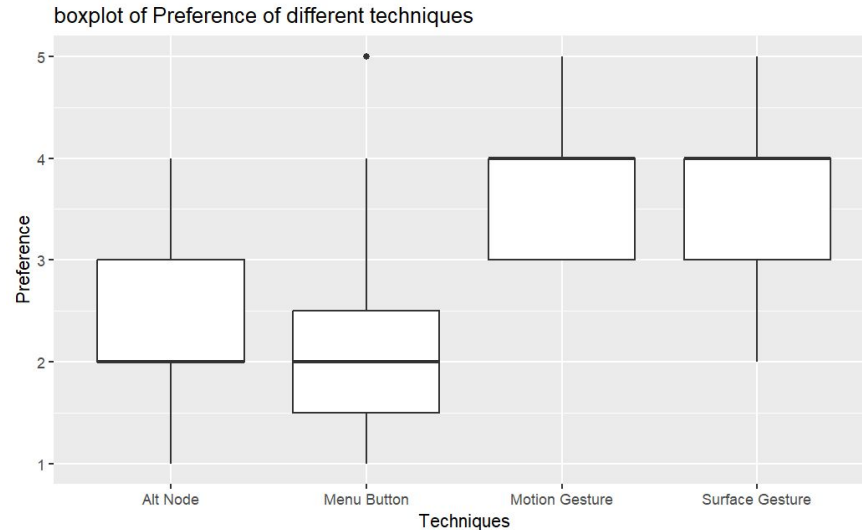


boxplot of handRPosXYZ of different techniques



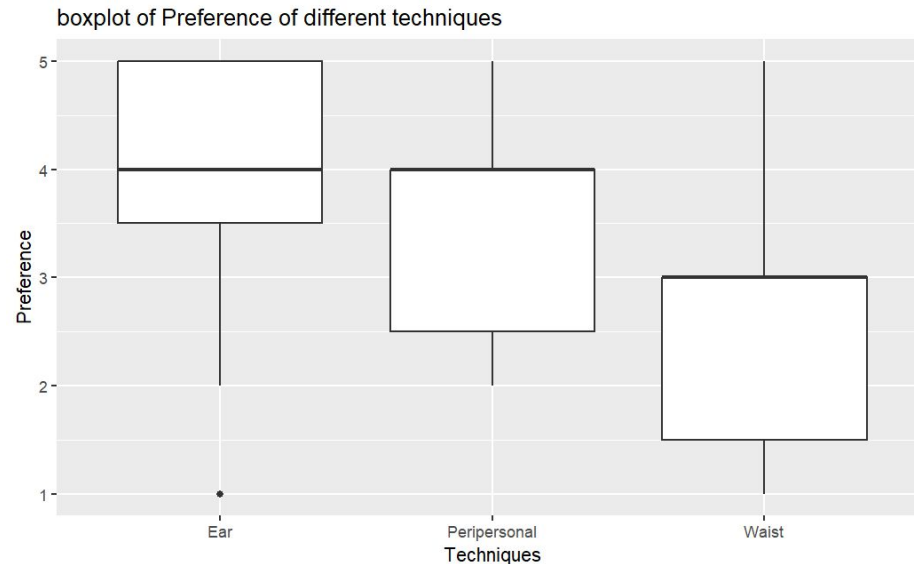
Post-Experiment Question - Techniques

Technique	Mental Demand	Physical Demand	Preference
Motion Gesture	1.55	1.82	3.82
Surface Gesture	1.73	1.55	3.55
Alt Node + Slider	2.27	2.45	2.45
Menu Button + Slider	2.09	2.00	2.27



Post-Experiment Question - Location

Location	Mental Demand	Physical Demand	Preference
Ear	1.82	1.82	3.91
Waist	2.36	2.27	2.45
Peripersonal	1.55	1.82	3.55



VES User Study Conclusion

Discussion

Techniques that are the most efficient (RQ1) are not those that require the least effort (RQ2). Interestingly, the techniques requiring the least movement are not perceived as least physically demanding.

Surface Gesture and Motion Gestures are not significantly different.

RQ1: How do the techniques compare in terms of efficiency?

RQ2: How do the techniques compare in the effort required for each interaction technique?

RQ3: What makes users prefer one technique over another?

Limitation

Due to the risk of COVID-19, user experiments were conducted with participants' own devices and at their respective homes. Combined with small sample size, these limitations reduce the generalizability of the study.

Even with the unorthodox data collection, the study has shown virtual equipment does not need to be restricted to personal space, demonstrated that different classes of techniques are useful for different contexts, and provided insights on how future user studies should be conducted.

Future Explorations for VES

1. Focus not on speed, but precision.
2. Combination of Virtual Equipment with different purposes (audio, visual, privacy)
3. In-Person Study

Other Work

Other related work

Text Entry

Poweren Yao et al. “Punch Typing: Alternative Method for Text Entry in Virtual Reality” SUI 2020

Tian Yang, **Poweren Yao**, and Mike Zyda. “Flick Typing: Toward A New XR Text Input System Based on 3D Gestures and Machine Learning”. IEEE VR 2022

Tian Yang, **Poweren Yao**, and Michael Zyda. “Flick Typing: A New VR Text Input System Based on Space Gestures”. VAMR 2022 / HCII 2022

Machine Learning Explorations

(in collaboration with students in the class Machine Learning in Games)

Sloan Swieso et al. “Toward Using Machine Learning-Based Motion Gesture for 3D Text Input”. SUI 2021

Adityan Jothi et al. “Toward Predicting User Waist Location From VR Headset and Controllers Through Machine Learning”. SUI 2021

Mark Miller et al. “Virtual Equipment System: Toward Peripersonal Equipment Slots with Machine Learning”. SUI 2021

Pranavi Jalapati et al. “Integrating Sensor Fusion with Pose Estimation for Simulating Human Interactions in Virtual Reality”. HCII 2022

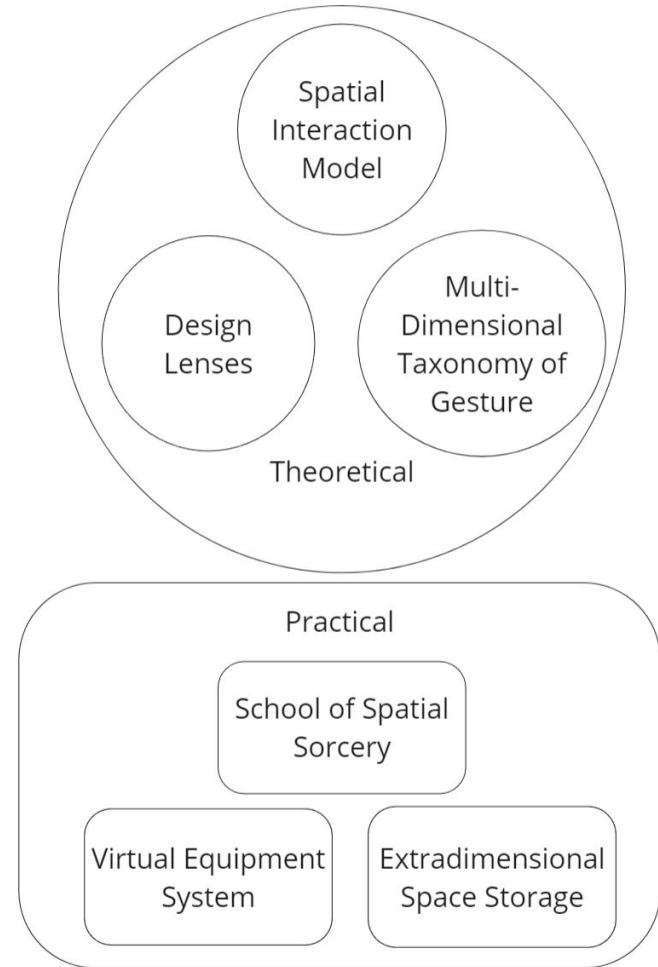
Summary And Conclusion

Body of Work

Summary

The main objective of this thesis is to explore design principles of 3D interaction techniques in the domain of Extended Reality that advances in body tracking technology will enable.

This thesis solves this problem by providing a framework that developers can use to understand existing hyperphysical techniques and to develop their own.



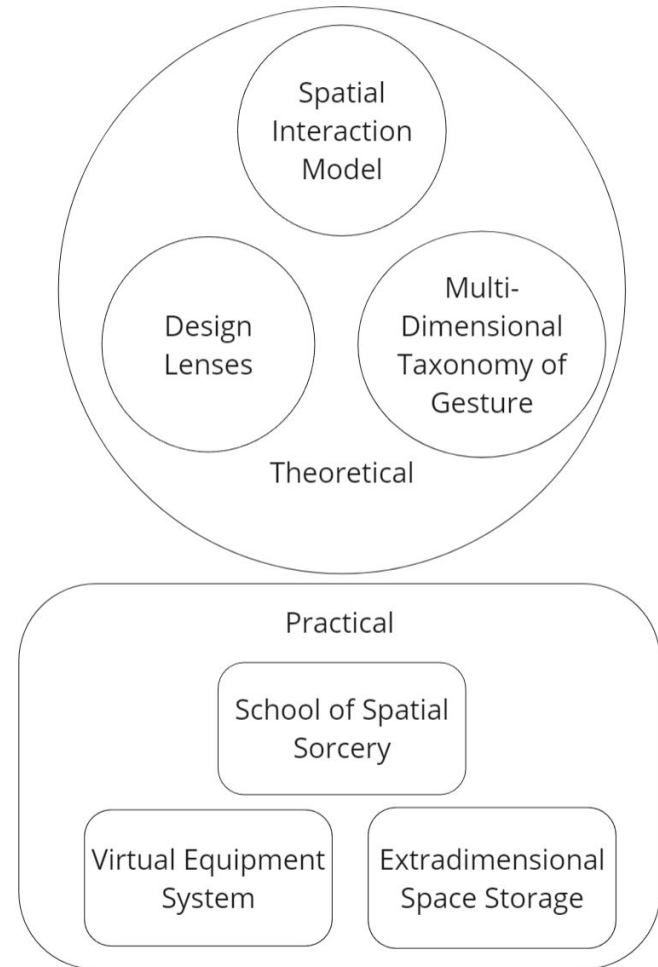
Body of Work

Summary

There will be a dominant interaction technique.

Many use cases will still require use of non-dominant interaction techniques.

Continue to develop specialized solution for different needs



Future Works

Future Works

- Short Term
 - Extradimensional Space Storage User Study
 - Gesture Taxonomy Submission now with Spatial Interaction Model
- Long Term
 - Neuropsychological Impact of Equipment and Interaction in Peripersonal and Extrapersonal Space
 - “Walking through doorways causes forgetting” with Extradimensional Space and other Hyperphysical Transitions

Final Thoughts

With **hyperphysicality**, the sky is the limit to what our interactions can do. Meanwhile, **whole-body interaction** can ground us to what is desirable out of the infinite possibilities.

Extradimensional Space makes it easy to access the most relevant technique to solve problems we face in daily life.

Together, these design lenses will create a future, described by Arthur C. Clarke's Third Law, with advanced interactions that will be truly indistinguishable from magic.



Design Lenses for 3D User Interface in Extended Reality

Powen Yao

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LinkedIn/Facebook/Google/Wechat: powenyao

Backup Slides

Qualification Scope

Design Lens

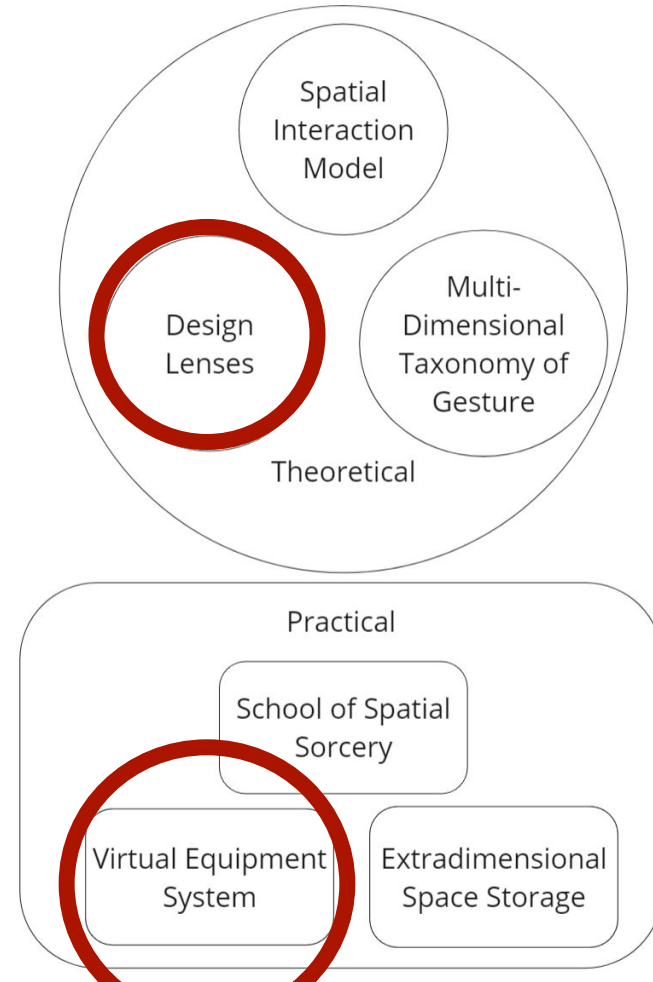
1. Hyperphysical User Interface
2. Whole-Body Interaction
3. Extradimensional Space

Virtual Equipment System

To do for Defense:

Evaluation of Virtual Equipment System

Body of Work



Extradimensional Space Storage User Study

Interaction Techniques

Name	Shorthand	Description
2D Grid Inventory	2DUI	Grabbing item laid out on a 2D User Interface grid
Bag of Holding	Nonlinear	Grabbing items in a 3D volume where the item positions are a non-linear mapping from their actual positions in the Extradimensional Space storage.
Extradimensional Space Storage	EDS Storage	Entering an Extradimensional Space Storage and grabbing objects stored within as if one would in a storage room
Flick Storage	Flick	Accessing items stored on the surface of a sphere by rotating the user's controller

Research Question

1. How do the techniques compare in terms of efficiency?
 - (a) How do the different techniques compare regarding task completion time?
 - (b) How do the different techniques compare regarding accumulated head movement required for task completion?
 - (c) How do the different techniques compare regarding accumulated hand movement required for task completion?
2. How do the techniques compare in the effort required for each interaction technique?
 - (a) How do the techniques compare in terms of mental demand?
 - (b) How do the techniques compare in terms of physical demand?
 - (c) How do the techniques compare in terms of temporal demand?
 - (d) How do the techniques compare in terms of effort?
3. What makes users prefer one technique over another?
 - (a) In what scenario does the user prefer one technique over another?
 - (b) Why does the user prefer one technique over another?

Study Flow

11 min Informed Consent Form

11 min Warm-Up (Wearing VR, VR Equipment Introduction, Safety)

40 min, 10 each Treatments, repeated 4 times total, 1 for each treatment

2 min Walkthrough & Tutorial

6 min Tasks

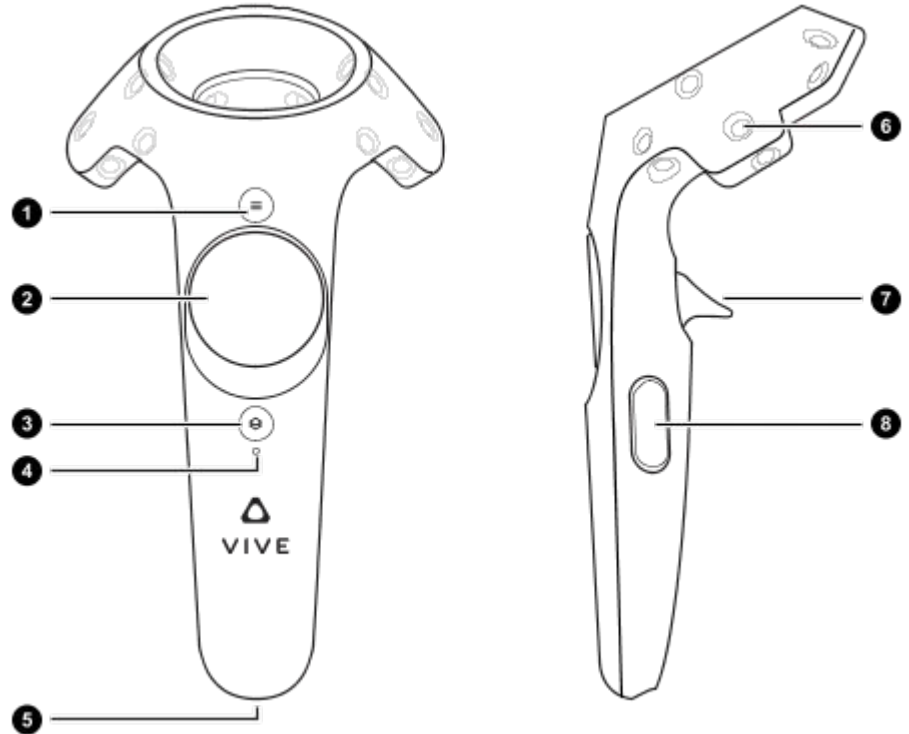
2 min Break & Questionnaire

20 min Semi-Structured Interview

5 min Debrief

“Not enough buttons”

“Not enough buttons”



Plan after Defense

Immediate

Donate Platelet at American Red Cross

See a therapist

Grab dinner with friends

After

Get a job

Taxonomy paper again.. But now with SIM

Global Game Jam

Publish Innovation in Games paper from my second PhD of Game Design

XROS UI Project

Project Codebase:

<https://github.com/powenyao/XR-Interaction-Toolkit-Examples>

Project Website:

<https://powenyao.github.io/XR-Interaction-Toolkit-Examples/website/index.html>

Relevant Youtube Videos

<https://www.youtube.com/playlist?list=PLQkQPxKAn5cRfVUPzxOg6kWXBP46UCV>

@Shitong Sketches needed?

F2. Personal, Peripersonal, Extrapersonal Space the othe after

H. Definition of Extradimensional Space

I think the example we have look decent, though its from wikipedia on connectivity (graph theory). Anything better would require a lot more work?

O. Extradimensional Space Storage sketches are... well they could be better lo

P. **(Higher Priority)** 5 Components of a Storage System

Q. Assumptions Slide “this "position and rotation" comment sounds like a good place for some hand gestures with a held object for clarity.”

A. (Low priority?) sketch that help explains AR/VR/MR is represented by XR

B. (Low priority?) Sketch to show different posture of a person, standing, sitting, lying down, prone (?), moving (room scale)

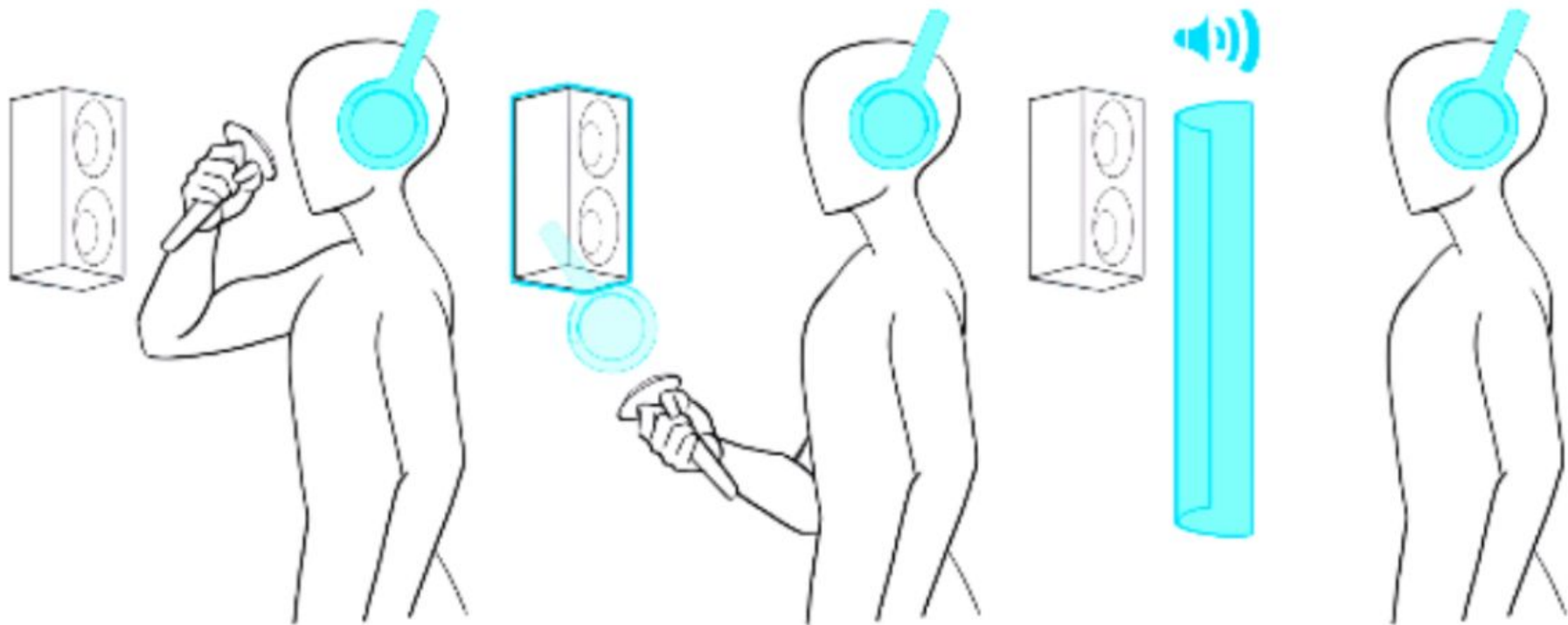
C. (Low Priority) Mobile Augmented Reality

Walking, Bicycling, Driving Vehicle, Riding as Passenger

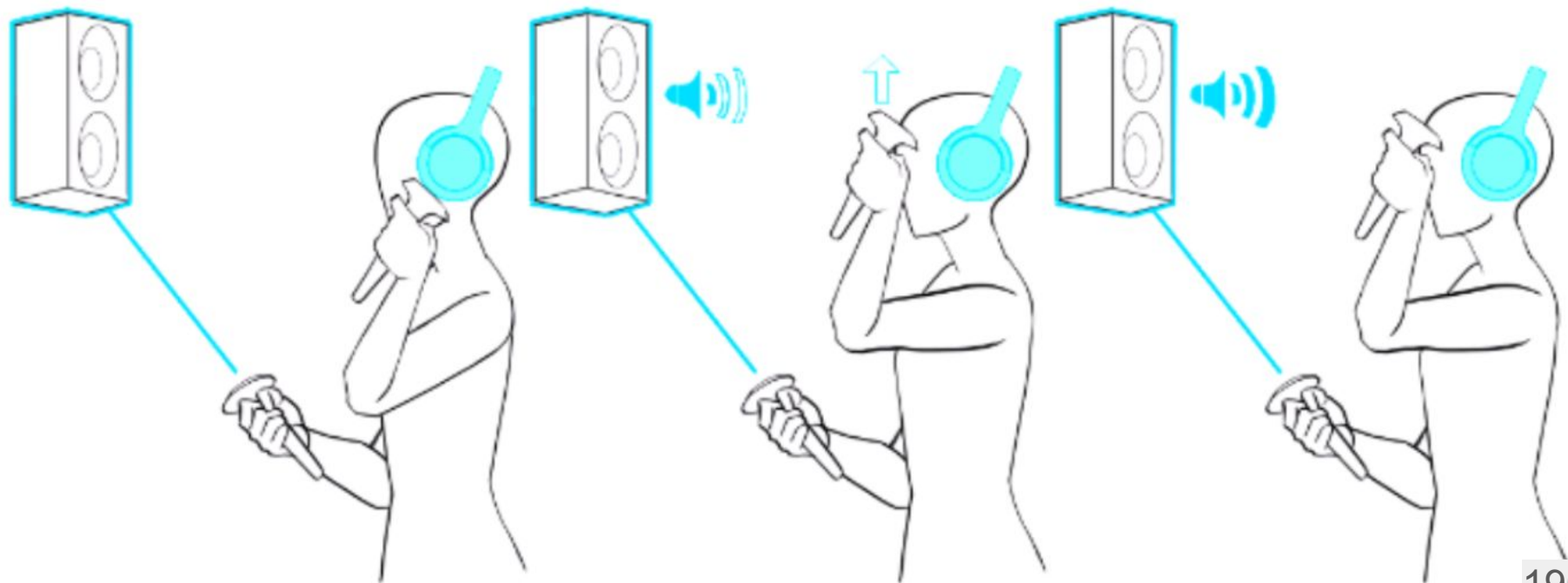
K. (Low priority?) Should we replace the coordinate system image in context mapping...? 93 188

L. (Low priority?) Spatial Interaction Model (being shown everything, made in Miro. Do you

Affecting Remote Target



Affecting Remote Target



Reference Links

Where some figures are created

https://miro.com/app/board/o9J_IaA4mjU=/

Qualification Slides

<https://docs.google.com/presentation/d/1GuzySbaRNpcD5JWaW6wE2jLJ5QrtebpKtc6LvTAuLuQ/edit>

PhD Thesis

<https://www.overleaf.com/read/ncptfcvcczwx#3b1888>

TODO

- 1) ~~better introduction stating the challenges~~
- 2) ~~Nature breakdown slides~~ quotes added for the six examples
- 3) ~~Context Mapping—User~~
- 4) ~~SSS~~
 - a) ~~talk more about what the symbols do~~ quotes added
 - b) ~~Dimensional Sight example~~ quotes added
 - e) ~~equipment as metaphor for having abilities~~
 - d) ~~Simple extradimensional storage~~
- 5) ~~VES~~
 - a) 1 slide to talk about sets
 - b) ~~1 slide for each set~~
 - e) ~~talk about surrogate object, actor, effect, voodoo doll, etc?~~ No time..
- 6) ~~explanation of the EDS~~ quotes added for the four diagrams
- 7) ~~VES user study details~~
 - a) ~~description of technique~~
 - b) ~~questionnaire, user study, questionnaire~~
 - c) ~~findings and interpretations~~
- 8) ~~summary and conclusion from thesis~~